

1.1 Linear Systems

$$\begin{aligned}
 a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n &= b_1 \\
 a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n &= b_2 \\
 \vdots & \\
 a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n &= b_m.
 \end{aligned}$$

unknowns: x_1, \dots, x_n
 $m \times n$ linear system
 \downarrow
 # equations

Remark: Any $m \times n$ -system either has no solution inconsistent
or exactly one solution.
or infinite # of solutions.
Consistent

Def: An $m \times n$ -system is called inconsistent if it has no solutions. It is called consistent if it has solution(s) {one or infinite solutions}.

$m \times n$ -system: Can be written as

$$\left(\begin{array}{cccc|c}
 a_{11} & a_{12} & \dots & a_{1n} & b_1 \\
 a_{21} & a_{22} & \dots & a_{2n} & b_2 \\
 \vdots & \vdots & \ddots & \vdots & \vdots \\
 a_{m1} & a_{m2} & \dots & a_{mn} & b_m
 \end{array} \right)$$

augmented matrix

$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}$ coefficient matrix.

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix} \text{ coefficient matrix.}$$

$$b = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix} \text{ constants.}$$

* $m \times n$ -system (A/b)

Ex:
$$\begin{cases} x_1 - x_2 + x_4 = 2 \\ -x_1 + 3x_2 + x_3 + x_4 = 1 \\ 4x_1 - x_3 + 3x_4 = 5 \end{cases}$$

3x4-system.

Augmented matrix (A/b)

$$\left(\begin{array}{cccc|c} 1 & -1 & 0 & 1 & 2 \\ -1 & 3 & 1 & 1 & 1 \\ 4 & 0 & -1 & 3 & 5 \end{array} \right)$$

$$-x_1 + 3x_2 + x_3 + x_4 = 1$$

Elementary Row Operations: (matrix)

- ① Row operation I: Interchange two rows. $(R_i \leftrightarrow R_j)$ etc
- " " II: Multiply a row by nonzero constant. (cR_i)
- " " III: Replace a row by its sum with a multiple of another row. $\{(kR_i + R_j) \leftrightarrow R_j\}$

$$3x_1 = -2 - 2(3) + 2 = -6 \Rightarrow x_1 = -2$$

$$3x_1 = -2 - 2(3) + 2 = -6 \Rightarrow x_1 = -2$$

Ex: (a) $3x_1 + 2x_2 - x_3 = -2$

back substitution

$$\begin{aligned} x_2 &= 3 \\ 2x_3 &= 4 \end{aligned}$$

Solution (a)

$$x = \begin{pmatrix} -2 \\ 3 \\ 2 \end{pmatrix}$$

(b) $3x_1 + 2x_2 - x_3 = -2$

$$-3x_1 - x_2 + x_3 = 5$$

$$3x_1 + 2x_2 + x_3 = 2$$

(b) has the same solutions as (a).

so $x = \begin{pmatrix} -2 \\ 3 \\ 2 \end{pmatrix}$ is solution to (b)

Def: Two systems with the same unknowns are called equivalent if they have the same solution set.

Remark: Given an $m \times n$ -system $(A|b)$

Applying E.R.O.'s $\{I, II, III\}$ on $(A|b)$ produces

an equivalent system $(U|d)$.

easy to solve.

Ex:

$$\begin{aligned} 3x_1 + 2x_2 - x_3 &= -2 \\ -3x_1 - x_2 + x_3 &= 5 \\ 3x_1 + 2x_2 + x_3 &= 2 \end{aligned} \quad (b)$$

$x_1 = -2$

$$5x_1 + 2x_2 + x_3 = 4$$

$$\left(\begin{array}{ccc|c} 3 & 2 & -1 & -2 \\ -3 & -1 & 1 & 5 \\ 3 & 2 & 1 & 2 \end{array} \right) \xrightarrow{\substack{(R_1+R_2) \leftrightarrow R_2 \\ (-R_1+R_3) \leftrightarrow R_3}} \left(\begin{array}{ccc|c} 3 & 2 & -1 & -2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 2 & 4 \end{array} \right) \rightarrow \begin{array}{l} 3x_1 = -2 - 2(3) + 2 \\ x_2 = 3 \\ x_3 = 2 \end{array}$$

solution $x = \begin{pmatrix} -2 \\ 3 \\ 2 \end{pmatrix}$ to (6)

Def: An $m \times n$ -system is said to be in strict triangular form if in k th equation, the coefficients of x_1, \dots, x_{k-1} are all zero and the coefficient of x_k is non zero.

back substitution

$$\left. \begin{array}{l} 2x_1 + x_2 - x_3 = 1 \\ -x_2 + 3x_3 = 2 \\ 2x_3 = 6 \end{array} \right\}$$

in strict triangular form.

so it has one solution.

2x2-system
3+3?

Ex:

$$\left. \begin{array}{l} x_1 + x_2 + x_3 + x_4 + x_5 = 1 \\ -x_1 - x_2 + x_5 = -1 \\ -2x_1 - 2x_2 + 3x_5 = 1 \\ x_2 + x_3 + x_4 + 3x_5 = -1 \\ x_1 + x_2 + 2x_3 + 2x_4 + 4x_5 = 1 \end{array} \right\}$$

5x5

pivot element.

$$\left(\begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 1 \\ -1 & -1 & 0 & 0 & 1 & -1 \\ -2 & -2 & 0 & 0 & 3 & 1 \\ 0 & 1 & 1 & 1 & 3 & -1 \\ 1 & 1 & 2 & 2 & 4 & 1 \end{array} \right)$$

$$\begin{array}{c}
 \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ -1 & -1 & 0 & 0 & 1 & -1 \\ -2 & -2 & 0 & 0 & 3 & 1 \\ 0 & 1 & 1 & 1 & 3 & -1 \\ 1 & 1 & 2 & 2 & 4 & 1 \end{pmatrix} \xrightarrow{\substack{R_1+R_2 \\ 2R_1+R_3 \\ -R_1+R_5}} \\
 \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 2 & 1 & 1 & 2 & 0 \\ 0 & 0 & 2 & 2 & 5 & 3 \\ 0 & 1 & 1 & 1 & 3 & -1 \\ 0 & 0 & 1 & 1 & 3 & 0 \end{pmatrix}
 \end{array}$$

$$\begin{array}{c}
 \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 3 & -1 \\ 0 & 0 & 2 & 2 & 5 & 3 \\ 0 & 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 1 & 1 & 3 & 0 \end{pmatrix} \xrightarrow{\substack{R_2 \leftrightarrow R_4 \\ R_3 \leftrightarrow R_4}} \\
 \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 3 & -1 \\ 0 & 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 2 & 2 & 5 & 3 \\ 0 & 0 & 1 & 1 & 3 & 0 \end{pmatrix} \xrightarrow{\substack{R_3 \leftrightarrow R_4 \\ \text{pivot element}}} \\
 \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 3 & -1 \\ 0 & 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 2 & 2 & 5 & 3 \\ 0 & 0 & 1 & 1 & 3 & 0 \end{pmatrix}
 \end{array}$$

$$\begin{array}{c}
 \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 3 & -1 \\ 0 & 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix} \xrightarrow{\substack{-2R_3+R_4 \\ -R_3+R_5}} \\
 \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 3 & -1 \\ 0 & 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 & 0 & -3 \end{pmatrix} \xrightarrow{-R_4+R_5} \\
 \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 3 & -1 \\ 0 & 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 & 0 & -3 \end{pmatrix}
 \end{array}$$

$$0 = -3$$

$$0x_1 + 0x_2 + 0x_3 + 0x_4 + 0x_5 = -3$$

The system is inconsistent