

Linear Algebra
FINAL / ٤٠

Birzeit University
Math. & Comp. Science Dept.
Linear Algebra

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Math 234 Final Exam

Fall Semester

Student Name: _____

Number: _____ Section: _____

(Question One: 40 points) Circle the MOST correct statement

1. If the coefficient matrix of a system of linear equations is

$$\left(\begin{array}{ccc|c} 1 & 2 & 3 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$$\left\{ \begin{array}{l} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \\ 8 \end{array} \right\}$$

then

- (a) the system is consistent.
- (b) if the system has a solution, it is unique.
- (c) if the system has a solution, it has infinitely many solutions.
- (d) the system is inconsistent.

2. If $A = (\vec{a}_1, \dots, \vec{a}_n) \in \mathbb{R}^{m \times n}$ where \vec{a}_j denotes the j^{th} column of A , then $A\vec{x} = \vec{b}$ is consistent if and only if

- (a) the system has a solution.
- (b) $\vec{b} \in \text{Span}(\vec{a}_1, \dots, \vec{a}_n)$.
- (c) $\text{rank}(A|\vec{b}) = \text{rank}(A)$.
- (d) all of the above.

3. If $A \in \mathbb{R}^{n \times n}$ such that $A^n = I$, then

- (a) $A^{-1} = A^{n-1}$.
- (b) $\det(A) \neq 0$.
- (c) any $\vec{x} \in \mathbb{R}^n$ is an eigenvector of A^n .
- (d) all of the above.

$$\sum_{i=1}^n c_i x_i^n = 0$$

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 \end{pmatrix}$$

$$\begin{aligned} 1^4 - (1+1)^4 &= 0 \\ (1-1)^4 &= 0 \\ 0 \cdot x &= 0 \end{aligned}$$

$$4. \text{ Let } A = \frac{1}{4} \begin{bmatrix} 1 & -2\sqrt{3} & 0 \\ \sqrt{12} & 4 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$\Rightarrow A = \begin{bmatrix} 1 & -2\sqrt{3} & 0 \\ \sqrt{12} & 4 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

- (b) Is A non-singular? explain.
 (b) If A^{-1} exists, Find A^{-1} .
 (c) Find the rank(A). $\Rightarrow 3$

$$5. \text{ Let } A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 3 & 4 & 2 & 0 \\ 0 & 0 & 5 & 3 \end{bmatrix}$$

$$(a) \text{ Find } \det(A). \Rightarrow 6$$

$$(b) \text{ Find } C(X).$$

$$(c) \text{ Find } N(A) \text{ and dimension of } N(A). \Rightarrow 0$$

$$\left(\frac{\sqrt{3}}{2} \right) \left(\frac{\sqrt{2}}{2} \right) = -\frac{6}{8}$$

$$\frac{1}{4} \times \frac{6}{8} = \frac{6}{32} = \frac{3}{16} = 1$$

$$A_2 = \begin{pmatrix} 1 & -\frac{\sqrt{3}}{2} & 0 \\ \frac{\sqrt{3}}{2} & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$-\frac{\sqrt{3}}{2} \times -\frac{\sqrt{3}}{2} = \frac{3}{4}$$

$$= \begin{pmatrix} 1 & -\frac{\sqrt{3}}{2} & 0 \\ 0 & \frac{7}{4} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -\frac{\sqrt{3}}{2} & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$|A| = \frac{7}{4} \neq 0$$

$A \rightarrow$ non-singular

$$1 \times \frac{\sqrt{3}}{2} \times 0$$

$$\frac{1}{7} \left(\begin{pmatrix} \frac{7}{4} & 0 & 0 \\ \frac{\sqrt{3}}{2} & 0 & 0 \\ 0 & 0 & -\frac{7}{4} \end{pmatrix} \right) = \begin{pmatrix} 1 & 0 & 0 \\ \frac{2\sqrt{3}}{7} & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

N.S.M.

Final

D.J.W.

Birzeit University
Math. & Comp. Science Dept.
Final Math. 234 Fall

Name: Dr. Mohammad Saleh

Q1: (20 Points) True or false:

- T (a) If A, B are invertible matrices then AB is invertible.
- F (b) A homogeneous system might have finitely many solutions.
- F (c) If the system $AX = B$ has more than one solution then A is invertible.
- T (d) If A, B are two matrices and AB is invertible then A and B are invertible.
- T (e) If A, B are two square non-zero matrices and $AB = 0$ then A and B are non-invertible.
- T (f) Let A be a square and invertible $n \times n$ matrix. Then $|\text{adj } A| = |A|^n$.
- T (g) Let A be a square $n \times n$ matrix. Then $|3A| = 3^n |A|$.
- F (h) If A is a symmetric and skew-symmetric then A must be a zero matrix.
- F (i) If A, B are symmetric then AB is symmetric.
- T (j) If all entries of the main diagonal of a square matrix A are zeros then A is not invertible.
- X (k) every metric space is a normed space.
- X (l) every normed space is an inner product space.
- T (m) if x_0 is a solution of the nonhomogeneous system $AX = B$ and x is a solution of the homogeneous system $AX = 0$. Then $x + x_0$ is a solution of the nonhomogeneous system $AX = B$.
- F (n) If $\text{Wronskian}(f_1, \dots, f_n) = 0$ then f_1, \dots, f_n are linearly dependent.
- T (o) If A, B are similar then $p_A(\lambda) = p_B(\lambda)$.
- F (p) If A is $n \times n$ and diagonalizable, then A has n different eigenvalues.
- T (q) If 0 is an eigenvalue of A then A is not invertible.
- F (r) If A is diagonalizable then A is diagonal.
- T (s) If A is $n \times n$ and has n linearly independent eigenvectors, then A is invertible.
- X (t) If A is 2×2 , $\text{tr}(A) = 5$, and 2 is an eigenvalue of A , then 3 is an eigenvalue of A .

Q2 (22 points) Circle the most correct answer

- (1) Let A be invertible. Then

- (a) if A is symmetric then A^{-1} is symmetric
(b) If A is triangular then A^{-1} is triangular
(c) If A is diagonalizable then A^{-1} is diagonalizable
(d) All of the above

(d)

- If u, v are orthogonal vectors then

- (a) $\|u \cdot v\| = \|u\| \cdot \|v\|$
(b) $\|u\| \cdot \|v\| = \|\langle u, v \rangle\|$
(c) $\|\langle u, v \rangle\| = 1$
(d) none

- (2) Define $\langle f, g \rangle = \int_0^1 f(x)g(x)dx$ for every $f, g \in C[0,1]$, then $\|x\| =$

- (a) $\frac{1}{2}$
(b) $\frac{1}{\sqrt{2}}$
(c) $\frac{1}{\sqrt{3}}$
(d) $\frac{1}{4}$

(d)

- (3) One of the following sets of vectors is l.d.

- (a) $\langle 1, 1, 1 \rangle, \langle 2, 3, 1 \rangle$
(b) $\langle 1, 1, 3 \rangle, \langle 2, 3, 4 \rangle, \langle 1, 0, 0 \rangle$
(c) $\langle 1, x, x^2 \rangle$
(d) $\langle 1, 0, 1 \rangle, \langle 2, 3, 5 \rangle, \langle 6, 4, 3 \rangle, \langle 3, 2, 5 \rangle, \langle 5, 0, 0 \rangle$

- (4) One of the following is not a basis for the corresponding space

- (a) $\langle 1, 1, 1 \rangle, \langle 2, 3, 1 \rangle, R^2$
(b) $\langle 1, 0, 1 \rangle, \langle 2, 3, 5 \rangle, \langle 6, 4, 3 \rangle, \langle 3, 2, 5 \rangle, \langle 5, 0, 0 \rangle, R^3$
(c) x, x^2, x^3, P_3
(d) all of the above

- (5) The dimension of the column space of $A = \begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & -1 & 1 & 0 \\ 2 & 4 & 0 & 1 \end{bmatrix}$ is

- (a) 3
(b) 4
(c) 2
(d) 1

$$= \begin{pmatrix} 1 & 2 & 3 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -6 & 1 \end{pmatrix}$$

- (6) If A is $n \times n$ invertible matrix then

- (a) $\text{Rank}(A) = n$
(b) $\text{Nullity}(A) = n$
(c) $\text{Nullity}(A) = n - 1$
(d) $\text{Nullity}(A) = n^2$

$$\begin{pmatrix} 1 & 2 & 1 \\ 1 & 3 & 0 \\ 3 & 2 & 1 \\ 0 & -2 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 \\ 1 & 3 \\ 1 & 1 \end{pmatrix}$$

(8) If an $n \times n$ matrix A has only one eigenvalue λ then dimension of the eigenspace corresponding to λ is.

- (a) n .
- (b) ≥ 1 .
- (c) $= 1$.
- (d) 0 .

b2

(9) If an 4×4 matrix A has $1, -1, 3, 5$ as its eigenvalues then $\det(A) =$

- (a) 8
- (b) 15
- (c) -15
- (d) -8

$$(1)(-1)(3)(5) = -15$$

(10) Let $A = \begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix}$ then the eigenvalues of A^{100}

- (a) 1, 2
- (b) $1, 2^{100}$
- (c) 2^{100}
- (d) none

1x2

$$\begin{pmatrix} 1-\lambda & 3 \\ 0 & 2-\lambda \end{pmatrix}$$

1, 2

(11) The nullity of $\begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix}$ is

- (a) 1
- (b) 2
- (c) 3
- (d) 4

$$\left(\begin{array}{|} \\ \hline \end{array} \right)$$

$$\cancel{6-6=12}$$

cancel

Q5: (20 points) Let $A =$

$$\begin{pmatrix} 1 & 1 & 2 \\ 0 & 2 & 1 \\ 0 & 0 & 3 \end{pmatrix}$$

a) Find the eigenvalues and eigenvectors of A :

$$\begin{pmatrix} 1-\lambda & 1 & 2 \\ 0 & 2-\lambda & 1 \\ 0 & 0 & 3-\lambda \end{pmatrix}$$

$$\begin{aligned} &= (1-\lambda)(2-\lambda)(3-\lambda) \\ &\quad \text{---} \\ &\quad \lambda_1 = 1, \lambda_2 = 2, \lambda_3 = 3 \end{aligned}$$

$\in \cup$

b) Is A diagonalizable, if yes find a matrix P that diagonalize A .

$$P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

MATH. 234, FINAL EXAM, FIRST SEMESTER

Dr. Ayman Abuhijleh (Sections 1 and 4)

Dr. Jawad Abuhlail (Section 5)

Dr. Alnazzal Elayyan (sections 2 and 3)

Dr. Hasan Yousef (Section 6)

Name _____, ID. Number _____, Score _____

QUESTION 1. (10 points) (Write Down True or False)

- (1) If A and B are $n \times n$ matrices, then $\det(AB) = \det(A)\det(B)$ (T)
- (2) If A and B are $n \times n$ nonsingular matrices, then $A + B$ is a nonsingular matrix (F)
- (3) If A is an $n \times n$ matrix and $b \in \mathbb{R}^n$ such that $AX = b$ has no solution, then A is singular. (T)
- (4) If A and B are $n \times n$ matrices and A is row equivalent to B , then $\det(A) = \det(B)$ (F)
- (5) It is possible that $x^2 - x$ be the characteristic polynomial of a nonsingular 2×2 matrix. (F)
- (6) If A is an $n \times n$ matrix and $\det(A) = 0$, then $AX = 0$ has infinitely many solutions. (T)
- (7) It is possible to have $v_1, v_2, v_3 \in \mathbb{R}^4$ such that $\text{span}\{v_1, v_2, v_3\} = \mathbb{R}^4$ (F)
- (8) Let V be the vector space of all 2×3 matrices. Then $\dim(V) = 5$. (F)
- (9) If A is a 2×2 nonzero singular matrix, then $\text{Nullity}(A) = 1$. (_____)
- (10) If A and B are $n \times n$ matrices and A is row equivalent to B , then A is singular if and only if B is singular. (T)
- (11) If A is an $n \times n$ matrix and a, b are eigenvalues of A , then $a + b$ is an eigenvalue of A . (F)
- (12) If A is an $n \times n$ matrix and a, b are two distinct eigenvalues of A and $v \in \text{Nul}(A - aI) \cap \text{Nul}(A - bI)$, then v is the zero vector. (_____)
- (13) If A is a singular $n \times n$ matrix, then 0 is an eigenvalue of A . (T)
- (14) If T is a linear transformation from \mathbb{R}^4 to \mathbb{R}^3 , then there is a matrix A , 3×4 , such that $T(v) = Av$ for every $v \in \mathbb{R}^4$. (T)
- (15) There is a linear transformation from \mathbb{R}^4 to \mathbb{R}^2 such that T is one to one. (_____)
- (16) If A is an $n \times n$ matrix such that $\det(A) = \det(-A)$, then n must be an even positive integer. (T)

$$T(v) = \begin{pmatrix} 3 & 4 \\ 4 & 1 \end{pmatrix} v$$

- (17) If A, B are $n \times n$ nonzero matrices such that AB is the zero matrix, then both A, B are singular. (T)
- (18) If A is a nonzero 3×2 matrix such that $Ax = 0$ has infinitely many solutions, then $\text{Nullity}(A) = 2$. (F)
- (19) If A is a 5×8 matrix such that $\text{Rank}(A) = 3$, then $\text{Nullity}(A) = 2$. (F)
- (20) There is a matrix, say A , 6×9 such that $\text{Rank}(A) = 7$. (F)
- (21) If A is a nonsingular $n \times n$ matrix such that $Av = 3v$ for some nonzero vector $v \in R^n$, then $A^{-1}v = -3v$. (—)
- (22) If A is a 7×4 matrix and $\text{Rank}(A) = 4$ and AB is the zero matrix for some matrix B , 4×2 , then B must be the zero matrix. (—)
- (23) If A, B are nonsingular $n \times n$ matrices, then A is row equivalent to B . (T)
- (24) If A, B are $n \times n$ matrices and $B = 3A$, then $\det(B) = 3\det(A)$ (F)
- (25) If A, B are $n \times n$ matrices and A is row equivalent to B , then $A = PB$ for some nonsingular $n \times n$ matrix P . (F)
- (26) $\{x^2 + 1, x^2 + x\}$ is a basis of P_3 . (F)
- (27) $\dim(\{x^3 + 3, x^3 + 1, x^3 + x\}) = 2$. (F)
- (28) $S = \{f(x) \in P_3 : f(1) = 0 \text{ or } f(0) = -1\}$ is a subspace of P_3 . (F)
- (29) $S = \{f(x) \in P_5 : f(x) = -f(x)\}$ is a 3-dimensional subspace of P_5 . (—)
- (30) Given $S = \{f(x) \in P_5 : f(1) = f(-1)\}$ is a subspace of P_5 . Then $\{1, x^2, x^4\}$ is a basis of S . (F)

QUESTION 2. (30 points, Each = 1.5 points) (CIRCLE THE CORRECT ANSWER)

- (1) Let A and B be 3×3 matrices such that $\det(A) = -1$ and $\det(B) = -2$.
Then $\det(2AB^{-1}) =$
(a) 1 (b) 4 (c) 16 (d) None

- (2) Given $S = \{A \in R^{4 \times 4} : A \text{ is a diagonal matrix}\}$ is a subspace of $R^{4 \times 4}$. Then
 $\dim(S) =$
(a) 2 (b) 3 (c) 4 (d) None

- (3) Given $S = \{f(x) \in P_9 : f(1) = f(-2) = 0\}$ is a subspace of P_9 . Then
 $\dim(S) =$
(a) 7 (b) 8 (c) 9 (d) None

- (4) If A is a 5×3 matrix and $b \in R^5$ such that $AX = b$ has exactly one solution.
Then $\text{Nullity}(A) =$
(a) 0 (b) at least one (c) 3 (d) None

- (5) Let $A = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$. Then the eigenvalues of A are

- (a) 1 and -1 (b) 0, 1, and -1 (c) -1, 2, and 0 (d) None

rank = 3

$$\begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$(-1)(-1)(-1)^{20}$$

$$(1-\lambda)(2-\lambda)(1-\lambda)$$

$$(2-\lambda)^3$$

$$(1-\lambda)^2(2-\lambda)^2$$

$$-1(\lambda-1)$$

- (6) If A is a 4×4 matrix and A is similar to $\begin{bmatrix} 1 & 2 & 0 & 8 \\ 0 & 2 & 1 & -4 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 2 \end{bmatrix}$, then the characteristic polynomial of A is

(a) $(x-1)^2(x-2)^2$ (b) $(x+1)^2(x+2)^2$ (c) $(x-1)(x-2)$ (d) None

- (7) If -2 is an eigenvalue of a 4×4 matrix A , then an eigenvalue of $4A$ is

(a) $1/2$ (b) $-1/2$ (c) -8 (d) 16

- (8) Let $A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$, $B = \begin{bmatrix} -2 & 2 \\ -2 & -2 \end{bmatrix}$, and $C = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$. Then a basis for $\text{Span}\{A, B, C\}$ is

(a) $\{A, C\}$ (b) $\{A, B, C\}$ (c) $\{A, B\}$ (d) None

- (9) If v_1, v_2 are independent in R^3 and v_3 is a (nonzero) element of R^3 such that $v_3 = 2v_1 + -3v_2$. Then

(a) $\dim \text{Span}\{v_1, v_2, v_3\} = 2$ (b) $\{v_1, v_3\}$ are independent (c) $\{v_2, v_3\}$ are independent (d) a, b, and c are correct statements

- (10) ONE of the following is not a vector space

(a) $V = \{f(x) \in P_9 : f(0) = 0\}$ (b) $V = \text{span}\{e^x, \sin x, \tan x\}$ (c) $V = \text{all upper triangular } 5 \times 5 \text{ matrices}$ (d) $V = \{f(x) \in P_{13} : f(0) = 1\}$

- (11) Given $A = \begin{bmatrix} 2 & -3 \\ 2 & -5 \end{bmatrix}$ is similar to a diagonal matrix D . Then $D =$

(a) $\begin{bmatrix} 1 & 0 \\ 0 & -4 \end{bmatrix}$ (b) $\begin{bmatrix} 2 & 0 \\ 0 & -5 \end{bmatrix}$ (c) $\begin{bmatrix} -2 & 0 \\ 0 & 5 \end{bmatrix}$ (d) $\begin{bmatrix} -1 & 0 \\ 0 & 4 \end{bmatrix}$

- (12) Given A is a 2×2 matrix and $2, 1$ are eigenvalues of A . Then the characteristic polynomial of A^{-1} is

(a) $x^2 - (3/2)x + 1/2$ (b) $x^2 + (1/3)x + 1/2$ (c) $x^2 - 3x + 2$ (d) $1/(x^2 - 3x + 2)$

- (13) Let $T : R^3 \rightarrow R^2$ such that $T(x_1, x_2, x_3) = (x_1 + x_2, x_2 + x_3)$. Given $B = \{(1, 2, 1), (0, 2, -1), (-1, -2, 3)\}$ is a basis for R^3 and $H = \{e_1, e_2\}$ is the standard basis for R^2 . Then the matrix representation of T with respect to B and H is

(a) $\begin{bmatrix} 1 & 0 & -1 \\ 2 & 2 & -2 \\ 1 & -1 & 3 \end{bmatrix}$ (b) $\begin{bmatrix} 3 & 2 & -3 \\ 3 & 1 & 1 \end{bmatrix}$ (c) $\begin{bmatrix} 3 & 3 & 2 \\ 1 & 1 & -3 \end{bmatrix}$ (d) None

- (14) Given A is a $4 \times m$ matrix, B is a $m \times 4$ matrix, and $C = AB$. Suppose that C is nonsingular (observe that C is a 4×4 matrix). Then

(a) $m \leq 4$ (b) $m = 4$ (c) $m < 4$ (d) $m \geq 4$

$$\frac{1}{2} \quad \frac{1}{2}$$

$$\det(A) = 2 \rightarrow \frac{1}{2} \\ \text{tra}(A) = 3 \rightarrow -10^3 - 2\lambda + 5\lambda + \lambda^2 + 6 \\ -4 + 3\lambda + \lambda^2$$

$$X^2 - BX + C \\ X^2 - 3X + \frac{1}{2}$$

$$\lambda^2 + 3\lambda - 4 \\ (\lambda + 4)(\lambda - 1) \\ \lambda_1 = -4, \lambda_2 = 1$$

- (15) Let $A = \begin{bmatrix} 2 & 0 & 0 & -2 \\ -4 & 0 & 0 & 4 \\ 0 & 3 & 0 & 0 \end{bmatrix}$. A basis for the row space of A is
 (a) $\{(2, 0, 0, -2), (-4, 0, 0, 4), (0, 3, 0, 0)\}$ (b) $\{(2, 0, 0, -2), (0, 0, 1, 0)\}$
 (c) $\{(1, 0, 0, -1), (0, 1, 1, 0)\}$ (d) $\{(2, 0, 0, -2), (0, 3, 0, 0)\}$

- (16) Let $A = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 2 & 1 & 0 & 1 \end{bmatrix}$. A basis for $N(A)$ is
 (a) $\{(1, 0, -1, 1), (0, 1, 2, -1)\}$ (b) $\{(1, 0), (0, 1)\}$ (c) $\{(0, -2, 1, 1), (1, -3, 1, 0)\}$
 (d) $\{(1, -2, 1, 0), (-1, 1, 0, 1)\}$

- (17) The solutions for
 $x_1 + x_2 + x_3 + x_4 + x_5 = 2$
 $x_1 + x_2 + x_3 + 2x_4 + 2x_5 = 3$
 $x_1 + x_2 + x_3 + 2x_4 + 3x_5 = 2$

$$\left(\begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 0 & 2 \\ 2 & 1 & 0 & 1 & 1 & 3 \\ 1 & 1 & 1 & 2 & 1 & 2 \end{array} \right) \xrightarrow{\text{Row operations}} \left(\begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 0 & 2 \\ 0 & 1 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 1 \end{array} \right) \quad \begin{array}{l} x_1=2 \\ x_2=1 \\ x_3=0 \\ x_4=1 \\ x_5=0 \end{array}$$

(a) $\{(x_1, x_2, x_3, 2x_4, -x_5) : x_1, x_2, x_3 \in R\}$ (b) $\{(2, -1, 1 + x_3, x_3, 0, -2) : x_3 \in R\}$

- (c) $\{(1 - x_2 - x_3, x_2, x_3, 2, -1) : x_2, x_3 \in R\}$ (d) $\{(x_2 + x_3, x_2, x_3, 2x_2, -x_3) : x_2, x_3 \in R\}$
- (18) Let $A = \begin{bmatrix} 1 & 3 & 2 \\ 0 & 0 & (c-3) \\ 0 & 3 & 10 \end{bmatrix}$. The values of c that make $AX = b$ has a solution for every $b \in R^3$ are
 (a) All real numbers (b) All real numbers except 3 (c) 0 (d) All real numbers except 0.

- (19) Given $A = \begin{bmatrix} 2 & 4 & 1 \\ 0 & 0 & 2 \\ 0 & -1 & 2 \end{bmatrix}$. The (1, 3)-entry of A^{-1} is
 (a) -2 (b) 2 (c) 0 (d) None

- (20) Given v_1, v_2 are independent in R^3 . Then
 (a) If $v_3 \in \text{span}\{v_1, v_2\}$, then it is possible that $\{v_1, v_2, v_3\}$ form a basis for R^3
 (b) It is possible that $(0, 0, 0) \notin \text{Span}\{v_1, v_2\}$
 (c) If $\text{Span}\{v_1, v_2, v_3\} = R^3$, then $v_3 \notin \text{Span}\{v_1, v_2\}$ (d) a, b, and c are correct statements

$$\begin{pmatrix} \alpha & \beta \\ -2 & \alpha \\ \beta & \alpha \end{pmatrix}$$

$$\begin{pmatrix} -1 & 1 \\ 0 & 0 \end{pmatrix} + \beta \begin{pmatrix} -1 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\alpha \begin{pmatrix} 1 & -2 \\ 1 & 0 \end{pmatrix} + \beta \begin{pmatrix} -1 & 1 \\ 0 & 0 \end{pmatrix}$$

Birzeit University
 Math. & Comp. Science Dept.
 Math. 234

Dr. Ayman Abu-Hijleh

~~217
218~~

Summer

Section: —

Final Exam

Student Name: Badie' Amrani Number:

1. Let $A = \begin{bmatrix} 1 & 3 \\ 0 & -1 \end{bmatrix}$. $\boxed{A = \begin{bmatrix} 2 & -3 \\ 1 & -2 \end{bmatrix}}$

(a) Find the eigenvalues of A .

(b) Explain, why A is diagonalizable.

(c) Find a diagonal matrix D and a matrix Q s.t. $Q^{-1}AQ = D$.

(d) Find A^{103}

$$\begin{bmatrix} 2-\lambda & -3 \\ 1 & -2-\lambda \end{bmatrix}$$

$$(2-\lambda)(-2-\lambda) + 3 = 0$$

$$-1 - 2\lambda + 2\lambda^2 + \lambda^2 + 3 = 0$$

$$-1 + \lambda^2 = 0$$

$$\lambda = \pm 1$$

2. Let $T : R^2 \rightarrow R^3$, given by $T \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 3x_1 \\ 0 \\ 2x_2 \end{pmatrix}$ is a L.T. Also, given $B_2 = \{(3, 2), (1, 6)\}$ is a basis for R^2 , and $B_3 = \{(2, 0, 4), (-1, 0, 2), (0, 2, 0)\}$ is a basis for R^3 .

(a) Find the matrix A representing T in terms of B_3 and B_2 .

(b) Find $\left[T \begin{pmatrix} 5 \\ 10 \end{pmatrix} \right]_{B_3}$

(c) Find the dimension of Range(T) and the dimension of Ker(T).

$$3x_1 \quad x_1 \begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$$

~~Range~~

$$U \begin{pmatrix} 3x_1 & | & 0 \\ 0 & | & 0 \\ 2x_2 & | & 0 \end{pmatrix} \xrightarrow{\text{Row operations}} \begin{pmatrix} 1 & | & 0 \\ 0 & | & 0 \\ 0 & | & 0 \end{pmatrix}$$

3. Let $B = \{10, 3x+1, 5x^2+2x-1\}$

(a) Show that B is a basis for P_2 .

(b) Find the transition matrix from B to $\{1, x, x^2\}$.

(c) Find the transition matrix from $\{1, x, x^2\}$ to B .

(d) Write $P(x) = 3x^2 + 17x + 33$ as a linear combination of the elements in B .

$$\begin{array}{l} x_3 = 0 \\ x_2 = 0 \\ x_1 = 0 \end{array}$$

$$A \xrightarrow{\text{Row operations}} \begin{pmatrix} 1 & | & 10 \\ 0 & | & 8 \\ 0 & | & 26 \end{pmatrix} \xrightarrow{\text{Row operations}} \begin{pmatrix} 1 & | & 10 \\ 0 & | & 8 \\ 0 & | & 2 \end{pmatrix} \xrightarrow{\text{Row operations}} \begin{pmatrix} 1 & | & 10 \\ 0 & | & 8 \\ 0 & | & 1 \end{pmatrix} \xrightarrow{\text{Row operations}} \begin{pmatrix} 1 & | & 10 \\ 0 & | & 8 \\ 0 & | & 15 \end{pmatrix}$$

4. If A and B are two matrices such that $(AB)^t = A^t B^t$, then

- (a) $AB = BA$.
- (b) A is a square matrix.
- (c) B is a square matrix.
- (d) Both (a) and (b) are correct.

5. If both U and V are subspaces of a vector space W , then

- (a) $U \cap V$ is a subspace of W .
- (b) $U + V$ is a subspace of W .
- (c) the union need not be a subspace of W .
- (d) all of the above.

6. One of the following statements is always true:

- (a) If $f, g \in C(-\infty, \infty)$ such that $W[f, g](x) = 0$ for all $x \in (-\infty, \infty)$, then f and g are linearly dependent.
- (b) A subset S of a vector space V is linearly independent if no element in S can be written as a linear combination of the other elements of S .
- (c) Any element in a linearly dependent set can be written as a linear combination of the other elements in the set.
- (d) all of the above.

7. The statement An $n \times n$ matrix A is nonsingular is equivalent to

- (a) $\vec{0} \in N(A)$.
- (b) $\text{Span}(\vec{a}_1, \dots, \vec{a}_n) = \mathbb{R}^n$.
- (c) $\text{rank}(A) + \text{nullity}(A) = n$.
- (d) all of the above.

8. Which of the following transformations $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is not linear?

- (a) Reflection: $T(\vec{x}) = -\vec{x}$.
- (b) Contraction: $T(\vec{x}) = \alpha \vec{x}, 0 < \alpha < 1$.
- (c) Expansion: $T(\vec{x}) = \alpha \vec{x}, 1 < \alpha$.
- (d) Translation: $T(\vec{x}) = \vec{x} + \vec{a}$.

9. In \mathbb{R}^2 with $\|\vec{x}\|_1 = |x_1| + |x_2|$, $\|\vec{x}\|_2 = \sqrt{x_1^2 + x_2^2}$, and $\|\vec{x}\|_\infty = \max\{|x_1|, |x_2|\}$,

- (a) $\|\vec{x}\|_1 \leq \|\vec{x}\|_2 \leq \|\vec{x}\|_\infty$.
- (b) $\|\vec{x}\|_1 \leq \|\vec{x}\|_\infty \leq \|\vec{x}\|_2$.
- (c) $\|\vec{x}\|_\infty \leq \|\vec{x}\|_1 \leq \|\vec{x}\|_2$.
- (d) $\|\vec{x}\|_\infty \leq \|\vec{x}\|_2 \leq \|\vec{x}\|_1$.

$T_u = T_u + \lambda u - \lambda x$

Birzeit University
Math. Dept.
Math 434: Advanced Linear Algebra

M. Saleh

Final Exam
Student Name: _____

First Semester 2012/2013
Number: _____ Section: _____

LA

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1. (a) Prove that the eigenvectors corresponding to distinct eigenvalues are linearly independent
- (b) Prove that the generalized eigenvectors in a chain are linearly independent
- (c) Let $L : C^2 \rightarrow C^2$ be a linear operator defined by $L(z, w) = (z + w, z - w)$. Find a basis for C^2 so that the matrix representation of L with respect to this basis is upper triangular.
- (d) Show that an orthogonal set of vectors is linearly independent
- (e) Show that a real symmetric matrix is diagonalizable
-
2. (a) Show that any linear operator over a finite dimensional complex space has an eigenvector
- (b) Show that any linear operator over a finite dimensional complex space has an upper triangular matrix representation
- (c) Define an inner product on R^n by $\langle x, y \rangle = x^T y, x, y \in R^n$. Let A be an $n \times n$ matrix. Show that $\|Ax\|^2 = \langle x, A^T Ax \rangle$, for every $x \in R^n$.
- (d) Let λ_1, λ_2 be distinct eigenvalues of A . Let x be an eigenvector of A corresponding to λ_1 , y be an eigenvector of A^T corresponding to λ_2 . Show that x, y are orthogonal vectors.
- $A^T \begin{matrix} x \\ y \end{matrix} \xrightarrow{\lambda_1} \lambda_1 \quad \xrightarrow{\lambda_2}$
-
3. (a) Use Gram-Schmidt to find the distance between the point $(1, 1, 1)$ and the plane $x - y = 1$
- (b) Use Gram-Schmidt to find the formula for the distance between the point (x_0, y_0) and the line $ax + by = c$
- (c) Use Gram-Schmidt to approximate $\sin x$ by a polynomial of degree 1. (use inner product on P_n to be $\langle f, g \rangle = \int_0^1 fg dx$)
- (d) Find the adjoint of the linear operator $L : R^3 \rightarrow R^2$ defined by $L(x, y, z) = (x - y, x + z - y)$
with respect to the standard basis of R^3 and the basis $(1, 1), (1, 2)$ for R^2

10. If B is similar to A , then

- (a) $\det(B) = \det(A)$.
- (b) $\text{tr}(B) = \text{tr}(A)$.
- (c) $\text{rank}(B) = \text{rank}(A)$.
- (d) all of the above.

11. An $n \times n$ matrix A will never have a zero eigenvalue if

- (a) $A^t = A$.
- (b) $A^t = -A$.
- (c) $A^t = A^{-1}$.
- (d) all of the above.