

## 7.8 Repeated Eigenvalues

Consider the linear homogeneous system with constant coefficients

$$\vec{x}' = A\vec{x}$$

which has a repeated eigenvalue  $\rho$  with corresponding eigenvector  $\vec{\xi}$

such that  $(A - \rho I)\vec{\xi} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

• Then one solution is  $\vec{x}^{(1)} = \vec{\xi} e^{\rho t}$

• The second solution is

$$\vec{x}^{(2)} = \vec{\xi} t e^{\rho t} + \vec{\eta} e^{\rho t} \quad \text{where}$$

$\vec{\eta}$  is called a generalized eigenvector corresponding to the eigenvalue  $\rho$  and satisfies

$$(A - \rho I)\vec{\eta} = \vec{\xi}$$

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Example: Find the general solution of the IVP "system"

$$x_1' = x_1 - 4x_2, \quad x_1(0) = 3, \quad x_2(0) = 2$$

$$x_2' = 4x_1 - 7x_2$$

$$\vec{x}' = \begin{pmatrix} 1 & -4 \\ 4 & -7 \end{pmatrix} \vec{x}, \quad \vec{x}(0) = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$$

Assume exponential solution  $\vec{x}(t) = \vec{\xi} e^{rt}$ , and substitute it above to solve the algebraic equation  $(A - rI)\vec{\xi} = \vec{0}$

$$\begin{pmatrix} 1-r & -4 \\ 4 & -7-r \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \text{This equation has a non trivial solution iff } \begin{vmatrix} 1-r & -4 \\ 4 & -7-r \end{vmatrix} = 0 \Leftrightarrow$$

The characteristic equation is  $r^2 + 6r + 9 = 0 \Leftrightarrow r_1 = r_2 = \rho = -3$

• To find the eigenvector corresponding to the single eigenvalue  $\rho = -3$ :

$$\begin{pmatrix} 4 & -4 \\ 4 & -4 \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad 4\xi_1 - 4\xi_2 = 0 \Leftrightarrow \xi_1 = \xi_2$$

so only eigenvector is  $\vec{\xi} = \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

• One solution is  $\vec{X}^{(1)}(t) = \vec{\xi} e^{pt} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-3t}$ .

• In order to generate a second linearly independent solution, we must look for a generalized eigenvector.

This leads to the system of equations  $(A - pI)\vec{\eta} = \vec{\xi}$

$$\begin{pmatrix} 1+3 & -4 \\ 4 & -7+3 \end{pmatrix} \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Leftrightarrow \begin{pmatrix} 4 & -4 \\ 4 & -4 \end{pmatrix} \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$4\eta_1 - 4\eta_2 = 1 \Leftrightarrow 4\eta_1 = 4\eta_2 + 1 \Leftrightarrow \eta_1 = \eta_2 + \frac{1}{4}$$

Setting  $\eta_2 = k$ , where  $k$  is arbitrary constant,

we obtain  $\eta_1 = k + \frac{1}{4}$ . Hence,

$$\vec{\eta} = \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix} = \begin{pmatrix} k + \frac{1}{4} \\ k \end{pmatrix} = \begin{pmatrix} \frac{1}{4} \\ 0 \end{pmatrix} + k \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

• A second solution is

$$\begin{aligned} \vec{X}^{(2)}(t) &= \vec{\xi} t e^{pt} + \vec{\eta} e^{pt} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} t e^{-3t} + \begin{pmatrix} \frac{1}{4} \\ 0 \end{pmatrix} e^{-3t} + k \underline{\underline{\begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-3t}}} \\ &= \begin{pmatrix} 1 \\ 1 \end{pmatrix} t e^{-3t} + \begin{pmatrix} \frac{1}{4} \\ 0 \end{pmatrix} e^{-3t} \end{aligned}$$

we ignore this term since it is a multiple of the first solution.

- The general solution is

$$\vec{X}(t) = c_1 \vec{X}^{(1)}(t) + c_2 \vec{X}^{(2)}(t) = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-3t} + c_2 \left[ \begin{pmatrix} 1 \\ 1 \end{pmatrix} t e^{-3t} + \begin{pmatrix} \frac{1}{4} \\ 0 \end{pmatrix} e^{-3t} \right]$$

- Note that  $w(\vec{X}^{(1)}(t), \vec{X}^{(2)}(t)) = \begin{vmatrix} e^{-3t} & t e^{-3t} + \frac{1}{4} e^{-3t} \\ e^{-3t} & t e^{-3t} \end{vmatrix} = -\frac{1}{4} e^{-6t} \neq 0$

Thus,  $\vec{X}^{(1)}(t)$  and  $\vec{X}^{(2)}(t)$  are linearly independent and so form a fundamental set of solutions.

- To find  $c_1$  and  $c_2$ , we impose the initial conditions:

$$\vec{X}(0) = c_1 + \frac{1}{4} c_2 = \begin{pmatrix} 3 \\ 2 \end{pmatrix}, \quad c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} \frac{1}{4} \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$$

$$\boxed{c_1 = 2}, \quad \boxed{c_2 = 4}$$

- Therefore, the general solution is:

$$\vec{X}(t) = 2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-3t} + 4 \begin{pmatrix} 1 \\ 1 \end{pmatrix} t e^{-3t} + 4 \begin{pmatrix} \frac{1}{4} \\ 0 \end{pmatrix} e^{-3t}$$

$$= \begin{pmatrix} 3 \\ 2 \end{pmatrix} e^{-3t} + \begin{pmatrix} 4 \\ 4 \end{pmatrix} t e^{-3t}$$

- Note that the solution approaches origin as  $t \rightarrow \infty$ .  
and the solution becomes unbounded as  $t \rightarrow -\infty$ .

- The origin is called an improper node and it is asymptotically stable "since  $p < 0$ "