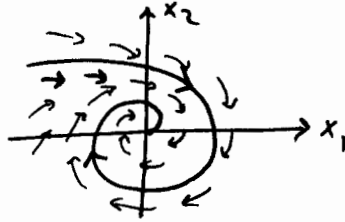


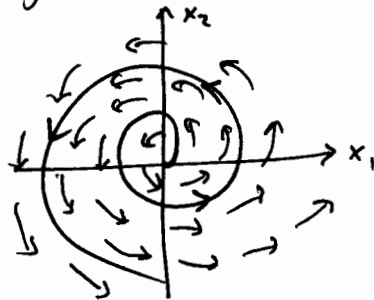
## 7.6 Complex Eigenvalues ( $r = \lambda \pm \mu i$ )

\* In case where the eigenvalues are complex for the system  $\vec{x}' = A\vec{x}$  then the origin is an spiral point. Moreover,

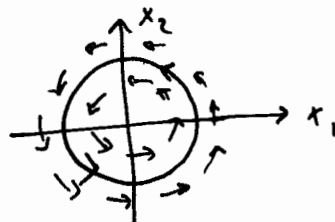
[a] if  $\lambda < 0$ , then the origin is asymptotically stable eq. point because all trajectories approach it as  $t$  increases.



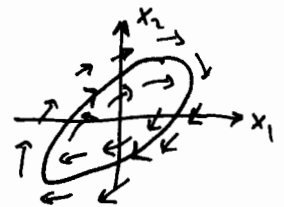
[b] If  $\lambda > 0$ , then the origin is unstable eq. point because the direction of motion is away from the origin and the trajectories become unbounded.



[c] If  $\lambda = 0$ , then the origin is stable <sup>eq. point</sup> but not asymptotically stable. In this case the origin is called a center, and the trajectories neither approach the origin nor become unbounded, but form a closed curve about the origin.



$$a_{12} < 0 \text{ and } a_{21} > 0$$



$$a_{12} > 0 \text{ and } a_{21} < 0$$

Example: Find the solution of the given system of equations in terms of real-valued functions and describe the behavior of the solution as  $t \rightarrow \infty$ . sketch a few trajectories and draw a direction field: ①  $\vec{x}' = \begin{pmatrix} 1 & -1 \\ 5 & -3 \end{pmatrix} \vec{x}$

Assume exponential solution  $\vec{x} = \vec{\xi} e^{rt}$ , and substitute it in the above system to solve the algebraic equation  $(A - rI) \vec{\xi} = \vec{0}$

$$\begin{pmatrix} 1-r & -1 \\ 5 & -3-r \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \text{This equation has a non trivial solution iff } \begin{vmatrix} 1-r & -1 \\ 5 & -3-r \end{vmatrix} = 0 \Leftrightarrow \text{The characteristic}$$

$$\text{equation is } (1-r)(-3-r) + 5 = 0 \Leftrightarrow r^2 + 2r + 2 = 0 \Leftrightarrow$$

$$r_{1,2} = -1 \pm i \quad \text{"}\lambda = -1\text{" and "}\mu = 1\text{"}. \quad r_1 = -1 - i \quad \text{and} \quad r_2 = -1 + i$$

- To find the eigenvector corresponding to the eigenvalue  $r_1 = -1 - i$ :

$$\begin{pmatrix} 2+i & -1 \\ 5 & -2+i \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad \begin{aligned} (2+i)\xi_1 - \xi_2 &= 0 \\ \xi_2 &= (2+i)\xi_1 \end{aligned}$$

$$\text{so the eigenvector is } \vec{\xi}^{(1)} = \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2+i \end{pmatrix}$$

- To find the eigenvector corresponding to the eigenvalue  $r_2 = -1 + i$

$$\begin{pmatrix} 2-i & -1 \\ 5 & -2-i \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad (2-i)\xi_1 - \xi_2 = 0 \Leftrightarrow \xi_2 = (2-i)\xi_1$$

$$\text{so the eigenvector is } \vec{\xi}^{(2)} = \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2-i \end{pmatrix}$$

- The corresponding solutions of the system above are

$$\vec{x}^{(1)}(t) = \vec{\xi}^{(1)} e^{r_1 t} = \begin{pmatrix} 1 \\ 2+i \end{pmatrix} e^{-(1+i)t} \quad \text{and} \quad \vec{x}^{(2)}(t) = \vec{\xi}^{(2)} e^{r_2 t} = \begin{pmatrix} 1 \\ 2-i \end{pmatrix} e^{(-1+i)t}$$

- To find a real-valued solutions, we find the real and imaginary parts of either  $\vec{x}^{(1)}(t)$  or  $\vec{x}^{(2)}(t)$ :

$$\vec{x}^{(1)}(t) = \begin{pmatrix} 1 \\ 2+i \end{pmatrix} e^{-t} e^{-it} = \begin{pmatrix} 1 \\ 2+i \end{pmatrix} e^{-t} (\cos t - i \sin t)$$

$$\begin{aligned} \vec{x}^{(1)}(t) &= \begin{pmatrix} e^{-t} \cos t & -i e^{-t} \sin t \\ 2e^{-t} \cos t + e^{-t} \sin t + i(e^{-t} \cos t - 2e^{-t} \sin t) \end{pmatrix} \\ &= e^{-t} \begin{pmatrix} \cos t \\ 2 \cos t + \sin t \end{pmatrix} + i e^{-t} \begin{pmatrix} -\sin t \\ \cos t - 2 \sin t \end{pmatrix} \end{aligned}$$

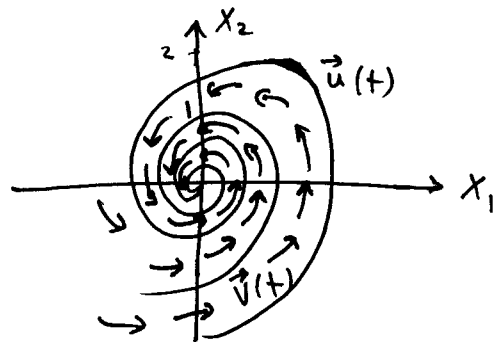
- Hence,  $\vec{u}(t) = e^{-t} \begin{pmatrix} \cos t \\ 2 \cos t + \sin t \end{pmatrix}$  and  $\vec{v}(t) = e^{-t} \begin{pmatrix} -\sin t \\ \cos t - 2 \sin t \end{pmatrix}$  are real-valued solutions.

Thus, the general solution is

$$\vec{x}(t) = c_1 \vec{u}(t) + c_2 \vec{v}(t) = c_1 e^{-t} \begin{pmatrix} \cos t \\ 2 \cos t + \sin t \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} -\sin t \\ \cos t - 2 \sin t \end{pmatrix}$$

- Since the eigenvalues are complex with negative real part " $\lambda < 0$ ", it follows that the origin is spiral eq. point that is asymptotically stable and all trajectories approach it as  $t$  increases.

$$\vec{u}(0) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad \vec{v}(0) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$



- Note that  $W(\vec{u}(t), \vec{v}(t))(t) =$

$$\begin{vmatrix} e^{-t} \cos t & -e^{-t} \sin t \\ e^{-t} (2 \cos t + \sin t) & e^{-t} (\cos t - 2 \sin t) \end{vmatrix} = e^{-2t} \neq 0$$

Thus,  $\vec{u}$  and  $\vec{v}$  are linearly independent and so they form a fundamental set of solutions.

$$\boxed{2} \quad \vec{x}' = \begin{pmatrix} 2 & -5 \\ 1 & -2 \end{pmatrix} \vec{x}$$

$\vec{x} = \vec{0}$  is eq. point or eq. solution

Assume exponential solution  $\vec{x}(t) = \vec{\xi} e^{rt}$ , and substitute it above to solve the algebraic equation  $(A - rI)\vec{\xi} = \vec{0}$

$$\begin{pmatrix} 2-r & -5 \\ 1 & -2-r \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \text{This equation has a non trivial solution iff } \begin{vmatrix} 2-r & -5 \\ 1 & -2-r \end{vmatrix} = 0 \Leftrightarrow \text{The characteristic}$$

equation is  $r^2 + 1 = 0 \Leftrightarrow r_{1,2} = \pm i$  " $\lambda = 0$  and  $M = 1$ ".  $r_1 = i$  and  $r_2 = -i$

• To find the eigenvector corresponding to the eigenvalue  $r_1 = i$ :

$$\begin{pmatrix} 2-i & -5 \\ 1 & -2-i \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad \xi_1 - (2+i)\xi_2 = 0 \Leftrightarrow \xi_1 = (2+i)\xi_2$$

so the eigenvector  $\vec{\xi}^{(1)} = \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 2+i \\ 1 \end{pmatrix}$

• To find the eigenvector corresponding to the eigenvalue  $r_2 = -i$

$$\begin{pmatrix} 2+i & -5 \\ 1 & -2+i \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad \xi_1 + (2+i)\xi_2 = 0 \Leftrightarrow \xi_1 = -(2+i)\xi_2$$

so the eigenvector  $\vec{\xi}^{(2)} = \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 2-i \\ 1 \end{pmatrix}$

• The corresponding solutions of the system above are

$$\vec{x}^{(1)}(t) = \vec{\xi}^{(1)} e^{r_1 t} = \begin{pmatrix} 2+i \\ 1 \end{pmatrix} e^{it} \quad \text{and} \quad \vec{x}^{(2)}(t) = \vec{\xi}^{(2)} e^{r_2 t} = \begin{pmatrix} 2-i \\ 1 \end{pmatrix} e^{-it}$$

• To find a real-valued solutions, we find the real and imaginary parts of either  $\vec{x}^{(1)}(t)$  or  $\vec{x}^{(2)}(t)$ :

$$\begin{aligned} \vec{x}^{(1)}(t) &= \begin{pmatrix} 2+i \\ 1 \end{pmatrix} e^{it} = \begin{pmatrix} 2+i \\ 1 \end{pmatrix} (\cos t + i \sin t) = \begin{pmatrix} 2 \cos t - \sin t + i(\cos t + 2 \sin t) \\ \cos t + i \sin t \end{pmatrix} \\ &= \begin{pmatrix} 2 \cos t - \sin t \\ \cos t \end{pmatrix} + i \begin{pmatrix} \cos t + 2 \sin t \\ \sin t \end{pmatrix} \end{aligned}$$

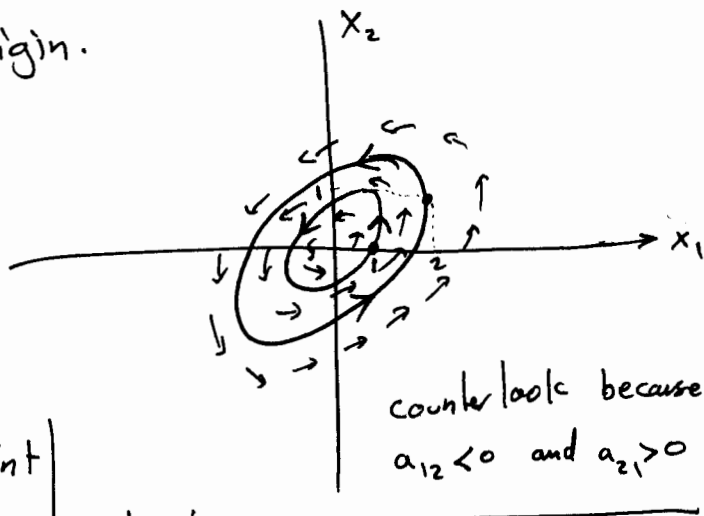
• Hence,  $\vec{u}(t) = \begin{pmatrix} 2 \cos t - \sin t \\ \cos t \end{pmatrix}$  and  $\vec{v}(t) = \begin{pmatrix} \cos t + 2 \sin t \\ \sin t \end{pmatrix}$  are real-valued solutions.

• Thus, the general solution is

$$\vec{x}(t) = c_1 \vec{u}(t) + c_2 \vec{v}(t) = c_1 \begin{pmatrix} 2 \cos t - \sin t \\ \cos t \end{pmatrix} + c_2 \begin{pmatrix} \cos t + 2 \sin t \\ \sin t \end{pmatrix}$$

• Since the eigenvalues are complex with no real part " $\lambda=0$ ", it follows that the origin is spiral eq. point that is stable but not asymptotically stable and called a center. The trajectories neither approach the origin nor become unbounded, but form a closed curve about the origin.

$$\vec{u}(0) = \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \quad \vec{v}(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$



• Note that  $w(\vec{u}(t), \vec{v}(t))(t) =$

$$\begin{vmatrix} 2 \cos t - \sin t & \cos t + 2 \sin t \\ \cos t & \sin t \end{vmatrix} = -1 \neq 0$$

Thus,  $\vec{u}$  and  $\vec{v}$  are linearly independent and so they form a fundamental set of solutions.

Example: Consider the system  $\vec{x}' = \begin{pmatrix} 0 & -5 \\ 1 & \alpha \end{pmatrix} \vec{x}$ .

Describe how the solutions depend qualitatively on  $\alpha$ .  
Find the critical values of  $\alpha$  at which the qualitative behavior of the trajectories in the phase plane changes markedly "portrait".

Assume exponential solution  $\vec{x}(t) = \vec{\xi} e^{rt}$ , and substitute it above to solve the algebraic equation  $(A - rI)\vec{\xi} = \vec{0}$

$$\begin{pmatrix} -r & -5 \\ 1 & \alpha - r \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \text{This equation has a non trivial solution iff } \begin{vmatrix} -r & -5 \\ 1 & \alpha - r \end{vmatrix} = 0 \Leftrightarrow \text{the characteristic equation is } r^2 - \alpha r + 5 = 0 \Leftrightarrow r_{1,2} = \frac{\alpha}{2} \pm \frac{1}{2} \sqrt{\alpha^2 - 20}$$

- The roots are complex when  $-\sqrt{20} < \alpha < \sqrt{20}$ , and real otherwise. Hence  $\alpha = \pm \sqrt{20}$  are critical values where the eigenvalues changes from real "nodes" to complex "spirals", or vice versa.
- If  $\alpha < -\sqrt{20}$ , then both eigenvalues are real and negative, so all trajectories approach the origin which is a asymptotically stable node.
- If  $\alpha > \sqrt{20}$ , then both eigenvalues are real and positive, so the origin is unstable node. All trajectories become unbounded (except  $\vec{x} = \vec{0}$ ).
- If  $\alpha \in (-\sqrt{20}, \sqrt{20})$ , then the eigenvalues are complex and the trajectories are spirals.
  - $\Rightarrow$  If  $\alpha \in (-\sqrt{20}, 0)$ , then the real part of the eigenvalue is negative, so the spirals are directed inward, and the origin is asymptotically stable.
  - $\Rightarrow$  If  $\alpha \in (0, \sqrt{20})$ , then the real part of the eigenvalue is positive, so the spirals are directed outward, and the origin is unstable.

$\Rightarrow \alpha=0$  is also a critical value since the direction of the spirals changes from inward to outward. The origin is a center and the trajectories are closed curves about the origin.

$$\boxed{3} \quad \vec{x}' = \begin{pmatrix} 2 & -\frac{5}{2} \\ \frac{9}{5} & -1 \end{pmatrix} \vec{x} \quad \dots$$

The characteristic equation is  $r^2 - r + \frac{5}{2} = 0 \Leftrightarrow r_{1,2} = \frac{1}{2} \pm \frac{3}{2}i$

- $r_1 = \frac{1}{2} + \frac{3}{2}i$  is an eigen value with eigenvector  $\vec{v}^{(1)} = \begin{pmatrix} 5 \\ 3-3i \end{pmatrix}$
- $r_2 = \frac{1}{2} - \frac{3}{2}i$  = = = = = =  $\vec{v}^{(2)} = \begin{pmatrix} 5 \\ 3+3i \end{pmatrix}$
- $\vec{x}^{(1)}(t) = \vec{v}^{(1)} e^{r_1 t} = \begin{pmatrix} 5 \\ 3-3i \end{pmatrix} e^{(\frac{1}{2} + \frac{3}{2}i)t} = e^{\frac{t}{2}} \begin{pmatrix} 2 \cos \frac{3}{2}t - \sin \frac{3}{2}t \\ \cos \frac{3}{2}t \end{pmatrix} + i e^{\frac{t}{2}} \begin{pmatrix} \cos \frac{3}{2}t + 2 \sin \frac{3}{2}t \\ \sin \frac{3}{2}t \end{pmatrix}$

• The general solution is

$$\vec{x}(t) = c_1 e^{\frac{t}{2}} \begin{pmatrix} 2 \cos \frac{3}{2}t - \sin \frac{3}{2}t \\ \cos \frac{3}{2}t \end{pmatrix} + c_2 e^{\frac{t}{2}} \begin{pmatrix} \cos \frac{3}{2}t + 2 \sin \frac{3}{2}t \\ \sin \frac{3}{2}t \end{pmatrix}$$

The origin is spiral eq. point that is unstable and the trajectories become unbounded.

