

Def.: An $m \times n$ -system is called overdetermined if $m > n$
underdetermined if $m < n$.
square if $m = n$.

Ex: $x_1 + x_2 = 1$
 $x_1 - x_2 = 3$
 $-x_1 + 2x_2 = -2$

} 3×2 -system
overdetermined.

$$\left(\begin{array}{cc|c} 1 & 1 & 1 \\ 1 & -1 & 3 \\ -1 & 2 & -2 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} 1 & 1 & 1 \\ 0 & -2 & 2 \\ 0 & 3 & -1 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 3 & -1 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 2 \end{array} \right) \rightarrow \text{The system is inconsistent.}$$

solve

Ex: $\left(\begin{array}{ccc|c} 1 & 2 & 1 & 1 \\ 2 & -1 & 1 & 2 \\ 4 & 3 & 3 & 4 \\ 2 & -1 & 3 & 5 \end{array} \right)$

4×3 -system
overdetermined.

$$\rightarrow \rightarrow \rightarrow \left(\begin{array}{ccc|c} 1 & 2 & 1 & 1 \\ 0 & 1 & \frac{1}{5} & 0 \\ 0 & 0 & 1 & \frac{3}{2} \\ 0 & 0 & 0 & 0 \end{array} \right) \rightarrow x_1 = 1 - 2x_2 - x_3 = 1 - 2\left(\frac{-2}{10}\right) - \frac{3}{2} = \frac{1}{10}$$

$$\rightarrow x_2 = -\frac{1}{5}x_3 = -\frac{1}{5}\left(\frac{3}{2}\right) = \frac{-3}{10}$$

$$\rightarrow x_3 = \frac{3}{2}$$

consistent: } leading variables: x_1, x_2, x_3
} No free variables.
} one solution.

sol. $x = \begin{pmatrix} 1/10 \\ -3/10 \\ 3/2 \end{pmatrix}$

Ex:
$$\begin{cases} x_1 + 2x_2 + x_3 = 1 \\ 2x_1 - x_2 + x_3 = 2 \\ 4x_1 + 3x_2 + 3x_3 = 4 \\ 3x_1 + x_2 + 2x_3 = 3 \end{cases}$$

4x3-system
overdetermined.

$$\left(\begin{array}{ccc|c} 1 & 2 & 1 & 1 \\ 2 & -1 & 1 & 2 \\ 4 & 3 & 3 & 4 \\ 3 & 1 & 2 & 3 \end{array} \right)$$

$\rightarrow \rightarrow$

$$\left(\begin{array}{ccc|c} 1 & 2 & 1 & 1 \\ 0 & 1 & \frac{1}{5} & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$x_1 = 1 - \frac{3}{5}\alpha$
 $x_1 = 1 - 2\left(\frac{-\alpha}{5}\right) - \alpha$
 $x_2 = -\frac{1}{5}\alpha$

consistent.

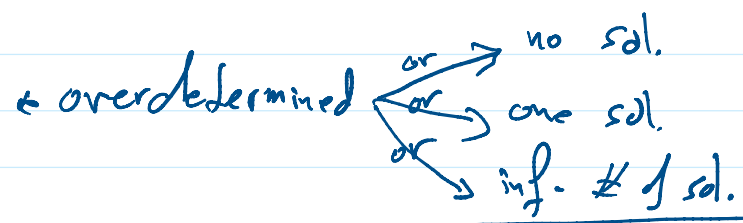
$x_3 = \alpha$

free variable \Rightarrow

inf. # of sol.

Any solution has the form

$$x = \begin{pmatrix} 1 - \frac{3\alpha}{5} \\ -\frac{\alpha}{5} \\ \alpha \end{pmatrix}$$



Ex:
$$\begin{cases} x_1 + 2x_2 + x_3 = 1 \\ 2x_1 + 4x_2 + 2x_3 = 3 \end{cases}$$

2x3-system.
undetermined.

$$\left(\begin{array}{ccc|c} 1 & 2 & 1 & 1 \\ 2 & 4 & 2 & 3 \end{array} \right)$$

$$\left(\begin{array}{ccc|c} 1 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{array} \right)$$

The system is inconsistent (No sol.)

Ex:
$$\left(\begin{array}{cccc|c} 1 & 1 & 1 & 1 & 2 \\ 1 & 1 & 1 & 2 & 3 \\ 1 & 1 & 1 & 2 & 2 \end{array} \right)$$

3x5-system.
undetermined.

$$\left(\begin{array}{cccc|c} 1 & 1 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right) \rightarrow x_1 = 2 - \alpha - \beta - \gamma + 1 = 1 - \alpha - \beta$$

$$\left(\begin{array}{cccc|c} 1 & 1 & 1 & 1 & 2 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & -1 \end{array} \right) \rightarrow \begin{aligned} x_1 &= 2 - \alpha - \beta - 2 + 1 = 1 - \alpha - \beta \\ x_4 &= 1 - (-1) = 2 \\ x_5 &= -1 \end{aligned}$$

Consistent: free variables: $x_2 = \alpha$, $x_3 = \beta$.

has inf. # of sol.

Any solution has the form

$$x = \begin{pmatrix} 1 - \alpha - \beta \\ \alpha \\ \beta \\ 2 \\ -1 \end{pmatrix}$$

For any $m \times n$ -system:

$$\# \text{ of leading variables} \leq m$$

\downarrow
of rows

Th. If an $m \times n$ -system is consistent and underdetermined then it has infinite number of solutions.

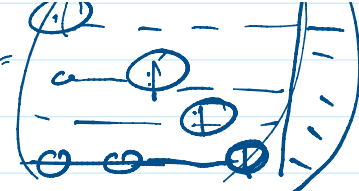
Proof: Given an $m \times n$ -system $(A|b)$ and assume it is consistent and $m < n$ {underdetermined}.

Use G.E.M to get $(U|d)$ in R.E.F.

The system is consistent $\Rightarrow (U|d)$ has no row of the form $(0 \ 0 \ \dots \ 0 \ | \ c \neq 0)$.

Now in $(U|d)$ we have $\# \text{ of leading variables} \leq \# \text{ of rows}$

$$\# \text{ of leading variables} \leq m < n (UA) = \begin{pmatrix} \text{---} \\ \text{---} \\ \text{---} \end{pmatrix}$$

of leading variables $\leq m$ $\leftarrow n$ (UA) 
 but $m < n = \#$ of variables.

\Rightarrow # of leading variables $<$ $n = \#$ of variables.

\Rightarrow # of variables $-$ # of leading variables > 0 .

\Rightarrow # of free variables > 0 .

\Rightarrow there are free variables
 so the system has inf. # of solutions.

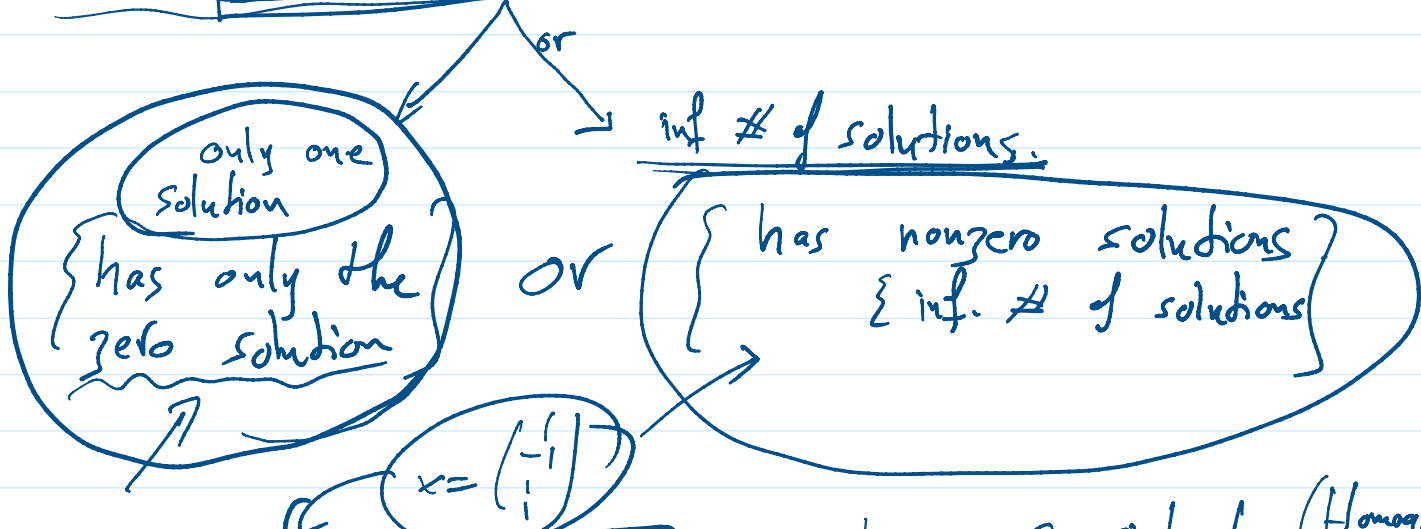
a Homogeneous system:

An $m \times n$ system is called homogeneous if
 $b_1 = b_2 = \dots = b_m = 0$.

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = 0 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = 0 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = 0. \end{cases} \quad \underline{\text{Homog. system.}}$$

a Remark! $x = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$ is a solution to Homog. system.
 is called zero solution (trivial solution)

1) Any homogenous system is consistent.



Ex.
$$\begin{cases} -x_1 + x_2 - x_3 + 3x_4 = 0 \\ 3x_1 + x_2 - x_3 - x_4 = 0 \\ 2x_1 - x_2 - 2x_3 - x_4 = 0. \end{cases}$$
 solve 3×4 system

Consistent. (Homog.)
and underdetermined.
has inf. # of solutions.

$$\left(\begin{array}{cccc|c} 1 & -1 & 1 & -3 & 0 \\ 3 & 1 & -1 & -1 & 0 \\ 2 & -1 & -2 & -1 & 0 \end{array} \right) \xrightarrow{\substack{-3R_1 + R_2 \\ -2R_1 + R_3}} \left(\begin{array}{cccc|c} 1 & -1 & 1 & -3 & 0 \\ 0 & 4 & -4 & 8 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{array} \right)$$

$$\left(\begin{array}{cccc|c} 1 & -1 & 1 & -3 & 0 \\ 0 & 1 & -4 & 5 & 0 \\ 0 & 4 & -4 & 8 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} 1 & -1 & 1 & -3 & 0 \\ 0 & 1 & -4 & 5 & 0 \\ 0 & 0 & 12 & -12 & 0 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{cccc|c} 1 & -1 & 1 & -3 & 0 \\ 0 & 1 & -4 & 5 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{array} \right) \rightarrow \begin{cases} x_1 = -x_2 - x_3 + 3x_4 = \alpha \\ x_2 = 4x_3 - 5x_4 = \alpha \\ x_3 = \alpha \end{cases}$$

$$\left(\begin{array}{cccc|c} 0 & 0 & 0 & 0 & 1 \end{array} \right) \\ 0=1 \text{ No solution.}$$

~~$$\left(\begin{array}{cccc|c} 0 & 0 & 0 & 0 & c \neq 0 \end{array} \right)$$~~

consistent, $x_4 = \alpha$ is free.
the system has inf # of solutions

Any solution has the form $x = \begin{pmatrix} \alpha \\ -\alpha \\ \alpha \\ \alpha \end{pmatrix}$

$$\left(\begin{array}{cccc|c} 0 & 0 & 0 & 1 & 0 \end{array} \right) \rightarrow x_4 = 0$$

Any solution has the form $x = \begin{pmatrix} \alpha \\ \alpha \\ \alpha \\ \alpha \end{pmatrix}$ LGR. $(0 \ 0 \ 0 \ 1 \mid 0) \rightarrow x_4 = 0$

(take $\alpha = 0 \Rightarrow x = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$ is a sol.)

$\alpha = 1 \Rightarrow x = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$ is a sol.

Def. A matrix M is called in reduced row echelon form {RREF} if REF

1) M is in REF.

2) each leading one is the only nonzero element in its column.

Ex. $A = \begin{pmatrix} 1 & 0 & 1 & 2 & 0 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$

REF ✓
in RREF.

$A = \begin{pmatrix} 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$

REF. ✓
not RREF.

* Any matrix can be transformed into a matrix in RREF. (How?).