

Linear System:

$$\underset{n \times n}{A} \underset{n \times 1}{X} = \underset{n \times 1}{b}$$

which is equivalent to

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n &= b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n &= b_2 \\ \vdots & \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n &= b_n \end{aligned}$$

Cost (Complexity): is the number of operations $+$, $-$, \times , \div required to complete a certain calculation.

Exp¹ Let $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$. Find the cost of finding $|A| = \det(A)$

$$|A| = a \times d - b \times c \Rightarrow \text{Cost} = 3$$

Exp² Let $A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$. Find the cost of calculating $|A|$.

$$|A| = a \times \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \times \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \times \begin{vmatrix} d & e \\ g & h \end{vmatrix}$$

$\begin{matrix} \nearrow \\ \text{cost} = 3 \end{matrix}$
 $\begin{matrix} \nearrow \\ \text{cost} = 3 \end{matrix}$
 $\begin{matrix} \nearrow \\ \text{cost} = 3 \end{matrix}$
by exp¹

$$\text{Cost} = 14$$

Remark: My student proved that the cost of finding $|A_{n \times n}|$ for $n \geq 2$

is ① $\text{cost} = n! \sum_{k=2}^n \frac{2k-1}{k!}$ or

② $\text{cost} = [n! e - 2]$ where $[]$ is the greatest integer function and $e \approx 2.718$

Exercise show that $n! \sum_{k=2}^n \frac{2k-1}{k!} = [n! e^{-2}]$

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where $[]$ is the greatest integer function

Proof: $n! \sum_{k=2}^n \frac{2k-1}{k!} = n! \sum_{k=2}^n \left(\frac{2k}{k!} - \frac{1}{k!} \right)$ $k! = k(k-1)!$

$$= n! \left[2 \sum_{k=2}^n \frac{1}{(k-1)!} - \sum_{k=2}^n \frac{1}{k!} \right]$$

$$= n! \left[2 \left(1 + \sum_{k=3}^n \frac{1}{(k-1)!} \right) - \sum_{k=2}^n \frac{1}{k!} + \sum_{k=2}^n \frac{1}{k!} - \sum_{k=2}^n \frac{1}{k!} \right]$$

$$= n! \left[2 + \sum_{k=2}^n \frac{1}{k!} + 2 \left(\sum_{k=3}^n \frac{1}{(k-1)!} - \sum_{k=2}^n \frac{1}{k!} \right) \right]$$

shifting index \swarrow

Note that $\sum_{k=2}^{n-1} \frac{1}{k!} - \sum_{k=2}^n \frac{1}{k!} = 0 + 0 + \dots + 0 - \frac{1}{n!} = -\frac{1}{n!}$

$$= n! \left[2 + \sum_{k=2}^n \frac{1}{k!} - \frac{2}{n!} \right]$$

$\sum_{k=0}^n \frac{1}{k!}$

$$= n! \left[\sum_{k=0}^n \frac{1}{k!} - \frac{2}{n!} \right]$$

$$= n! \sum_{k=0}^n \frac{1}{k!} - 2$$

• But $e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!}$ so $e = \sum_{k=0}^{\infty} \frac{1}{k!}$

• Hence, $n! e = n! \sum_{k=0}^n \frac{1}{k!} + n! \sum_{k=n+1}^{\infty} \frac{1}{k!}$

• That is, $n! \sum_{k=0}^n \frac{1}{k!} = n! e - n! \sum_{k=n+1}^{\infty} \frac{1}{k!}$

• Now $n! \sum_{k=2}^n \frac{2k-1}{k!} = n! \sum_{k=0}^n \frac{1}{k!} - 2$
 $= n! e - 2 - n! \sum_{k=n+1}^{\infty} \frac{1}{k!}$

Assume this value is R

• Note that R represents the error of calculating $n! e$ which is always less than one " since k starts at $n+1$ and we have $n \geq 2$ " .

• So we can get rid of R by taking the floor function or greatest integer number.

• That is, $n! \sum_{k=2}^n \frac{2k-1}{k!} = [n! e - 2]$

- $[2.9] = 2$
- $[2.5] = 2$
- $[2.1] = 2$
- $[-2.9] = -3$
- $[-2.1] = -3$

Exp³ Let A be 3×3 matrix.

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Find the cost of calculating A^2 .

$$A^2 = A A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$$
$$= \begin{bmatrix} a \times a + b \times d + c \times g & \textcircled{5} & \textcircled{5} \\ \textcircled{5} & \textcircled{5} & \textcircled{5} \\ \textcircled{5} & \textcircled{5} & \textcircled{5} \end{bmatrix}$$

Cost = $(9)(5) = 45$

Exp⁴ Let A and B be 3×3 matrices.

Find the cost of $A + |B| B$

$|B|$ requires cost = 14 by Exp²

$|B| \times B$ requires cost = 9

$A + |B| B$ requires cost = 9

Total Cost = 32

Result: If A is $n \times n$ matrix, then the cost of calculating A^2 is $2n^3 - n^2$

check!
see page 58

see Exp³ $\Rightarrow n=3 \Rightarrow 2(3)^3 - (3)^2 = 2(27) - 9$
 $= 54 - 9$
 $= 45$

3.3 Backward Substitution

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Backward substitution method used to solve a linear system of equations that has an upper-triangular coefficient matrix:

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1$$

$$a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n = b_2$$

$$a_{33}x_3 + \dots + a_{3n}x_n = b_3$$

...

$$a_{nn}x_n = b_n$$

$$\left[\begin{array}{cccc|c} a_{11} & a_{12} & a_{13} & \dots & a_{1n} & b_1 \\ 0 & a_{22} & a_{23} & \dots & a_{2n} & b_2 \\ 0 & 0 & a_{33} & \dots & a_{3n} & b_3 \\ \vdots & \vdots & \vdots & \dots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & a_{nn} & b_n \end{array} \right]$$

$$= [U|b]$$

↑
coefficient matrix

Exp Solve the following linear system using Backward Substitution and find the cost.

$$4x_1 - x_2 + 2x_3 + 3x_4 = 20$$

$$-2x_2 + 7x_3 - 4x_4 = -7$$

$$6x_3 + 5x_4 = 4$$

$$3x_4 = 6$$

step 1 : $x_4 = \frac{6}{3} = 2$

⇒ one operation

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- , + 0
÷ , × 1

step 2 : $x_3 = \frac{4 - 5 \times 2}{6} = -1$

⇒ Three operations

- , + 1
÷ , × 2

step 3 : $x_2 = \frac{-7 \times -1 + 4 \times 2 - 7}{-2} = -4$

⇒ Five operations

- , + 2
÷ , × 3

step 4 : $x_1 = \frac{1 \times -4 - 2 \times -1 - 3 \times 2 + 20}{4} = 3$

⇒ Seven operations

- , + 3
÷ , × 4

Hence, total cost = $16 = (4)^2 = n^2$

Cost of Backward Substitution (B.S.)
for solving $n \times n$ linear system

step	+ , -	× , ÷
1	0	1
2	1	2
3	2	3
4	3	4
⋮	⋮	⋮
n	n-1	n

Total + , - is $0 + 1 + 2 + 3 + \dots + n-1 = \frac{n(n-1)}{2} = \frac{n^2 - n}{2}$

Total × , ÷ is $1 + 2 + 3 + 4 + \dots + n = \frac{n(n+1)}{2} = \frac{n^2 + n}{2}$

Hence, total cost = $\frac{n^2 - n}{2} + \frac{n^2 + n}{2} = n^2$

$$1 + 2 + 3 + \dots + n = \sum_{k=1}^n k = \frac{n(n+1)}{2}$$

$$1 + 2^2 + 3^2 + \dots + n^2 = \sum_{k=1}^n k^2 = \frac{n(n+1)(2n+1)}{6}$$

Five Methods to solve the linear system $AX=b$

① Gaussian Elimination:

$$\begin{array}{ccc} (A|b) & \xrightarrow{\quad} & (U|c) \\ \text{Augmented} & & \text{Upper} \\ \text{matrix} & & \text{matrix} \end{array} \quad \text{solve by B.S.}$$

② Gauss - Jordan Reduction:

$$(A|b) \xrightarrow{\quad} (I|X)$$

③ Inverse Method:

• Find A^{-1} :

$$(A|I) \xrightarrow{\quad} (I|A^{-1})$$

• Then $X = A^{-1}b$

④ Cramer's Rule:

• Find $|A| \neq 0$

$$\text{• Then } x_1 = \frac{|A_1|}{|A|}, \quad x_2 = \frac{|A_2|}{|A|}, \quad \dots, \quad x_n = \frac{|A_n|}{|A|}$$

[5] LU Factorization:

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- Write $A = LU$ where L is lower triangle matrix
 U is upper triangle matrix
- Let $Y = UX \Rightarrow$
 $AX = b$ becomes $LUX = b$
 $LY = b$
- Now solve $LY = b$ by F.S and find Y
- Then solve $UX = Y$ by B.S and find X

Remark: The speed of these methods is like this

$$[4] < [3] < [2] < [1] = [5]$$

Exp show that if A is $n \times n$ matrix, then the cost of finding A^2 is $2n^3 - n^2$

$$A^2 = AA = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \dots & c_{1n} \\ c_{21} & c_{22} & \dots & c_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ c_{n1} & c_{n2} & \dots & c_{nn} \end{bmatrix}$$

$$c_{11} = a_{11} \times a_{11} + a_{12} \times a_{12} + \dots + a_{1n} \times a_{1n} \quad \begin{array}{l} \text{costs } n \text{ for } \times \\ n-1 \text{ for } + \\ \hline 2n-1 \end{array}$$

Hence, c_{11} costs $2n-1$

But A^2 has n^2 elements and each one costs $2n-1$

Hence, total cost of calculating A^2 is

$$n^2 (2n-1) = 2n^3 - n^2$$

I Gaussian Elimination (G.E.)

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The Augmented matrix is denoted by

$$[A|b] = \left[\begin{array}{cccc|c} a_{11} & a_{12} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & b_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} & b_n \end{array} \right] \dots *$$

Th (Elementary Row Operations ERO)

The following operations applied to the augmented matrix * yield an equivalent linear system:

Row Operation I: Interchange two rows

Row Operation II: Multiply a row by a nonzero constant

Row operation III: The row R_K can be replaced by the sum of R_K and a nonzero multiple of any other row R_P . That is, $R_K = R_K - m_{KP} R_P$

where $m_{KP} = \frac{a_{KP}}{a_{PP}}$ is called the KP multiplier

Exp Consider the following linear system:

$$x_1 + 2x_2 + x_3 + 4x_4 = 13$$

$$2x_1 \quad + 4x_3 + 3x_4 = 28$$

$$4x_1 + 2x_2 + 2x_3 + x_4 = 20$$

$$-3x_1 + x_2 + 3x_3 + 2x_4 = 6$$

$$n = 4$$

i Express this system in augmented matrix form.

Pivot

$$m_{21} = \frac{a_{21}}{a_{11}} = 2$$

$$m_{31} = \frac{a_{31}}{a_{11}} = 4$$

$$m_{41} = \frac{a_{41}}{a_{11}} = -3$$

are the multipliers

$$\left(\begin{array}{cccc|c} 1 & 2 & 1 & 4 & 13 \\ 2 & 0 & 4 & 3 & 28 \\ 4 & 2 & 2 & 1 & 20 \\ -3 & 1 & 3 & 2 & 6 \end{array} \right) = (A | b)$$

Pivot row

or $(12)(2) = 24 + 3$
 entry operations
 $+ : - : 1$
 $\times : 1$

multiplies

ii Find an equivalent upper-triangular system using G.E.

• Step 1 • Find multipliers m_{21}, m_{31}, m_{41}

Apply them

$$R_2 - 2R_1$$

$$R_3 - 4R_1$$

$$R_4 - 3R_1$$

$$\left(\begin{array}{cccc|c} 1 & 2 & 1 & 4 & 13 \\ 0 & -4 & 2 & -5 & 2 \\ 0 & -6 & -2 & -15 & -32 \\ 0 & 7 & 6 & 14 & 45 \end{array} \right)$$

Costs

$$\div : 3$$

$$+ (- : 3(4))$$

$$\times : 3(4)$$

• Step 2 • Find multipliers $m_{32} = \frac{-6}{-4} = 1.5$ and $m_{42} = \frac{7}{-4} = -1.75$

Apply them

$$R_3 - 1.5 R_2$$

$$R_4 + 1.75 R_2$$

$$\left(\begin{array}{cccc|c} 1 & 2 & 1 & 4 & 13 \\ 0 & -4 & 2 & -5 & 2 \\ 0 & 0 & -5 & -7.5 & -35 \\ 0 & 0 & 9.5 & 5.25 & 48.5 \end{array} \right)$$

$$\div : 2$$

$$+ (- : 2(3))$$

$$\times : 2(3)$$

• step 3 • Find the multiplier $m_{43} = \frac{9.5}{-5} = -1.9$

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• Apply it

$$\left(\begin{array}{cccc|c} 1 & 2 & 1 & 4 & 13 \\ 0 & -4 & 2 & -5 & 2 \\ 0 & 0 & -5 & -7.5 & -35 \\ 0 & 0 & 0 & -9 & -18 \end{array} \right)$$

$$\begin{array}{l} \div : 1 \\ +, - : 1(2) \\ \times : 1(2) \end{array}$$

iii Use B.S to solve the resulting system

$$x_4 = \frac{-18}{-9} = 2$$

$$x_3 = \frac{7.5(2) - 35}{-5} = 4$$

$$x_2 = \frac{-2(4) + 5(2) + 2}{-4} = -1$$

$$x_1 = 13 - 2(-1) - 4 - 4(2) = 3$$

iv Find the cost of solving this system using G.E.

• Cost 1: $(A|b) \rightarrow (U|c)$ for this 4×4 system

Step	+, -	÷, ×
1	3(4)	3, 3(4)
2	2(3)	2, 2(3)
3	1(2)	1, 1(2)
Total	20	26

cost 1 = 46

• Cost 2: Using B.S. \Rightarrow cost 2 = $n^2 = 4^2 = 16$

Hence, total cost for 4×4 system = cost 1 + cost 2 = 62

Result ① The cost of reducing $n \times n$ linear system to an upper-triangular system using G.E. is

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$$\frac{4n^3 + 3n^2 - 7n}{6}$$

② The cost of solving $n \times n$ linear system using G.E. is

$$\frac{4n^3 + 9n^2 - 7n}{6}$$

Proof

① Cost of $(A|b) \rightarrow (U|c)$ as we have seen in Exp - iv page 61 is as follow:

step	+, -	÷	x
1	$(n-1)n$	$n-1$	$(n-1)n$
2	$(n-2)(n-1)$	$n-2$	$(n-2)(n-1)$
⋮	⋮	⋮	⋮
k	$(n-k)(n-k+1)$	$n-k$	$(n-k)(n-k+1)$
⋮	⋮	⋮	⋮
Total	$\sum_{k=1}^{n-1} (n-k)(n-k+1)$	$\sum_{k=1}^{n-1} (n-k)$	$\sum_{k=1}^{n-1} (n-k)(n-k+1)$

Hence, total cost is $\sum_{k=1}^{n-1} [2(n-k)(n-k+1) + n-k]$

$$= \sum_{m=1}^{n-1} [2m(m+1) + m] = \sum_{m=1}^{n-1} 2m^2 + 3m$$

$m = n - k$
 $k = 1 \Rightarrow m = n - 1$
 $k = n - 1 \Rightarrow m = 1$

$$= 2 \frac{n(n-1)(2n-1)}{6} + 3 \frac{n(n-1)}{2} = \frac{4n^3 + 3n^2 - 7n}{6}$$

② Cost of any $n \times n$ system using G.E. is cost of $(A|b) \rightarrow (U|c)$ + cost of B.S.

$$= \frac{4n^3 + 3n^2 - 7n}{6} + n^2 = \frac{4n^3 + 9n^2 - 7n}{6}$$

Gaussian Elimination and Pivoting

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- If the pivot element $a_{pp} = 0$ in row p , then row p can not be used to eliminate the elements in column p below the main diagonal.
- The process of finding a row k with nonzero pivot element $a_{kp} \neq 0$, $k > p$ and interchanging row p by row k is called **pivoting**.
- **Pivoting** is two types:

□ Trivial pivoting:

- if $a_{pp} \neq 0$, then do not switch rows
- if $a_{pp} = 0$, then switch row p by the first row k below p s.t. $a_{kp} \neq 0$.

Exp

$$\begin{bmatrix} 0 & -1 & 2 & | & 3 \\ 4 & 3 & -1 & | & 2 \\ 7 & 0 & -3 & | & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 4 & 3 & -1 & | & 2 \\ 0 & -1 & 2 & | & 3 \\ 7 & 0 & -3 & | & 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 & -1 & 2 & | & 3 \\ 0 & 2 & 4 & | & 7 \\ 1 & 2 & 3 & | & 4 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 3 & | & 4 \\ 0 & 2 & 4 & | & 7 \\ 0 & -1 & 2 & | & 3 \end{bmatrix}$$

2 Partial Pivoting:

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- if $a_{pp} = 0$ or $a_{pp} \neq 0$, choose the pivotal row k whose pivot a_{kp} , $k > p$ satisfy $|a_{kp}| = \max\{|a_{pp}|, |a_{p+1,p}|, \dots, |a_{np}|\}$
- This will make all multipliers m_{rp} , $r = p+1, \dots, n$ less than or equal to 1 in absolute value.
- And hence, reducing the error being propagated when using a finite-digit arithmetic

Exp Consider the following linear system

$$\begin{aligned} 1.133 x_1 + 5.281 x_2 &= 6.414 \\ 24.14 x_1 - 1.210 x_2 &= 22.93 \end{aligned}$$

whose solution is $(x_1, x_2) = (1, 1)$.

1 Use G.E. with **trivial pivoting** and use four-digit arithmetic to solve this system.

pivot \rightarrow $\left[\begin{array}{cc|c} 1.133 & 5.281 & 6.414 \\ 24.14 & -1.210 & 22.93 \end{array} \right]$ since pivot $a_{11} \neq 0$
so we do not switch rows

$$m_{21} = \frac{a_{21}}{a_{11}} = \frac{24.14}{1.133} = 21.31$$

$$\left[\begin{array}{cc|c} 1.133 & 5.281 & 6.414 \\ 0 & -113.7 & -113.8 \end{array} \right]$$

$$x_2 = \frac{-113.8}{-113.7} = 1.001$$

$$x_1 = \frac{6.414 - 5.281(1.001)}{1.133} = 0.9956$$

Note that the error in the solution is due to the magnitude of the multiplier m_{21} which is $\gg 1$.

2] Use G.E. with **partial pivoting** and use four-digit arithmetic to solve this system.

pivot $\left[\begin{array}{cc|c} 24.14 & -1.210 & 22.93 \\ 1.133 & 5.281 & 6.414 \end{array} \right]$

- $\max\{1.133, 24.14\} = 24.14$
- Hence, pivot = 24.14

$$m_{21} = \frac{1.133}{24.14} = 0.04693 < 1$$

$$\left[\begin{array}{cc|c} 24.14 & -1.210 & 22.93 \\ 0 & 5.338 & 5.338 \end{array} \right]$$

$$x_2 = \frac{5.338}{5.338} = 1$$

$$x_1 = \frac{22.93 + 1.210(1)}{24.14} = 1$$

No Error



2 LU - Factorization

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To solve the linear system $AX = b$:

- Write $A = LU$ where L is lower triangular matrix and U is upper triangular matrix
 - Let $Y = UX \Rightarrow$
 $AX = b$ becomes $LUX = b$
 $LY = b$
 - Now solve $LY = b$ by F.S and find Y
 - Then solve $UX = Y$ by B.S and find X
-

* We will see that :

$$\text{cost of LU} = \text{cost of G.E.}$$

Exp ① Use LU factorization to solve the linear

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system: $4x_1 + 3x_2 - x_3 = 1$

$$-2x_1 - 4x_2 + 5x_3 = 6$$

$$x_1 + 2x_2 + 6x_3 = 14$$

② find the cost of this method

① $A = \begin{pmatrix} 4 & 3 & -1 \\ -2 & -4 & 5 \\ 1 & 2 & 6 \end{pmatrix}, \quad b = \begin{pmatrix} 1 \\ 6 \\ 14 \end{pmatrix}$

• We need to write $A = LU$

• First we find U using row operations:

step 1 $m_{21} = \frac{a_{21}}{a_{11}} = \frac{-2}{4} = -0.5 \Rightarrow R_2 + 0.5 R_1$

$$m_{31} = \frac{a_{31}}{a_{11}} = \frac{1}{4} = 0.25 \Rightarrow R_3 - 0.25 R_1$$

$$\begin{pmatrix} 4 & 3 & -1 \\ 0 & -2.5 & 4.5 \\ 0 & 1.25 & 6.25 \end{pmatrix}$$

cost $\div : 2$
 $+,- : 2(2)$
 $\times : 2(2)$

step 2 $m_{32} = \frac{a_{32}}{a_{22}} = \frac{1.25}{-2.5} = -0.5 \Rightarrow R_3 + 0.5 R_2$

$$U = \begin{pmatrix} 4 & 3 & -1 \\ 0 & -2.5 & 4.5 \\ 0 & 0 & 8.5 \end{pmatrix}$$

cost $\div : 1$
 $+,- : 1(1)$
 $\times : 1(1)$

$$L = \begin{pmatrix} 1 & 0 & 0 \\ m_{21} & 1 & 0 \\ m_{31} & m_{32} & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ -0.5 & 1 & 0 \\ 0.25 & -0.5 & 1 \end{pmatrix}$$

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Note that cost of $A = LU$ is $13 = \frac{4n^3 - 3n^2 - n}{6} \Big|_{n=3}$

Now solve $LY = b$ using F.S. where $Y = UX$

$$\left(\begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ -0.5 & 1 & 0 & 6 \\ 0.25 & -0.5 & 1 & 14 \end{array} \right)$$

$$y_1 = 1$$

$$y_2 = 6 + 0.5(1) = 6.5$$

$$y_3 = 14 - 0.25(1) + 0.5(6.5) = 17$$

cost
 $\div : 0$
 $+,- : 3$
 $\times : 3$

Note that cost of F.S. is $n^2 - n = 3^2 - 3 = 9 - 3 = 6$

Now solve $UX = Y$ using B.S.

$$\left(\begin{array}{ccc|c} 4 & 3 & -1 & 1 \\ 0 & -2.5 & 4.5 & 6.5 \\ 0 & 0 & 8.5 & 17 \end{array} \right)$$

$$x_3 = \frac{17}{8.5} = 2$$

$$x_2 = \frac{6.5 - 4.5(2)}{-2.5} = \frac{-2.5}{-2.5} = 1$$

$$x_1 = \frac{1 + (2)(+1) - 3(1)}{4} = \frac{0}{4} = 0$$

cost
 $\div : 3$
 $+,- : 3$
 $\times : 3$

Note that cost of B.S. is $n^2 = 3^2 = 9$

② Hence, total cost is $13 + 6 + 9 = 28$

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Remark The total cost of solving any linear $n \times n$ system $AX = b$ using LU factorization is cost of LU + cost of F.S. + cost of B.S.

$$= \frac{4n^3 - 3n^2 - n}{6} + n^2 - n + n^2$$

$$= \frac{4n^3 + 9n^2 - 7n}{6}$$

= cost of G.E.

Exp Let A be 3×3 matrix and b_1, b_2 are 3×1 vectors.

Find the cost of solving the linear systems $AX = b_1$ and $AX = b_2$ using LU factorization.

$$\text{cost of } A = LU \text{ is } \left. \frac{4n^3 - 3n^2 - n}{6} \right|_{n=3} = 13$$

$$\text{cost of solving } AX = b_1 \Rightarrow LY = b_1 \text{ costs } \left. n^2 - n \right|_{n=3} = 6 \text{ by FS}$$

$$UX = Y \text{ costs } \left. n^2 \right|_{n=3} = 9 \text{ by BS}$$

$$\text{cost of solving } AX = b_2 \Rightarrow LY = b_2 \text{ costs } 6 \text{ using FS}$$

$$UX = Y \text{ costs } 9 \text{ using BS}$$

$$\text{Total cost} = 13 + 6 + 9 + 6 + 9$$

$$= 43$$

3 Cramer's Rule

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To solve the linear $n \times n$ system $AX = b$:

- Find $|A|$ "it should not be zero"
- The solution $X = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$ is obtained as follow:

$$x_i = \frac{|A_i|}{|A|} \text{ where } A_i \text{ is obtained by replacing the } i^{\text{th}} \text{ column of } A \text{ by the column } b \text{ for all } i=1, 2, \dots, n$$

Exp Solve the following linear system using Cramer's Rule

$$2x_1 - 3x_2 = 8$$

$$x_1 + 5x_2 = -9$$

Then find the cost.

$$A = \begin{pmatrix} 2 & -3 \\ 1 & 5 \end{pmatrix} \Rightarrow |A| = (2)(5) - (1)(-3) = 13 \quad \text{with cost:}$$

+,- : 1

$$\frac{x : 2}{3}$$

$$x_1 = \frac{|A_1|}{|A|} = \frac{\begin{vmatrix} 8 & -3 \\ -9 & 5 \end{vmatrix}}{13} = \frac{13}{13} = 1 \quad \text{with cost} = 3 + 1 = 4$$

$$x_2 = \frac{|A_2|}{|A|} = \frac{\begin{vmatrix} 2 & 8 \\ 1 & -9 \end{vmatrix}}{13} = \frac{-26}{13} = -2 \quad \text{with cost} = 3 + 1 = 4$$

$$\text{Total cost} = 3(3) + 2 = 11$$

number of determinants

cost of each one

division

Exp Assume $AX=b$ is 3×3 linear system.

71

Find the cost of solving this system using Cramer's Rule.

$$x_1 = \frac{|A_1|}{|A|}, \quad x_2 = \frac{|A_2|}{|A|}, \quad x_3 = \frac{|A_3|}{|A|}$$

$$\text{Total cost} = 4(14) + 3 = 59$$

number of determinants

cost of each one

number of divisions

Remark To solve $n \times n$ linear system by Cramer's Rule, the cost will be

$$(n+1)D_n + n \quad \text{where } D_n \text{ is the cost of } |A|$$

Exp : For 4×4 system \Rightarrow
the cost is

• $5D_4 + 4$ where

$$\begin{aligned} D_4 \text{ is the cost of } |A| &= 4D_3 + 4 + 3 \\ &= 4(14) + 7 \\ &= 63 \end{aligned}$$

• Hence, $\text{cost} = 5D_4 + 4$
 $= 5(63) + 4$
 $= 319$

4 Gauss - Jordan Reduction (G.J.R)

72

To solve the linear system $AX = b$:

$$(A|b) \rightarrow (I|X)$$

Exp Find the cost of solving the 4×4 linear system

$$2x_1 + 2x_2 + 2x_3 + 2x_4 = 4$$

$$2x_1 - x_2 + 3x_3 - 5x_4 = -7$$

$$3x_1 - 2x_2 - x_3 - 4x_4 = -2$$

$$-x_1 + 3x_2 - 2x_3 + 2x_4 = 0$$

using

G.J.R

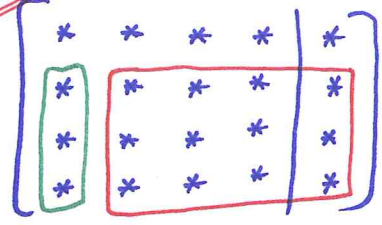
$$(A|b) = \left(\begin{array}{cccc|c} 2 & 2 & 2 & 2 & 4 \\ 2 & -1 & 3 & -5 & -7 \\ 3 & -2 & -1 & -4 & -2 \\ -1 & 3 & -2 & 2 & 0 \end{array} \right) \Rightarrow (I|X) = \left(\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 2 \end{array} \right)$$

step	+, -	÷, ×
1	3(4)	4, 3(4)
2	3(3)	3, 3(3)
3	3(2)	2, 3(2)
4	3(1)	1, 3(1)

$$\text{Total cost} = 70 = \frac{2n^3 + n^2 - n}{2} \quad \Big|_{n=4}$$

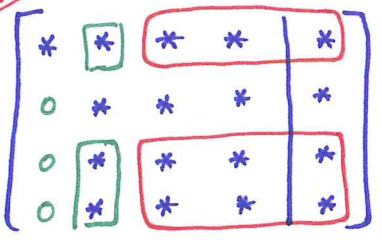
72.1

step 1



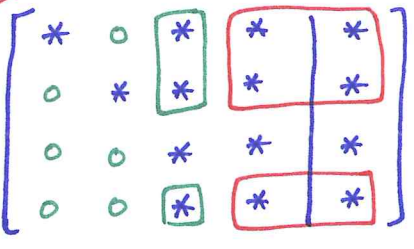
$$\begin{aligned} \text{cost of } x &= 3 \times 4 = 12 \\ \text{cost of } \pm &= 3 \times 4 = \frac{12}{24} \end{aligned}$$

step 2



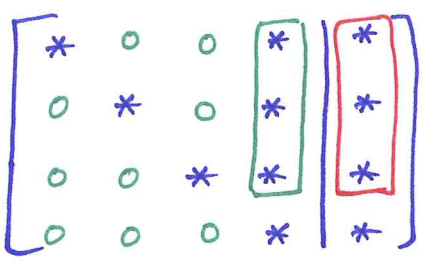
$$\begin{aligned} \text{cost of } x &= 3 \times 3 = 9 \\ \text{cost of } \pm &= 3 \times 3 = \frac{9}{18} \end{aligned}$$

step 3

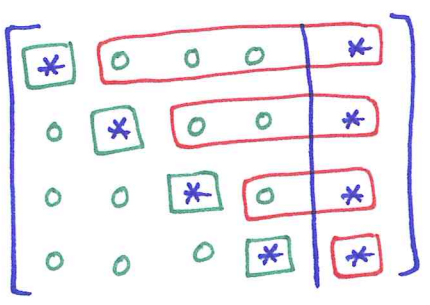


$$\begin{aligned} \text{cost of } x &= 3 \times 2 = 6 \\ \text{cost of } \pm &= 3 \times 2 = \frac{6}{12} \end{aligned}$$

step 4



$$\begin{aligned} \text{cost of } x &= 3 \times 1 = 3 \\ \text{cost of } \pm &= 3 \times 1 = \frac{3}{6} \end{aligned}$$



$$\begin{aligned} \text{cost of } \div &= 4 \\ &3 \\ &2 \\ &1 \\ \hline &10 \end{aligned}$$

Total cost =

$$\begin{aligned} &24 + \\ &18 + \\ &12 + \\ &6 + \\ \hline &10 \\ \hline &70 \end{aligned}$$

↓

$$\left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & x_1 \\ 0 & 1 & 0 & 0 & x_2 \\ 0 & 0 & 1 & 0 & x_3 \\ 0 & 0 & 0 & 1 & x_4 \end{array} \right]$$

Exp Show that the cost of solving $n \times n$ linear system using G.J.R is $\frac{2n^3 + n^2 - n}{2}$

73

step	+, -	\times, \div
1	$(n-1)n$	$n + (n-1)n$
2	$(n-1)(n-1)$	$(n-1) + (n-1)(n-1)$
3	$(n-1)(n-2)$	$(n-2) + (n-1)(n-2)$
\vdots	\vdots	\vdots
k	$(n-1)(n-k+1)$	$(n-k+1) + (n-1)(n-k+1)$
\vdots	\vdots	\vdots
n	$(n-1)(1)$	$1 + (n-1)(1)$

$$\begin{aligned}
 \text{Total cost} &= \sum_{k=1}^n [(n-1)(n-k+1) + (n-k+1) + (n-1)(n-k+1)] \\
 &= \sum_{k=1}^n (2n-1)(n-k+1) \\
 &= (2n-1) \left[n \sum_{k=1}^n 1 - \sum_{k=1}^n k + \sum_{k=1}^n 1 \right] \\
 &= (2n-1) \left[n^2 - \frac{n(n+1)}{2} + n \right] \\
 &= (2n-1) \left(\frac{n^2+n}{2} \right) \\
 &= \frac{2n^3 + n^2 - n}{2}
 \end{aligned}$$



5 Inverse Method

74

To solve the linear system $AX=b$:

• Find A^{-1} : $(A|I) \rightarrow (I|A^{-1})$

• Then $x = A^{-1}b$

Exp Find the cost of solving the following linear system using inverse method:

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 = b_1$$

$$a_{21}x_1 + a_{22}x_2 + a_{23}x_3 = b_2$$

$$a_{31}x_1 + a_{32}x_2 + a_{33}x_3 = b_3$$

• $(A|I) = \left(\begin{array}{ccc|ccc} a_{11} & a_{12} & a_{13} & 1 & 0 & 0 \\ a_{21} & a_{22} & a_{23} & 0 & 1 & 0 \\ a_{31} & a_{32} & a_{33} & 0 & 0 & 1 \end{array} \right) \rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & & & \\ 0 & 1 & 0 & & & \\ 0 & 0 & 1 & & & \end{array} \right) A^{-1}$

• Cost of $A_{3 \times 3}^{-1}$:

Step	+ , -	÷ , ×
1	2 (5)	5 , 2(5)
2	2 (4)	4 , 2(4)
3	2 (3)	3 , 2(3)
	24	12 , 24

Total cost of $A_{3 \times 3}^{-1} = 60 = \frac{n}{2}(2n-1)(3n-1)$
 $= \frac{n(6n^2 - 5n + 1)}{2}$ at $n=3$

• Cost of $x = A^{-1}b$

$= \begin{pmatrix} * & * & * \\ * & * & * \\ * & * & * \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$ is $(3+3+3) + (2+2+2) = 15 = n(2n-1)$
 $= 2n^2 - n$ at $n=3$

• Hence, total cost of 3×3 linear system using inverse method is $60 + 15 = 75$

Exp show that the cost of finding $\bar{A}_{n \times n}^{-1}$ is

75

$$\frac{n}{2} (2n-1)(3n-1)$$

step	+, -	÷, ×
1	$(n-1)(2n-1)$	$(2n-1)$, $(n-1)(2n-1)$
2	$(n-1)(2n-2)$	$(2n-2)$, $(n-1)(2n-2)$
3	$(n-1)(2n-3)$	$(2n-3)$, $(n-1)(2n-3)$
⋮	⋮	⋮
K	$(n-1)(2n-K)$	$(2n-K)$, $(n-1)(2n-K)$
⋮	⋮	⋮
n	$(n-1)n$	n , $(n-1)n$

$$\text{Total cost of } \bar{A}^{-1} = \sum_{k=1}^n [(n-1)(2n-k) + (2n-k) + (n-1)(2n-k)]$$

$$= \sum_{k=1}^n (2n-1)(2n-k)$$

$$= 2n^2(2n-1) - (2n-1) \sum_{k=1}^n k$$

$$= 2n^2(2n-1) - (2n-1) \frac{n(n+1)}{2}$$

$$= (2n-1) \left(2n^2 - \frac{n^2+n}{2} \right)$$

$$= \frac{n}{2} (2n-1)(3n-1)$$

Hence total cost of solving $n \times n$ linear system by inverse method is

$$\frac{n}{2} (2n-1)(3n-1) + n(2n-1) = \frac{n}{2} (2n-1)(3n+1)$$

Solving Nonlinear Systems of Equations

76

We will study the following three Methods:

[1] Newton's Method \rightarrow For 2×2 nonlinear system

[2] Fixed Point Iteration

[3] Gauss-Seidel Iteration

\rightarrow For 2×2 or 3×3 nonlinear systems

[1] Newton's Method

• Given 2×2 non linear system

$$f(x, y) = 0$$

$$g(x, y) = 0$$

with initial point (x_0, y_0)

• This method find a sequence of points

$(x_1, y_1), (x_2, y_2), \dots$ that approximates (x, y)

• We will only find (x_1, y_1) as follow:

$$\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} - \bar{J}^{-1}(x_0, y_0) \begin{pmatrix} f(x_0, y_0) \\ g(x_0, y_0) \end{pmatrix} \quad \dots *$$

where \bar{J} is the Jacobian matrix given by

$$\bar{J}(x, y) = \begin{pmatrix} f_x & f_y \\ g_x & g_y \end{pmatrix}$$

Exp Solve the following nonlinear system using Newton's method with initial guess $(1, \frac{1}{2})$

77

$$x^2 + y^2 = 10$$

$$xy = 5$$

use three significant digits and find the first iteration

$$\bullet \quad x^2 + y^2 - 10 = 0 \quad \rightarrow \quad f(x, y) = x^2 + y^2 - 10$$

$$xy - 5 = 0 \quad \rightarrow \quad g(x, y) = xy - 5$$

$$\bullet \quad (x_0, y_0) = (1, \frac{1}{2}) \quad \rightarrow \quad f(1, \frac{1}{2}) = 1 + 0.25 - 10 = -8.75$$

$$g(1, \frac{1}{2}) = 1 - 5 = -4.50$$

$$\bullet \quad \overline{J}(x, y) = \begin{pmatrix} f_x & f_y \\ g_x & g_y \end{pmatrix} = \begin{pmatrix} 2x & 2y \\ y & x \end{pmatrix} \quad \rightarrow \quad \overline{J}(1, \frac{1}{2}) = \begin{pmatrix} 2 & 1 \\ 0.5 & 1 \end{pmatrix}$$

$$\bullet \quad \overline{J}^{-1}(1, \frac{1}{2}) = \frac{1}{1.5} \begin{pmatrix} 1 & -1 \\ -0.5 & 2 \end{pmatrix} = \begin{pmatrix} 0.667 & -0.667 \\ -0.334 & 1.33 \end{pmatrix}$$

$$\bullet \quad \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} - \overline{J}^{-1}(x_0, y_0) \begin{pmatrix} f(x_0, y_0) \\ g(x_0, y_0) \end{pmatrix}$$

$$= \begin{pmatrix} 1 \\ 0.5 \end{pmatrix} - \begin{pmatrix} 0.667 & -0.667 \\ -0.334 & 1.33 \end{pmatrix} \begin{pmatrix} -8.75 \\ -4.50 \end{pmatrix}$$

$$= \begin{pmatrix} 1 \\ 0.5 \end{pmatrix} - \begin{pmatrix} -2.84 \\ -3.07 \end{pmatrix} = \begin{pmatrix} 3.84 \\ 3.57 \end{pmatrix}$$

$$\text{10 find } \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} - \overline{J}^{-1}(x_1, y_1) \begin{pmatrix} f(x_1, y_1) \\ g(x_1, y_1) \end{pmatrix}$$

Exp Find the first iteration that approximates the solution of the following nonlinear system

78

$$x^2 - 2x - y + 0.5 = 0$$

$$x^2 + 4y^2 - 4 = 0$$

using Newton's method and starting with $(2, 0.25)$.

$$\bullet f(x, y) = x^2 - 2x - y + 0.5 \Rightarrow f(2, 0.25) = 0.25$$

$$g(x, y) = x^2 + 4y^2 - 4 \Rightarrow g(2, 0.25) = 0.25$$

$$\bullet (x_0, y_0) = (2, 0.25)$$

$$\bullet J(x, y) = \begin{pmatrix} 2x-2 & -1 \\ 2x & 8y \end{pmatrix} \Rightarrow J(2, 0.25) = \begin{pmatrix} 2 & -1 \\ 4 & 2 \end{pmatrix}$$

$$\bullet J^{-1}(2, 0.25) = \frac{1}{8} \begin{pmatrix} 2 & 1 \\ -4 & 2 \end{pmatrix} = \begin{pmatrix} 0.25 & 0.125 \\ -0.5 & 0.25 \end{pmatrix}$$

$$\bullet \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} 2 \\ 0.25 \end{pmatrix} - \begin{pmatrix} 0.25 & 0.125 \\ -0.5 & 0.25 \end{pmatrix} \begin{pmatrix} 0.25 \\ 0.25 \end{pmatrix}$$

$$= \begin{pmatrix} 2 \\ 0.25 \end{pmatrix} - \begin{pmatrix} 0.0938 \\ -0.0625 \end{pmatrix}$$

$$= \begin{pmatrix} 1.91 \\ 0.313 \end{pmatrix}$$

Exp show the formula * page 76

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- Given the following nonlinear system

$$\begin{aligned} f(x, y) &= 0 \\ g(x, y) &= 0 \end{aligned} \quad \text{starting at } (x_0, y_0)$$

- The Taylor series expansions of f and g at (x_0, y_0) are

$$f(x, y) \approx f(x_0, y_0) + f_x^{(x_0, y_0)}(x - x_0) + f_y^{(x_0, y_0)}(y - y_0)$$

$$g(x, y) \approx g(x_0, y_0) + g_x^{(x_0, y_0)}(x - x_0) + g_y^{(x_0, y_0)}(y - y_0)$$

- But $f(x, y) = g(x, y) = 0 \Rightarrow$

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} f(x_0, y_0) \\ g(x_0, y_0) \end{pmatrix} + \begin{pmatrix} f_x & f_y \\ g_x & g_y \end{pmatrix} \begin{pmatrix} x - x_0 \\ y - y_0 \end{pmatrix}$$

- Multiply both sides by $J^{-1}(x_0, y_0) \Rightarrow$

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} = J^{-1} \begin{pmatrix} f(x_0, y_0) \\ g(x_0, y_0) \end{pmatrix} + \begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$$

- Rearrange the last equation \Rightarrow

$$\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} - J^{-1}(x_0, y_0) \begin{pmatrix} f(x_0, y_0) \\ g(x_0, y_0) \end{pmatrix}$$

2 Fixed Point Iteration (F.P.I)

80

- This method can be used to solve 2×2 or 3×3 nonlinear systems:

$$f_1(x, y) = 0$$

$$f_2(x, y) = 0$$

or

$$f_1(x, y, z) = 0$$

$$f_2(x, y, z) = 0$$

$$f_3(x, y, z) = 0$$

- For 2×2 system:

$$\rightarrow \text{write } x = g_1(x, y)$$

$$y = g_2(x, y)$$

(1)

$$\rightarrow \text{Given } (x_0, y_0) = (p_0, q_0)$$

\rightarrow The FPI is

$$p_{n+1} = g_1(p_n, q_n)$$

$$q_{n+1} = g_2(p_n, q_n)$$

$n = 0, 1, 2, \dots$

- For 3×3 system:

$$\rightarrow \text{write } x = g_1(x, y, z)$$

$$y = g_2(x, y, z)$$

$$z = g_3(x, y, z)$$

(2)

$$\rightarrow \text{Given } (x_0, y_0, z_0) = (p_0, q_0, r_0)$$

\rightarrow The FPI is

$$p_{n+1} = g_1(p_n, q_n, r_n)$$

$$q_{n+1} = g_2(p_n, q_n, r_n)$$

$$r_{n+1} = g_3(p_n, q_n, r_n)$$

Def • The point (p, q) is fixed point of the system (1) if

$$p = g_1(p, q) \quad \text{and}$$

$$q = g_2(p, q).$$

• The point (p, q, r) is fixed point of the system (2) if

$$p = g_1(p, q, r) \quad \text{and}$$

$$q = g_2(p, q, r) \quad \text{and}$$

$$r = g_3(p, q, r).$$

Exp Find the fixed points of the following system

81

$$\begin{aligned}x - \sin y &= 0 \\x^2 + \cos^2 y &= \frac{y}{\pi} + \frac{1}{2}\end{aligned}$$

$$\bullet \quad x = g_1(x, y) \Leftrightarrow x = \sin y$$

$$y = g_2(x, y) \Leftrightarrow y = \left(x^2 + \cos^2 y - \frac{1}{2}\right) \pi$$

$$\bullet \quad y = \left(\sin^2 y + \cos^2 y - \frac{1}{2}\right) \pi = \left(1 - \frac{1}{2}\right) \pi = \frac{\pi}{2}$$

$$x = \sin y = \sin \frac{\pi}{2} = 1$$

Hence, $(p, q) = (x, y) = \left(1, \frac{\pi}{2}\right)$ is fixed point

Exp* Consider the following nonlinear system:

$$x^2 + y^2 - x = 0$$

$$e^x + y^2 - y = 0$$

Use initial approximation $(p_0, q_0) = (0.5, 0.4)$ to find the next three approximation using the FPI. 3-digits

$$\bullet \quad x = g_1(x, y) = x^2 + y^2 \quad \Rightarrow \quad p_{n+1} = p_n^2 + q_n^2$$

$$y = g_2(x, y) = e^x + y^2 \quad \Rightarrow \quad q_{n+1} = e^{p_n} + q_n^2$$

$$\bullet \quad p_1 = g_1(p_0, q_0) = g_1(0.5, 0.4) = 0.25 + 0.16 = 0.41$$

$$q_1 = g_2(p_0, q_0) = g_2(0.5, 0.4) = 1.65 + 0.16 = 1.81$$

$$\bullet \quad p_2 = g_1(p_1, q_1) = g_1(0.41, 1.81) = 0.168 + 3.28 = 3.45$$

$$q_2 = g_2(p_1, q_1) = g_2(0.41, 1.81) = 1.51 + 3.28 = 4.79$$

$$\bullet P_3 = g_1(p_2, q_2) = g_1(3.45, 4.79) = 11.9 + 22.9 = 34.8$$

82

$$q_3 = g_2(p_2, q_2) = g_2(3.45, 4.79) = 31.5 + 22.9 = 54.4$$

• Note that the FPI here diverges (see [2] in Remark below).

Th* (Convergence of FPI - Two dimensions)

• Assume (p, q) is fixed point of $x = g_1(x, y)$ and $y = g_2(x, y)$.

• If (p_0, q_0) is sufficiently close to (p, q) and if

$$\left| \frac{\partial g_1}{\partial x}(p, q) \right| + \left| \frac{\partial g_1}{\partial y}(p, q) \right| < 1 \quad \text{and}$$

$$\left| \frac{\partial g_2}{\partial x}(p, q) \right| + \left| \frac{\partial g_2}{\partial y}(p, q) \right| < 1$$

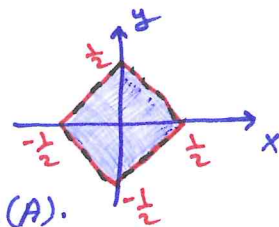
Then the FPI converges to the fixed point (p, q)

Remarks: [1] Convergence of FPI for three dimensions follows similarly to Th above by adding z-component.

[2] In Exp* page 81 \Rightarrow note that

$$(A) \quad \dots \quad \left| \frac{\partial g_1}{\partial x} \right| + \left| \frac{\partial g_1}{\partial y} \right| = 2|x| + 2|y| < 1 \Leftrightarrow |x| + |y| < \frac{1}{2}$$

$$(B) \quad \dots \quad \left| \frac{\partial g_2}{\partial x} \right| + \left| \frac{\partial g_2}{\partial y} \right| = e^x + 2|y| < 1$$



but $(p_0, q_0) = (0.5, 0.4)$ does not satisfy (A).

That is why the FPI in this Exp* diverges

from the fixed point.

Exercise [1] Find the fixed point in Exp*

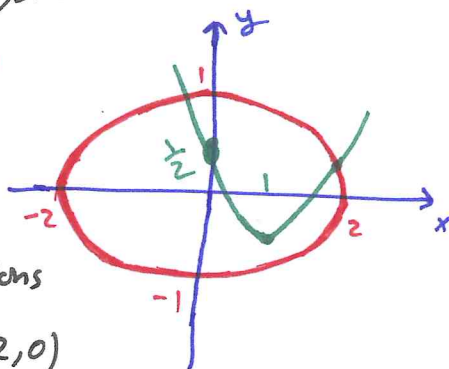
[2] Solve Exp* again using $(p_0, q_0) = (-0.45, 0.04)$ and show the FPI still diverges.

Exp Consider the following nonlinear system:

83

$$y = x^2 - 2x + 0.5 \quad \text{"parabola"}$$

$$x^2 + 4y^2 = 4 \quad \text{"Ellipse"}$$



Use the FPI to approximate the solutions using [1] $(p_0, q_0) = (0, 1)$ [2] $(p_0, q_0) = (2, 0)$

• The system is equivalent to

$$x = g_1(x, y) = \frac{x^2 - y + 0.5}{2}$$

* ...

$$y = g_2(x, y) = \frac{-x^2 - 4y^2 + 8y + 4}{8} \quad \text{add to each side } -8y$$

• This system has two solutions (or fixed points of *):

$$(p, q) \in \{ (-0.2, 1), (1.9, 0.3) \}$$

✓ To find the first solution $(p, q) = (-0.2, 1)$ we apply formula * as follows:

$$p_{n+1} = \frac{p_n^2 - q_n + 0.5}{2} = g_1(p_n, q_n)$$

$$q_{n+1} = \frac{-p_n^2 - 4q_n^2 + 8q_n + 4}{8} = g_2(p_n, q_n)$$

... (1)

$$\textcircled{1} (p_0, q_0) = (0, 1)$$

n	p_n	q_n
1	-0.25	1
2	-0.21875	0.9921875
3	-0.2221680	0.9939880
4	-0.2223147	0.9938121
5	-0.2221941	0.9938029
6	-0.2222163	0.9938095

This FPI converges to the first solution

$$\textcircled{2} (p_0, q_0) = (2, 0)$$

n	p_n	q_n
1	2.25	0
2	2.78125	-0.1328125
3	4.184082	-0.6085510
4	9.307547	-2.4820360
5	44.80623	-15.891091
6	1011.995	-392.60426

This FPI diverges

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- Note that Theorem* in page 82 can be used to show that iteration (1) converges to the fixed point near $(-0.2, 1)$:

$$\left| \frac{\partial g_1}{\partial x} \right| + \left| \frac{\partial g_1}{\partial y} \right| = |x| + 0.5 < 1 \Leftrightarrow |x| < 0.5$$

(2)

$$\left| \frac{\partial g_2}{\partial x} \right| + \left| \frac{\partial g_2}{\partial y} \right| = \frac{|x|}{4} + |1-y| < \frac{0.5}{4} + |1-y| < 1 \Leftrightarrow 0.125 < y < 1.875$$

- The fixed point $(p, q) = (-0.2, 1)$ satisfy (2) and so this implies that the FPI converges to $(p, q) = (-0.2, 1)$.
- However, the fixed point $(p, q) = (1.9, 0.3)$ does not satisfy (2):

$$\left| \frac{\partial g_1}{\partial x}(1.9, 0.3) \right| + \left| \frac{\partial g_1}{\partial y}(1.9, 0.3) \right| = 2.4 > 1$$

$$\left| \frac{\partial g_2}{\partial x}(1.9, 0.3) \right| + \left| \frac{\partial g_2}{\partial y}(1.9, 0.3) \right| = 1.16 > 1$$

so the FPI diverges from $(1.9, 0.3)$ if we use (1).

- Hence, the iteration (1) can not be used to find the second solution $(1.9, 0.3)$.

• To find this solution, we need a different formula for this iteration (1).

• If we add $-2x$ to the first equation and $-11y$ to the second equation, we get

$$x^2 - 4x - y + 0.5 = -2x$$

$$x^2 + 4y^2 - 11y - 4 = -11y$$

• The iteration now is

$$P_{n+1} = g_1(P_n, q_n) = \frac{-P_n^2 + 4P_n + q_n - 0.5}{2} \dots (2)$$

$$q_{n+1} = g_2(P_n, q_n) = \frac{-P_n^2 - 4q_n^2 + 11q_n + 4}{11}$$

• starting from same point $(p_0, q_0) = (2, 0) \Rightarrow$

n	P_n	q_n
1	1.75	0
2	1.71875	0.0852273
3	1.753063	0.1776676
4	1.808345	0.2504410
8	1.903595	0.3160782
12	1.900924	0.3112267
16	1.900652	0.3111994
20	1.900677	0.3112196

The FPI converges to the second solution using formula (2)

3 Seidel Iteration (Improvement of FPI)

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- This method can be used to solve 2×2 or 3×3 non linear systems:

$$f_1(x, y) = 0$$

$$f_2(x, y) = 0$$

or

$$f_1(x, y, z) = 0$$

$$f_2(x, y, z) = 0$$

$$f_3(x, y, z) = 0$$

- For 2×2 system:

$$\rightarrow \text{Write } x = g_1(x, y)$$

$$y = g_2(x, y)$$

$$\rightarrow \text{Given } (x_0, y_0) = (p_0, q_0)$$

\rightarrow The Seidel Iteration is

$$p_{n+1} = g_1(p_n, q_n)$$

$$q_{n+1} = g_2(p_{n+1}, q_n)$$

- For 3×3 system:

$$\rightarrow \text{Write } x = g_1(x, y, z)$$

$$y = g_2(x, y, z)$$

$$z = g_3(x, y, z)$$

$$\rightarrow \text{Given } (x_0, y_0, z_0) = (p_0, q_0, r_0)$$

\rightarrow The Seidel Iteration is

$$p_{n+1} = g_1(p_n, q_n, r_n)$$

$$q_{n+1} = g_2(p_{n+1}, q_n, r_n)$$

$$r_{n+1} = g_3(p_{n+1}, q_{n+1}, r_n)$$

Exp • Consider the following non linear system:

$$x = e^x + zy$$

$$y = xy - x^2z + 4$$

$$z = x^2 - yz$$

- Use Seidal iteration to find the next two approximations if the initial approximation of the solution is $(1, -1, 2)$.
- Use 4 - significant digits.

- $x = g_1(x, y, z) = e^x + zy$

$$y = g_2(x, y, z) = xy - x^2z + 4$$

$$z = g_3(x, y, z) = x^2 - yz$$

- $(x_0, y_0, z_0) = (p_0, q_0, r_0) = (1, -1, 2)$

- $p_1 = g_1(1, -1, 2) = e - 2 = 0.7180$

$$q_1 = g_2(0.7180, -1, 2) = -0.7180 - (0.5155)(2) + 4 = 2.251$$

$$r_1 = g_3(0.7180, 2.251, 2) = 0.5155 - 4.502 = -3.987$$

- $p_2 = g_1(p_1, q_1, r_1) = g_1(0.7180, 2.251, -3.987) = -6.925$

$$q_2 = g_2(-6.925, 2.251, -3.987) = -202.8$$

$$r_2 = g_3(-6.925, -202.8, -3.987) = -760.6$$
