## MATH 234 FIRST HOUR EXAM

Student :	Name:Student Number:
Instructo	or: Section:
Ques	stion 1. (20 points) Answer by true or false:
1	If a system of linear equations is undetermined, then it must have infinitely many solutions.
2.	If A and B are $n \times n$ nonsingular matrices, then AB is also nonsingular.
3.	If A and B are $2 \times 2$ matrices that satisfy $AB = O$ , then $A = O$ or $B = O$ .
4	The product of two elementary matrices of the same size is an elementary matrix.
5	$\sum$ The sum of two $n \times n$ nonsingular matrices is also nonsingular.
6	If a matrix A is symmetric, then the matrix $A^T$ is also symmetric.
7	If a matrix $A$ is row equivalent to $I$ , then $A$ is nonsingular.
8	If a matrix A is nonsingular, then the matrix $A^T$ is also nonsingular.
9	The inverse of an elementary matrix is also an elementary matrix.
10	The method of solving a linear system by reducing its augmented matrix to reduced row echelon is called Gaussian elimination.
11. <u></u>	If $Ax = b$ is an overdetermined and consistent linear system, then it must have infinitely many utions.
12	Any two nonsingular matrices are row equivalent.
13.	A homogeneous system can have a nontrivial solution.
14	$F$ If A and B are $n \times n$ matrices such that $AB = BA$ , then A and B are both nonsingular.
15. <b>_</b>	If $ A  = 0$ , then A must have two identical rows or two identical columns.
16	If A is an $n \times n$ matrix, and $A\mathbf{x} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ has a unique solution, then $A\mathbf{x} = \mathbf{b}$ has a unique solution
for	every $\mathbf{b} \in R^3$
17	If a matrix is in row echelon form, then it is also in reduced row echelon form.
18. <b>_</b>	It is possible for a singular matrix to be row equivalent to the identity matrix.
19.	If A is a $3 \times 3$ matrix, then $ -2A  = -2 A $ .
20	If A is an $n \times n$ matrix, then $ A^n  =  A ^n$

## Question 2 (3 points each ) Circle the most correct answer:

- 1. If A is a  $3 \times 5$  matrix, then
  - (a)  $A\mathbf{x} = \mathbf{b}$  is consistent for every vector  $b \in \mathbb{R}^5$ .
  - (b) Ax = b is inconsistent for every vector  $b \in \mathbb{R}^5$ .
  - (c) Ax = 0 has infinitely many solutions.
  - (d) Ax = 0 has only the trivial solution.
- 2. Let  $A = \begin{bmatrix} 1 & 2 & 1 \\ -1 & 1 & 0 \\ 1 & 8 & 1 \end{bmatrix}$ . If we want to find the LU factorization of A, then  $L = \begin{bmatrix} 1 & 2 & 1 \\ -1 & 1 & 0 \\ 1 & 8 & 1 \end{bmatrix}$ .

  - (b)  $\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & 8 & 1 \end{bmatrix}$
  - (c)  $\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ -1 & -2 & 1 \end{bmatrix}$
  - (d)  $\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ -1 & -8 & 1 \end{bmatrix}$
- 3. If B = EA, where E is an elementary matrix of type I, then
  - (a) |B| = |A|
  - (b)|B| = -|A|
    - (c) |B| = |E|
  - (d) |B| = -|E|
- 4. If A and B are  $n \times n$  matrices such that A singular and B is nonsingular, then
  - (a) AB = O
  - $\bigcirc$  AB is singular
  - (c) A + B is singular
  - (d) AB is nonsingular
- 5. Let  $A = \begin{bmatrix} a & 1 & 1 \\ a & 2 & 0 \\ -2 & 2 & a \end{bmatrix}$ . Then A is nonsingular if and only if
  - (a) a = 2
  - (b) a is any real number
  - (c) a = -2
  - (d)  $a = \pm 2$

- 6. Let A be a  $3 \times 3$  matrix and suppose that  $A \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ . Then
  - (a) Ax = 0 has infinitely many solutions
  - (b)  $A\mathbf{x} = (1,0,0)^T$  has infinitely many solutions
  - (c) A is nonsingular
  - (d) None of the above
- 7. Let  $A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$  and  $B = \begin{bmatrix} a & 4d & a+g \\ b & 4e & b+h \\ c & 4f & c+i \end{bmatrix}$ . If |A| = 3 then |B| = 1
  - (a) 12
  - (b) 6
  - (c) 3
  - (d) 24
- 8. If A is a  $4 \times 4$  matrix with det(A) = 2 then  $det(4A^{-1})$  is
  - (a) 2
  - (b) 8
  - (c) 264
  - (d) 128
- 9. Let  $A = \begin{bmatrix} 2 & 3 \\ 4 & 1 \end{bmatrix}$ . Then the adjoint of A is
  - - (b)  $\begin{bmatrix} -1 & 4 \\ 3 & -2 \end{bmatrix}$
    - (c)  $\begin{bmatrix} 1 & -4 \\ -3 & 2 \end{bmatrix}$
    - (d)  $\begin{bmatrix} -1 & 3 \\ 4 & -2 \end{bmatrix}$
- 10. If  $det(A) \neq 0$  then
  - (a) A is nonsingular
  - (b) Ax = 0 has only the trivial solution
  - (c) A is row equivalent to I
  - All of the above

Question 3.(10 points) Suppose that 
$$[A|b] = \begin{bmatrix} 1 & -1 & 1 & 2 \\ 2 & 1 & -1 & 5 \\ 1 & -1 & a & b \end{bmatrix}$$
 is the augmented matrix of a linear system.

For what values of a and b does the system have

- 1. a unique solution.
- 2. no solution.
- 3. infinitely many solutions.

$$\begin{bmatrix} 1 & -1 & 1 & 2 \\ 0 & 3 & -3 & 1 \\ 0 & 0 & a-1 & b-2 \end{bmatrix}$$

2. 
$$a=1 \ \{b \neq 2\}$$

Question 4.(12 points) Use Guauss-Jordan reduction to solve the system

$$\begin{bmatrix} 1 & 1 & 2 & 1 & 5 \\ 2 & -1 & 1 & 8 & 4 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 1 & 2 & 1 & 5 \\ 0 & -3 & -3 & 6 & -6 \\ 4 & 1 & 5 & -2 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 2 & 1 & 5 \\ 0 & 1 & 1 & -2 & 2 \\ 0 & 0 & 0 & -12 & -9 \end{bmatrix} \xrightarrow{\begin{bmatrix} 1 & 1 & 2 & 0 & 1\frac{1}{3} \\ 0 & 1 & 1 & 0 & \frac{1}{3} \\ 0 & 0 & 0 & 1\frac{3}{3} \end{bmatrix}}$$

Question 5.(10 points) Let 
$$A = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 1 \\ -1 & -2 & -3 \end{bmatrix}$$
. Find

- 1. The adjoint of A.
- 2. The determinant of A.
- 3. The inverse of A.

1. 
$$\begin{bmatrix} -1 - 4 & 3 \\ -2 - 2 & 2 \\ -1 - 2 & 1 \end{bmatrix}$$

## MATH 234 FIRST HOUR EXAM

Question 1. (20 points) Answer by true or false:  1.
<ol> <li>If a matrix A is nonsingular, then the matrix A<sup>T</sup> is also nonsingular.</li> <li>The inverse of an elementary matrix is also an elementary matrix.</li> <li>If a system of linear equations is undetermined, then it must have infinitely many solutions.</li> <li>If A and B are n × n nonsingular matrices, then AB is also nonsingular.</li> <li>If A and B are 2 × 2 matrices that satisfy AB = O, then A = O or B = O.</li> <li>If a matrix A is row equivalent to I, then A is nonsingular.</li> <li>The method of solving a linear system by reducing its augmented matrix to reduced row echelon form is called Gaussian elimination.</li> <li>The product of two elementary matrices of the same size is an elementary matrix.</li> <li>If a matrix A is symmetric, then the matrix A<sup>T</sup> is also symmetric.</li> <li>Any two nonsingular matrices are row equivalent.</li> <li>F If Ax = b is an overdetermined and consistent linear system, then it must have infinitely many solutions.</li> <li>A homogeneous system can have a nontrivial solution.</li> <li>If A and B are n × n matrices such that AB = BA, then A and B are both nonsingular.</li> <li>If it is possible for a singular matrix to be row equivalent to the identity matrix.</li> </ol>
The inverse of an elementary matrix is also an elementary matrix.  If a system of linear equations is undetermined, then it must have infinitely many solutions.  If A and B are n × n nonsingular matrices, then AB is also nonsingular.  If A and B are 2 × 2 matrices that satisfy AB = O, then A = O or B = O.  If a matrix A is row equivalent to I, then A is nonsingular.  The method of solving a linear system by reducing its augmented matrix to reduced row echelon form is called Gaussian elimination.  The product of two elementary matrices of the same size is an elementary matrix.  The sum of two n × n nonsingular matrices is also nonsingular.  If a matrix A is symmetric, then the matrix A <sup>T</sup> is also symmetric.  Any two nonsingular matrices are row equivalent.  If Ax = b is an overdetermined and consistent linear system, then it must have infinitely many solutions.  A homogeneous system can have a nontrivial solution.  If A and B are n × n matrices such that AB = BA, then A and B are both nonsingular.  It is possible for a singular matrix to be row equivalent to the identity matrix.
<ol> <li>If a system of linear equations is undetermined, then it must have infinitely many solutions.</li> <li>If A and B are n × n nonsingular matrices, then AB is also nonsingular.</li> <li>If A and B are 2 × 2 matrices that satisfy AB = O, then A = O or B = O.</li> <li>If a matrix A is row equivalent to I, then A is nonsingular.</li> <li>The method of solving a linear system by reducing its augmented matrix to reduced row echelon form is called Gaussian elimination.</li> <li>The product of two elementary matrices of the same size is an elementary matrix.</li> <li>If a matrix A is symmetric, then the matrix A<sup>T</sup> is also symmetric.</li> <li>Any two nonsingular matrices are row equivalent.</li> <li>If Ax = b is an overdetermined and consistent linear system, then it must have infinitely many solutions.</li> <li>A homogeneous system can have a nontrivial solution.</li> <li>If A and B are n × n matrices such that AB = BA, then A and B are both nonsingular.</li> <li>If it is possible for a singular matrix to be row equivalent to the identity matrix.</li> </ol>
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7. The method of solving a linear system by reducing its augmented matrix to reduced row echelon form is called Gaussian elimination.  8. The product of two elementary matrices of the same size is an elementary matrix.  9. The sum of two $n \times n$ nonsingular matrices is also nonsingular.  10. If a matrix A is symmetric, then the matrix $A^T$ is also symmetric.  11. Any two nonsingular matrices are row equivalent.  12. Find $A \times B$ is an overdetermined and consistent linear system, then it must have infinitely many solutions.  13. A homogeneous system can have a nontrivial solution.  14. Find $A \times B$ and $A \times B$ are $A \times B$ matrices such that $A \times B$ are $A \times B$ are both nonsingular.  15. Find $A \times B$ is possible for a singular matrix to be row equivalent to the identity matrix.
form is called Gaussian elimination.  8.
9. The sum of two $n \times n$ nonsingular matrices is also nonsingular.  10. If a matrix A is symmetric, then the matrix $A^T$ is also symmetric.  11. Any two nonsingular matrices are row equivalent.  12. Fig. If $A\mathbf{x} = \mathbf{b}$ is an overdetermined and consistent linear system, then it must have infinitely many solutions.  13. A homogeneous system can have a nontrivial solution.  14. Fig. If A and B are $n \times n$ matrices such that $AB = BA$ , then A and B are both nonsingular.  15. Fig. It is possible for a singular matrix to be row equivalent to the identity matrix.
<ul> <li>10.</li></ul>
11. Any two nonsingular matrices are row equivalent.  12. F If $Ax = b$ is an overdetermined and consistent linear system, then it must have infinitely many solutions.  13. A homogeneous system can have a nontrivial solution.  14. F If $A$ and $B$ are $n \times n$ matrices such that $AB = BA$ , then $A$ and $B$ are both nonsingular.  15. F It is possible for a singular matrix to be row equivalent to the identity matrix.
12. Figure 12. If $A\mathbf{x} = \mathbf{b}$ is an overdetermined and consistent linear system, then it must have infinitely many solutions.  13. A homogeneous system can have a nontrivial solution.  14. Figure 14 A and B are $n \times n$ matrices such that $AB = BA$ , then A and B are both nonsingular.  15. Figure 15 It is possible for a singular matrix to be row equivalent to the identity matrix.
solutions.  13. A homogeneous system can have a nontrivial solution.  14. If A and B are $n \times n$ matrices such that $AB = BA$ , then A and B are both nonsingular.  15. It is possible for a singular matrix to be row equivalent to the identity matrix.
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16 If A is a $3 \times 3$ matrix, then $ -2A  = -2 A $ .
17. If A is an $n \times n$ matrix, then $ A^n  =  A ^n$
18. $A = 0$ , then A must have two identical rows or two identical columns.
19. If A is an $n \times n$ matrix, and $A\mathbf{x} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ has a unique solution, then $A\mathbf{x} = \mathbf{b}$ has a unique solution for every $\mathbf{b} \in \mathbb{R}^3$
20. F If a matrix is in row echelon form, then it is also in reduced row echelon form.

Question 2 (3 points each ) Circle the most correct answer:

- 1. Let  $A = \begin{bmatrix} 1 & 2 & 1 \\ -1 & 1 & 0 \\ 1 & 8 & 1 \end{bmatrix}$ . If we want to find the LU factorization of A, then  $L = \begin{bmatrix} 1 & 2 & 1 \\ -1 & 1 & 0 \\ 1 & 8 & 1 \end{bmatrix}$ .

  - (a)  $\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ -1 & -2 & 1 \end{bmatrix}$ (b)  $\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ -1 & -8 & 1 \end{bmatrix}$

  - (d)  $\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & 8 & 1 \end{bmatrix}$
- 2. If  $det(A) \neq 0$  then
  - (a) Ax = 0 has only the trivial solution
  - (b) A is row equivalent to I
  - (c) A is nonsingular
  - (d) All of the above
- 3. Let  $A = \begin{bmatrix} a & 1 & 1 \\ a & 2 & 0 \\ -2 & 2 & a \end{bmatrix}$ . Then A is nonsingular if and only if
  - (a) a = 2

  - (b) a = -2 (c) a is any real number
  - (d)  $a = \pm 2$
- 4. If B = EA, where E is an elementary matrix of type I, then
  - (a) |B| = |E|
  - (b) |B| = -|E|

  - (c) |B| = |A|(d) |B| = -|A|
- 5. If A and B are  $n \times n$  matrices such that A singular and B is nonsingular, then
  - (a) AB is singular
  - (b) A + B is singular
  - (c) AB = O
  - (d) AB is nonsingular

6. If A is a  $3 \times 5$  matrix, then

- (a) Ax = 0 has only the trivial solution.
- (b)  $A\mathbf{x} = \mathbf{b}$  is consistent for every vector  $b \in \mathbb{R}^5$ .
- (c)  $A\mathbf{x} = \mathbf{b}$  is inconsistent for every vector  $b \in \mathbb{R}^5$ .
- (d) Ax = 0 has infinitely many solutions.

7. Let A be a  $3 \times 3$  matrix and suppose that  $A \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ . Then

- (a) A is nonsingular
- $\widehat{\mathrm{(b)}}$   $A\mathbf{x}=0$  has infinitely many solutions
- (c)  $A\mathbf{x} = (1,0,0)^T$  has infinitely many solutions
- (d) None of the above

8. Let  $A = \begin{bmatrix} a & b & c \\ d & e & f \\ a & b & i \end{bmatrix}$  and  $B = \begin{bmatrix} a & 4d & a+g \\ b & 4e & b+h \\ c & 4f & c+i \end{bmatrix}$ . If |A| = 3 then |B| = 1

- (a) 3
- (c) 6
- (d) 24

9. If A is a  $4 \times 4$  matrix with det(A) = 2 then  $det(4A^{-1})$  is

10. Let  $A = \begin{bmatrix} 2 & 3 \\ 4 & 1 \end{bmatrix}$ . Then the adjoint of A is

- (a)  $\begin{bmatrix} 1 & -4 \\ -3 & 2 \end{bmatrix}$
- (b)  $\begin{bmatrix} -1 & 3 \\ 4 & -2 \end{bmatrix}$
- $\bigcirc \left[\begin{array}{cc} 1 & -3 \\ -4 & 2 \end{array}\right]$
- (d)  $\begin{bmatrix} -1 & 4 \\ 3 & -2 \end{bmatrix}$