

Birzeit University  
Mathematics Department  
Second Semester 2013/2014  
MATH 330 – Exam No. 1  
Instructor: Dr. Hani Kabajah

Name (بالعربية): Key Form 2 Student No.: \_\_\_\_\_

Sections: Put a tick in the last column

Section	Time		Your section
1	T, R	09:30 – 11:00	
2	S, M, W	09:00 – 10:00	
3	S, M, W	10:00 – 11:00	

Question 1 (20 points)

Circle the correct answer then fill the following table.

In the table write A, B, C, or D in the answer column.

Question	Answer
1	B
2	D
3	B
4	B
5	B
6	C
7	B
8	B
9	A
10	B

Question	Answer
11	C
12	C
13	A
14	B
15	C
16	C
17	C
18	D
19	B
20	C

- 1) Let  $f(x) = x^3 - 10x + 4$ , using Newton method and  $p_0 = -2$  then  $p_7$  equals
- a)  $-3.3496327$
  - b)  $-3.345969012$
  - c)  $-3.345963296$
  - d) None of the above.
- 2) Let  $f(x) = x^3 - 10x + 4$ , using bisection method on the interval  $[0, 3]$  then  $c_1$  equals
- a) 1.5
  - b) 2.25
  - c) 0.75
  - d) None of the above.
- 3) Let  $f(x) = x^3 - 10x + 4$ , using false position method on the interval  $[0, 2]$  then  $c_1$  equals
- a) 0.6667
  - b) 0.4186
  - c) 0.9148
  - d) 1.1111
- 4) Let  $f(x) = x^3 - 10x + 4$ , using secant method and  $p_0 = 0$  and  $p_1 = 1$  then  $p_2$  equals
- a) 0.6667
  - b) 0.4444
  - c) 1.5556
  - d) 0.9148
- 5) The interpolation polynomial of the following data points  $(0,0)$ ,  $(1,1)$ ,  $(2,3)$ ,  $(3,-1)$ ,  $(4,4)$  is of degree
- a) At least 4
  - b) At most 4
  - c) At most 5
  - d) At least 5

- 6) Polynomial Interpolation of the data points  $(x_0, y_0), (x_1, y_1), \dots, (x_n, y_n)$  means
- Finding a function  $f(x)$  such that  $f(x) = y$  for all  $x$
  - Finding a polynomial  $P_n(x)$  such that  $P_n(x) = y$  for all  $x$
  - Finding a polynomial  $P_n(x)$  such that  $P_n(x_k) = y_k$  for all  $x_k, k = 0, 1, \dots, n$
  - None of the above.
- 7) Using interpolation by polynomial of the following data points  $(0,0), (1,1), (2,3)$  the value of  $f(1.5)$  is best approximated by
- 2
  - 1.875
  - 2.25
  - 2.375
- 8) The function  $g(x) = \frac{4}{x^2} + 2$  has a fixed point in the interval  $[1,10]$ . Which statement is true?
- Using the Fixed Point Theorem we are sure that the function  $g(x)$  has a unique fixed point in the interval  $[1,10]$ .
  - Using the Fixed Point Theorem we cannot know if the function  $g(x)$  has a unique fixed point in the interval  $[1,10]$ .
  - Using the Fixed Point Theorem we are sure that the Fixed Point Iteration of the function  $g(x)$  converges for any  $p_0 \in [1,10]$ .
  - None of the above.
- 9) Let  $f(x) = (x - 1) \cdot \sin(\pi x)$ . If we use the secant method to find the root  $p = 1$  then the order of convergence will be
- $R = 1$
  - $R = \frac{1+\sqrt{5}}{2}$
  - $R = 2$
  - None of the above.
- 10) The system

$$\begin{aligned} y &= x^3 \\ x^2 + y^2 &= 1 \end{aligned}$$

- has one solution
- has two solutions
- has three solutions
- has four solutions

- 11) Using 7-digit rounding the value of  $f(x) = \ln(1 + x^2)$  at  $x = 10^{-4}$  is
- a)  $9.999999 \times 10^{-9}$
  - b) 1
  - c) 0
  - d)  $1 \times 10^{-8}$

12) Given the following two approximations

$$\begin{aligned}f(h) &= 1 + h^3 + O(h^5) \\g(h) &= h + h^2 + O(h^3)\end{aligned}$$

The value of  $f(0.1) + g(0.1)$  is best approximated by

- a) 1.1
  - b) 1.11
  - c) 1.111
  - d) None of the above
- 13) The function  $f(x) = \ln(1 + x^2) - 4$  has a root in the interval
- a)  $[7, 8]$
  - b)  $[-7, -6]$
  - c)  $[7, 8]$  and  $[-7, -6]$
  - d) None of the above

14) If we solve the following system using Gaussian elimination, partial pivoting, and 3-digit chopping

$$\begin{aligned}0.121x + 0.287y &= 0.399 \\1.12x + 2.87y &= 3.99\end{aligned}$$

The solution is

- a)  $(x, y) = (0.00892, 1.39)$
  - b)  $(x, y) = (-0.0178, 1.40)$
  - c)  $(x, y) = (-0.0178, 1.39)$
  - d)  $(x, y) = (0.00892, 1.38)$
- 15) To approximate  $\sin(2.01)$  with smallest error we shall use
- a)  $2.01 - \frac{(2.01)^3}{3!}$
  - b)  $2.01 - \frac{(2.01)^3}{3!} + \frac{(2.01)^5}{5!}$
  - c)  $2 - \frac{(2)^3}{3!} + \frac{(2)^5}{5!} - \frac{(2)^7}{7!}$
  - d) None of the above

16) A linear system  $AX = B$  is called ill-conditioned if

- a)  $\det(A) \approx 0$
- b) Large changes in  $A$  makes large changes in  $X$
- c) Small changes in  $A$  makes large changes in  $X$
- d) None of the above

17) To solve the system

$$\begin{aligned} x \sin(y) + y \sin(x) &= x \\ e^x - e^y &= y \end{aligned}$$

Using Seidel method and  $(p_0, q_0) = (1, 1)$  then

- a)  $(p_1, q_1) = (0.0349, -1.683)$
- b)  $(p_1, q_1) = (1.682, 4.376)$
- c)  $(p_1, q_1) = (1.682, 2.658)$
- d)  $(p_1, q_1) = (1.682, 0)$

18) Let  $A$  be a  $3 \times 3$  matrix. The cost calculating  $A^2$  then solving  $A^2X = B$  (using Gaussian Elimination and Back Substitution) is

- a) 63
- b) 72
- c) 42
- d) 73

19) Find the distance between the points  $(4, 2, 3)$  and  $(5, 3, 6)$  using  $L_4$  norm.

- a) 3.072
- b) 3.018
- c) 3.317
- d) 3

20) One of these is not a stopping criteria for solving  $x = g(x)$

- a)  $|p_{n+1} - p_n| < \delta$
- b)  $\frac{|p_{n+1} - p_n|}{|p_n|} < \delta$
- c)  $\frac{2|p_{n+1} - p_n|}{|p_{n+1}| + |p_n|} < \delta$
- d)  $\frac{2|p_{n+1} - p_n|}{|p_{n+1}| + |p_n|} < \delta$

Question 2 (5 points)

Given the system

$$\begin{aligned}x^2 + y^2 - 25 &= 0 \\x^2 - y - 3 &= 0\end{aligned}$$

Use Newton method and  $(p_0, q_0) = (3, 4)$  to calculate  $(p_1, q_1)$ .

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Q2

$$x^2 + y^2 - 25 = 0$$

$$x^2 - y - 3 = 0$$

$$(p_0, q_0) = (3, 4), \quad (p_1, q_1) = ?$$

$$\begin{pmatrix} p_1 \\ q_1 \end{pmatrix} = \begin{pmatrix} p_0 \\ q_0 \end{pmatrix} - \begin{pmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{pmatrix}^{-1} \begin{pmatrix} f_1(p_0, q_0) \\ f_2(p_0, q_0) \end{pmatrix}$$

$$\frac{\partial f_1}{\partial x} = 2x$$

$$\frac{\partial f_1}{\partial y} = 2y$$

$$\frac{\partial f_2}{\partial x} = 2x$$

$$\frac{\partial f_2}{\partial y} = -1$$

$$J(p_0, q_0) = \begin{pmatrix} 2p_0 & 2q_0 \\ 2p_0 & -1 \end{pmatrix} = \begin{pmatrix} 6 & 8 \\ 6 & -1 \end{pmatrix}$$

$$J^{-1}(p_0, q_0) = \begin{pmatrix} 6 & 8 \\ 6 & -1 \end{pmatrix}^{-1} = \frac{1}{-54} \begin{pmatrix} -1 & -8 \\ -6 & 6 \end{pmatrix}$$

$$\begin{pmatrix} p_1 \\ q_1 \end{pmatrix} = \begin{pmatrix} 3 \\ 4 \end{pmatrix} - \left( \frac{1}{-54} \begin{pmatrix} -1 & -8 \\ -6 & 6 \end{pmatrix} \right) \begin{pmatrix} f_1(3, 4) \\ f_2(3, 4) \end{pmatrix}$$

$$= \begin{pmatrix} 3 \\ 4 \end{pmatrix} + \frac{1}{54} \begin{pmatrix} -1 & -8 \\ -6 & 6 \end{pmatrix} \begin{pmatrix} 0 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} 3 \\ 4 \end{pmatrix} + \frac{1}{54} \begin{pmatrix} -16 \\ 12 \end{pmatrix} = \begin{pmatrix} 3 - 16/54 \\ 4 + 12/54 \end{pmatrix}$$

$$= \begin{pmatrix} 2 \frac{19}{27} \\ 4 \frac{2}{9} \end{pmatrix} = \begin{pmatrix} 2.704 \\ 4.222 \end{pmatrix}$$