

3.3

Let $v_1, v_2, \dots, v_n \in V$.

consider $c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0$.

1) we say v_1, v_2, \dots, v_n are called linearly independent if the system $c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0$ has only the zero solution.

2) If $c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0$ has nonzero solution, we say v_1, v_2, \dots, v_n are linearly dependent.

* v_1, v_2, \dots, v_n are L.I.D. \Leftrightarrow There exists scalars c_1, c_2, \dots, c_n not all zero such that $c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0$.

Ex: $v_1 = \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}, v_2 = \begin{pmatrix} -2 \\ 3 \\ 1 \end{pmatrix}, v_3 = \begin{pmatrix} -1 \\ 3 \\ 8 \end{pmatrix}$. L.I.D or L.I.

Solve $c_1 \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} + c_2 \begin{pmatrix} -2 \\ 3 \\ 1 \end{pmatrix} + c_3 \begin{pmatrix} -1 \\ 3 \\ 8 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ (*)

$$\begin{pmatrix} 1 & -2 & -1 \\ -1 & 3 & 3 \\ 2 & 1 & 8 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -2 & -1 \\ 0 & 1 & 2 \\ 0 & 5 & 10 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & -2 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & -2 & -1 \\ -1 & 3 & 3 \\ 2 & 1 & 8 \end{pmatrix}$$

$$\det(A) = 0$$

A singular

$\therefore (*)$ has non-zero solutions.

solutions.

so (*) has nonzero solutions.

$\Rightarrow v_1, v_2, v_3$ are L.I.D.

* Ex: $P_1(x) = x^2 + x + 1$, $P_2(x) = x - 1$, $P_3(x) = x^2 + 1$. L.D. or L.I.

Solve $c_1(x^2 + x + 1) + c_2(x - 1) + c_3(x^2 + 1) = 0$.

coef. x^2 : $c_1 + c_3 = 0$
 x : $c_1 + c_2 = 0$
const.: $c_1 - c_2 + c_3 = 0$

(*) $A = \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & -1 & 1 \end{pmatrix}$

$$\det(A) = \begin{vmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & -1 & 1 \end{vmatrix} = 1 + (-2) = -1 \neq 0$$

$\Rightarrow A$ is nonsingular. \Rightarrow (*) has only the zero solution $c_1 = c_2 = c_3 = 0$.

$\Rightarrow P_1(x), P_2(x), P_3(x)$ are L.I.

Remarks: If $v_1, v_2, \dots, v_n \in \mathbb{R}^{(n)}$, then

v_1, v_2, \dots, v_n are L.I. \Leftrightarrow the matrix

$A = (v_1 \ v_2 \ \dots \ v_n)$ is nonsingular.

* The system $c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0$ \Leftrightarrow

$A c = 0$: $A = (v_1 \ v_2 \ \dots \ v_n)$
 $c = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}$

$c = \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix}$
 so v_1, v_2, \dots, v_n are L.I. $\Leftrightarrow Ax=0$
 has only the zero solution.
 $\Leftrightarrow \det(A) \neq 0$
 $\Leftrightarrow A$ is nonsingular

columns of A.

$v_1, v_2, \dots, v_n \in \mathbb{R}^n$ are L.D. \Leftrightarrow
 the matrix $A = (v_1 \ v_2 \ \dots \ v_n)$ is singular.
 $\Leftrightarrow \det(A) = 0$.

The matrix $A_{n \times n}$ is nonsingular \Leftrightarrow
 columns of A are L.I.

Ex: $v_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, v_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, v_3 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, v_4 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, v_5 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$
 are L.I. or L.D.

Method I: solve $c_1 v_1 + c_2 v_2 + c_3 v_3 + c_4 v_4 = 0$

4 vectors in \mathbb{R}^4

Let $A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix}$

$|A| = \begin{vmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{vmatrix} = 1 \cdot \begin{vmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 1 \cdot \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix} = 1 \cdot 1 = 1 \neq 0$
 $\rightarrow A$ is nonsingular

$\Rightarrow A$ is non-invertible.

$\Rightarrow v_1, v_2, v_3, v_4$ are L.I.

* Let $v_1, v_2, \dots, v_n \in V$ are L.I.D. \Leftrightarrow
 $\exists c_1, c_2, \dots, c_n$ not all zero such that

$$c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0.$$

c_1, c_2, \dots, c_n are not all zero \Rightarrow
at least one of c_1, \dots, c_n is not zero

assume $c_1 \neq 0$ ($\frac{1}{c_1} \in \mathbb{R}$).

$$\Rightarrow c_1 v_1 = -c_2 v_2 - c_3 v_3 - \dots - c_n v_n$$

$$\Rightarrow \underline{v_1} = \frac{-c_2}{c_1} v_2 - \frac{c_3}{c_1} v_3 - \dots - \frac{c_n}{c_1} v_n$$

$\Rightarrow \underline{v_1}$ is a linear combination of $\underline{v_2, \dots, v_n}$.

⊕ Th. Let $v_1, \dots, v_n \in V$. Then

① v_1, v_2, \dots, v_n are L.I.D. \Leftrightarrow one of them
can be written as a linear combination
of the other vectors.

② v_1, v_2, \dots, v_n are L.I. \Leftrightarrow none
of them can be written as a l.c. of
the other (n-1) vectors.

the other (n-1) vectors.

* v_1, \dots, v_n are L.I.

the $\boxed{c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0}$ has only the zero sol.

Ex: $P_1(x) = x^2 + x, P_2(x) = x - 1, P_3(x) = x^2 - 1, P_4(x) = 2x + 3.$

in P_3 : L.I. or L.D.

solve $\boxed{c_1(x^2+x) + c_2(x-1) + c_3(x^2-1) + c_4(2x+3) = 0.}$

Cof: $x^2: \begin{cases} c_1 + c_3 = 0 \\ c_1 + c_2 + 2c_4 = 0 \\ -c_2 - c_3 + 3c_4 = 0 \end{cases}$ } 3×4 system.

under determined homog. system.

\Rightarrow it has inf # of sol. (it has nonzero solutions) $\Rightarrow \boxed{P_1(x), \dots, P_4(x) \text{ are L.D.}}$

\Rightarrow one of them can be written as a l.c. of the others. (which one?)

solve (4): $\left(\begin{array}{cccc|c} 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 2 & 0 \\ 0 & -1 & -1 & 3 & 0 \end{array} \right)$

$$\begin{array}{c} | \quad 0 \quad - \quad 1 \quad - \quad 1 \quad | \quad 1 \quad | \quad / \\ \rightarrow \left(\begin{array}{cccc|c} 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & -1 & -1 & 3 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -2 & 5 & 0 \end{array} \right) \end{array}$$

$$c_4 = \alpha \text{ free}$$

$$c_3 = \frac{5}{2}\alpha$$

$$c_2 = c_3 - 2c_4$$

$$= \frac{5}{2}\alpha - 2\alpha = \frac{\alpha}{2}$$

$$c_1 = -c_3 = -\frac{5}{2}\alpha$$

$$\text{solution} = \begin{pmatrix} -\frac{5}{2}\alpha \\ \frac{\alpha}{2} \\ \frac{5}{2}\alpha \\ \alpha \end{pmatrix}$$

a sol
($\alpha=2$)

$$c = \begin{pmatrix} -5 \\ 1 \\ 5 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} -\frac{5}{2}\alpha \\ 0 \\ \frac{5}{2}\alpha \\ \alpha \end{pmatrix}$$

If $f_1(x), f_2(x), \dots, f_n(x)$ are functions that have derivatives up to $(n-1)$ -th der.

we define Wronskian of $f_1(x), \dots, f_n(x)$

$$\text{as } W[f_1(x), \dots, f_n(x)] = \begin{vmatrix} f_1(x) & f_2(x) & \dots & f_n(x) \\ f_1'(x) & f_2'(x) & \dots & f_n'(x) \\ f_1''(x) & f_2''(x) & \dots & f_n''(x) \\ \vdots & \vdots & \ddots & \vdots \end{vmatrix}$$

$$\begin{matrix} \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \end{matrix} \begin{vmatrix} p_1^{(1)}(x) & p_2^{(1)}(x) & \dots & p_n^{(1)}(x) \\ \vdots & \vdots & \dots & \vdots \\ p_1^{(n)}(x) & p_2^{(n)}(x) & \dots & p_n^{(n)}(x) \end{vmatrix} \quad n \times n$$

Ex: $W[\sin x, \cos x]$, $p_1(x) = \sin x$
 $p_2(x) = \cos x.$

$$W[\sin x, \cos x] = \begin{vmatrix} \sin x & \cos x \\ \cos x & -\sin x \end{vmatrix}$$

$$= -\sin^2 x - \cos^2 x.$$

$$= -1$$