

6.4

Differential Equations with Discontinuous Forcing Functions

In this section we study the solution of nonhomogeneous IVP in which the forcing function "g(t)" is discontinuous.

Example: Find the solution of the IVP

$$2y'' + y' + 2y = g(t), \quad y(0) = 0, \quad y'(0) = 0 \quad \text{---} \textcircled{D}$$

$$\text{where } g(t) = u_5(t) - u_{20}(t) = \begin{cases} 1, & 5 \leq t < 20 \\ 0, & 0 \leq t < 5 \text{ and } t > 20 \end{cases}$$

$$2L\{y''\} + L\{y'\} + 2L\{y\} = \{u_5(t)\} - L\{u_{20}(t)\}$$

$$2[s^2 L\{y\} - sy(0) - y'(0)] + sL\{y\} - y(0) + 2L\{y\} = \frac{-5s}{s} - \frac{-20s}{s}$$

$$(2s^2 + s + 2)L\{y\} = \frac{-5s}{s} - \frac{-20s}{s} \quad \text{"using the initial conditions"}$$

$$L\{y\} = \left(\frac{-5s}{s} - \frac{-20s}{s}\right) H(s), \quad \text{where } H(s) = \frac{1}{s(2s^2 + s + 2)}$$

If $h(t) = \mathcal{L}^{-1}(H(s))$, then the solution is

$$y(t) = \phi(t) = u_5(t) h(t-5) - u_{20}(t) h(t-20) \quad \text{by Th 6.3.1.}$$

$$h(t) = \mathcal{L}^{-1}\left(\frac{1}{s(2s^2 + s + 2)}\right)$$

see $\textcircled{*}$ on the back:

$$\frac{1}{s(2s^2 + s + 2)} = \frac{A}{s} + \frac{Bs + C}{2s^2 + s + 2}$$

$$= \mathcal{L}^{-1}\left(\frac{\frac{1}{2}}{s} - \frac{s + \frac{1}{2}}{2s^2 + s + 2}\right)$$

$$1 = (2A + B)s^2 + (A + C)s + 2A$$

$$A = \frac{1}{2}, \quad B = -1, \quad C = \frac{-1}{2}$$

$$= \frac{1}{2} \mathcal{L}^{-1}\left(\frac{1}{s}\right) - \frac{1}{2} \mathcal{L}^{-1}\left(\frac{s + \frac{1}{2}}{s^2 + \frac{5}{2}s + 1}\right)$$

$$= \frac{1}{2}(1) - \frac{1}{2} \mathcal{L}^{-1}\left(\frac{s + \frac{1}{4} + \frac{1}{4}}{(s + \frac{1}{4})^2 + \frac{15}{16}}\right)$$

④ Partial Fraction:

Factor in denominator (total)

$$ax+b$$

$$(ax+b)^k$$

$$ax^2 + bx + c$$

$$(ax^2 + bx + c)^k$$

Term in partial fraction decomposition

$$\frac{A}{ax+b}$$

$$\frac{A_1}{ax+b} + \frac{A_2}{(ax+b)^2} + \dots + \frac{A_k}{(ax+b)^k}$$

$$\frac{Ax + B}{ax^2 + bx + c}$$

$$\frac{A_1x + B_1}{ax^2 + bx + c} + \frac{A_2x + B_2}{(ax^2 + bx + c)^2} + \dots + \frac{A_kx + B_k}{(ax^2 + bx + c)^k}$$

$$h(t) = \frac{1}{2} - \frac{1}{2} L^{-1} \left(\frac{s + \frac{1}{4}}{(s + \frac{1}{4})^2 + \frac{15}{16}} \right) - \frac{1}{2\sqrt{15}} L^{-1} \left(\frac{\frac{\sqrt{15}}{4}}{(s + \frac{1}{4})^2 + \frac{15}{16}} \right)$$

$$h(t) = \frac{1}{2} - \frac{1}{2} e^{\frac{-t}{4}} \cos\left(\frac{\sqrt{15}}{4}t\right) - \frac{1}{2\sqrt{15}} e^{\frac{-t}{4}} \sin\left(\frac{\sqrt{15}}{4}t\right) \quad \text{②}$$

• Thus, the solution becomes $\phi(t) = u_5(t) h(t-5) - u_{20}(t) h(t-20)$ where $h(t)$ is given above.

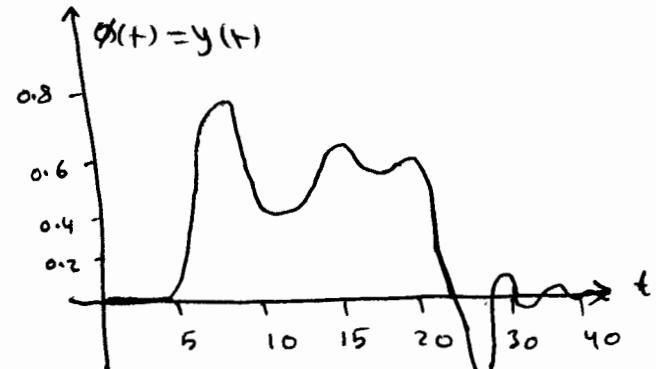
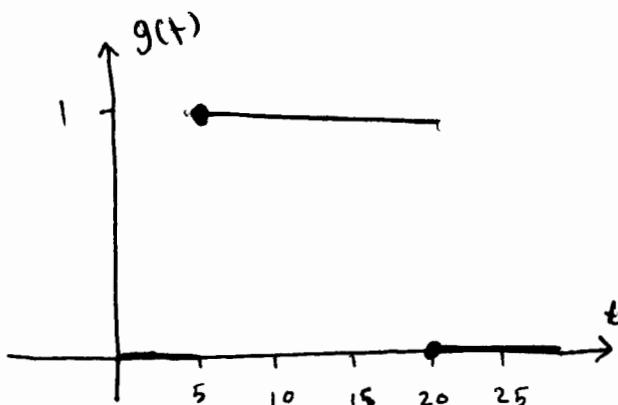
* Laplace transform methods provide a much more convenient approach to solve discontinuous forcing functions.

* The solution of the IVP ① can be seen as a composite of 3 separate solutions to 3 separate IVPs:

① $0 \leq t < 5 : 2y_1'' + y_1' + 2y_1 = 0, y_1(0) = 0, y_1'(0) = 0$

② $5 < t < 20 : 2y_2'' + y_2' + 2y_2 = 1, y_2(5) = 0, y_2'(5) = 0$

③ $t > 20 : 2y_3'' + y_3' + 2y_3 = 0, y_3(20) = 0.5, y_3'(20) = 0.01$



① $2r^2 + r + 2 = 0 \Leftrightarrow r_{1,2} = -\frac{1}{4} \pm \frac{\sqrt{15}}{4};$

$$\Leftrightarrow y_1(t) = c_1 e^{\frac{-t}{4}} \cos\left(\frac{\sqrt{15}}{4}t\right) + c_2 e^{\frac{-t}{4}} \sin\left(\frac{\sqrt{15}}{4}t\right)$$

Using $y_1(0) = 0 \Leftrightarrow c_1 = 0$ and $y_1'(0) = 0 \Leftrightarrow c_2 = 0$

Hence $y_1(t) = 0$. The system is initially at rest, and since there is no external forcing, it remains at rest.

$$y_2(5) = y_1(5) = 0$$

$$y_2'(5) = y_1'(5) = 0 \quad \text{since } y_1'(t) = 0$$

$$\boxed{2} \quad y_2(t) = y_h(t) + y_p(t) \quad \text{since } 2y'' + y' + 2y = 1 \quad y_2(5) = 0$$

$$y_p(t) = c_1 e^{-\frac{t}{4}} \cos\left(\frac{\sqrt{15}}{4}t\right) + c_2 e^{-\frac{t}{4}} \sin\left(\frac{\sqrt{15}}{4}t\right) + \frac{1}{2}$$

Physically, the system responds with the sum of a constant (the response to the constant forcing function) and a damped oscillation over the time interval $(5, 20)$.

$$\boxed{3} \quad y_3(t) = c_1 e^{-\frac{t}{4}} \cos\left(\frac{\sqrt{15}}{4}t\right) + c_2 e^{-\frac{t}{4}} \sin\left(\frac{\sqrt{15}}{4}t\right)$$

Physically, since there is no external forcing, the response is a damped oscillation about $y=0$ for $t > 20$.

What is the effect of discontinuity of the forcing function $g(t)$ on the solution $\phi = \phi(t)$?

- It can be shown that ϕ and ϕ' are continuous at $t=5$ and $t=20$.
But ϕ has a jump of $\frac{1}{2}$ at $t=5$ and
jump of $-\frac{1}{2}$ at $t=20$:

$$\lim_{t \rightarrow 5^-} \phi''(t) = 0 \quad \text{and} \quad \lim_{t \rightarrow 5^+} \phi''(t) = \frac{1}{2} \quad \lim_{t \rightarrow 20^-} \phi''(t) \approx 0 \quad \text{and} \quad \lim_{t \rightarrow 20^+} \phi''(t) \approx -\frac{1}{2}$$

- Thus, jump in the forcing term $g(t)$ at these points is balanced by a corresponding jump in the highest order term $2y''$ in the ODE.

* Smoothness of solution in General

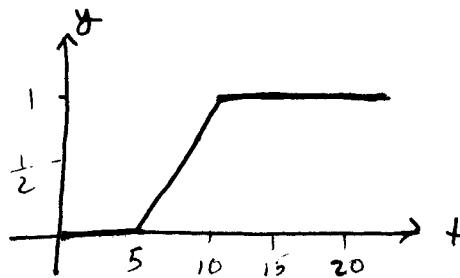
Consider a general 2nd order linear equation: $y'' + p(t)y' + q(t)y = g(t)$
where p and q are continuous on some interval (a, b) but
 g is only piecewise continuous there.

- If $y = \psi(t)$ is a solution, then ψ and ψ' are continuous on (a, b) but ψ'' has jump discontinuities at the same points as g .
- Similarly for higher order equations, where the highest derivative of the solution has jump discontinuities at the same points as the forcing function, but the solution itself and its lower derivatives are continuous over (a, b) .

Example: Solve the IVP $y'' + 4y = g(t)$, $y(0) = 0$, $y'(0) = 0$

where $g(t) = \frac{t-5}{5} u_5(t) - \frac{t-10}{5} u_{10}(t) = \begin{cases} 0 & , 0 \leq t < 5 \\ \frac{t-5}{5} & , 5 \leq t < 10 \\ 1 & , t \geq 10 \end{cases}$

The graph of the forcing function $g(t)$ is known as ramp loading (跳跃输入)



$$L\{y''\} + 4 L\{y\} = \frac{1}{5} L\{u_5(t)(t-5)\} - \frac{1}{5} L\{u_{10}(t)(t-10)\}$$

$$s^2 L\{y\} - s y(0) - y'(0) + 4 L\{y\} = \frac{1}{5} \frac{e^{-5s}}{s^2} - \frac{1}{5} \frac{e^{-10s}}{s^2}$$

$$(s^2 + 4) L\{y\} = \frac{-5s}{5s^2} - \frac{-10s}{5s^2} \quad \Leftrightarrow \quad L\{y\} = \frac{-5s}{5s^2 + 4} - \frac{-10s}{5s^2 + 4} \frac{1}{s^2(s^2 + 4)}$$

$$\Leftrightarrow L\{y\} = \frac{\frac{-5s}{5} - \frac{-10s}{5}}{s^2 + 4} H(s)$$

If $h(t) = \overset{-1}{L}\left(H(s)\right)$, then the solution is

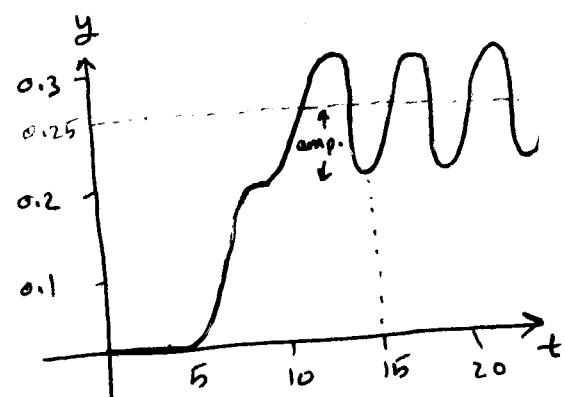
$$y(t) = \phi(t) = \frac{1}{5} [u_5(t) h(t-5) - u_{10}(t) h(t-10)] \text{ by Th 6.3.1.}$$

$$\begin{aligned} h(t) &= \overset{-1}{L}\left(\frac{1}{s^2(s^2+4)}\right) = \overset{-1}{L}\left(\frac{\frac{1}{s^2} - \frac{1}{4}}{s^2+4}\right) \quad \left| \begin{array}{l} \frac{1}{s^2(s^2+4)} = \frac{A}{s} + \frac{B}{s^2} + \frac{Cs+D}{s^2+4} \\ 1 = (A+C)s^3 + (B+D)s^2 + 4As + 4B \end{array} \right. \\ &= \frac{1}{4} \overset{-1}{L}\left(\frac{1}{s^2}\right) - \frac{1}{8} \overset{-1}{L}\left(\frac{2}{s^2+4}\right) \quad \left| \begin{array}{l} A=0, B=\frac{1}{4}, C=0, D=-\frac{1}{4} \end{array} \right. \end{aligned}$$

$$h(t) = \frac{t}{4} - \frac{\sin 2t}{8}$$

Thus, the solution to the IVP above is

$$\begin{cases} \phi(t) = \frac{1}{5} [u_5(t) h(t-5) - u_{10}(t) h(t-10)] \\ \text{where } h(t) = \frac{t}{4} - \frac{\sin(2t)}{8} \end{cases}$$



* The solution of the IVP above can be seen as a composite of 3 separate solutions to 3 separate IVPs:

$$\boxed{1} \quad 0 \leq t < 5: \quad y_1'' + 4y_1 = 0, \quad y_1(0) = 0, \quad y_1'(0) = 0$$

$$\boxed{2} \quad 5 < t < 10: \quad y_2'' + 4y_2 = \frac{t-5}{5}, \quad y_2(5) = 0, \quad y_2'(5) = 0$$

$$\boxed{3} \quad 10 < t: \quad y_3'' + 4y_3 = 1, \quad y_3(10) = y_2(10), \quad y_3'(10) = y_2'(10)$$

$$\boxed{1} \quad r^2 + 4 = 0 \Leftrightarrow r_{1,2} = \pm 2i \Leftrightarrow y_1(t) = c_1 \cos 2t + c_2 \sin 2t$$

$$y_1(0) = 0 \Rightarrow c_1 = 0, \quad y_1'(0) = 0 \Rightarrow c_2 = 0$$

$$\Leftrightarrow y_1(t) = 0$$

$$y_2(5) = y_1(5) = 0$$

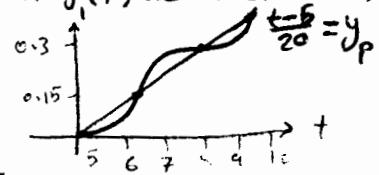
$$y_2'(5) = y_1'(5) = 0$$

The system is initially at rest, and since there is no external forcing, it remains at rest. Thus, the solution $y_1(t) = 0$ over $[0, 5]$.

$$\boxed{2} \quad y_2(t) = y_h(t) + y_p(t)$$

$$y_2(t) = c_1 \cos 2t + c_2 \sin 2t + \frac{t-5}{20} - \frac{1}{4}$$

The solution is an oscillation about the line $\frac{t-5}{20}$ over $(5, 10)$.



$$\boxed{3} \quad y_3(t) = y_h(t) + y_p(t)$$

$$y_3(t) = c_1 \cos 2t + c_2 \sin 2t + \frac{1}{4}$$

The solution is an oscillation

about $y = \frac{1}{4}$ for $t \geq 10$ (see the figure)

Recall the solution * • To find the amplitude of the oscillation part for $t > 10$, we locate one of the Max or Min points by solving $\dot{y} = \phi(t) = 0$.

Thus, the first max is $(10.642, 0.298)$.

Hence, the amplitude of the oscillation is 0.0479.

- Note that in this example the forcing function g is continuous but g' is discontinuous at $t = 5$ and $t = 10$.

- It follows that ϕ and its first two derivatives are continuous everywhere, but ϕ'' has discontinuities at $t = 5$ and $t = 10$ that match the discontinuities of g' at $t = 5$ and $t = 10$.