

3.2 Solutions for linear DE's of order 2 (Wronskian, Fundamental Solutions, Abel's Theorem)

Th 3.2.1 (Existence and Uniqueness)

Consider the IVP:

$$\ddot{y} + p(t) \dot{y} + q(t) y = g(t), \quad y(t_0) = y_0, \quad \dot{y}(t_0) = \dot{y}_0 \quad (1)$$

If $p(t), q(t), g(t)$ are cont. on an open interval I containing t_0 , then \exists a unique solution $y = \phi(t)$ satisfying the IVP (1) on I .

Ex Find the largest interval in which the solution of the following IVP's is valid (defined):

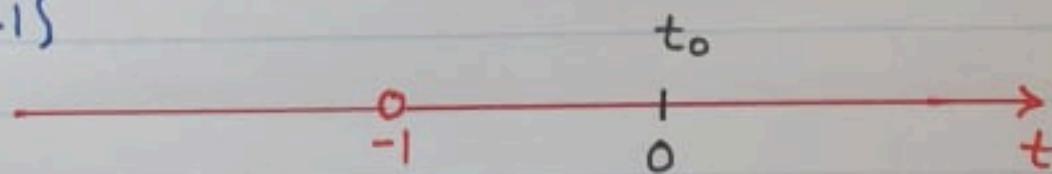
A) $(t+1)\ddot{y} - (\cos t)\dot{y} = 1 - 3y, \quad y(0) = 1, \quad \dot{y}(0) = 0$

Compare this IVP with (1) \Rightarrow

$$\ddot{y} - \left(\frac{\cos t}{t+1}\right)\dot{y} + \left(\frac{3}{t+1}\right)y = \frac{1}{t+1}$$

$$p(t) = -\frac{\cos t}{t+1}, \quad q(t) = \frac{3}{t+1}, \quad g(t) = \frac{1}{t+1}$$

All cont. on $\mathbb{R} \setminus \{-1\}$



$$I = (-1, \infty)$$

75

$$\textcircled{B} \quad (t^2 - 4) \ddot{y} + (\sin t) \dot{y} + \ln|t| y = t, \quad y(-1) = 0, \quad \dot{y}(-1) = 0$$

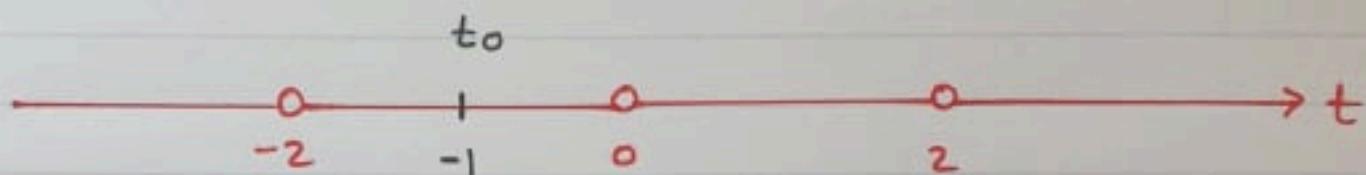
Compare this IVP with ① \Rightarrow

$$\ddot{y} + \left(\frac{\sin t}{t^2 - 4} \right) \dot{y} + \left(\frac{\ln|t|}{t^2 - 4} \right) y = \frac{t}{t^2 - 4}$$

$p(t)$ $q(t)$ $g(t)$

All cont. on $\mathbb{R} \setminus \{-2, 0, 2\}$

$$I = (-2, 0)$$



$$\textcircled{C} \quad \sqrt{2t+6} \ddot{y} + \dot{y} = \ln(2-t), \quad y(1) = 4, \quad \dot{y}(1) = 2$$

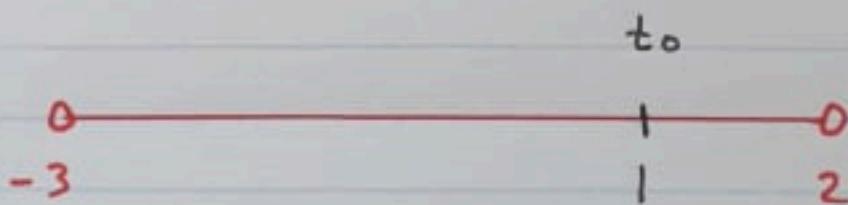
Compare this IVP with ① \Rightarrow

$$\ddot{y} + \frac{1}{\sqrt{2t+6}} \dot{y} = \frac{\ln(2-t)}{\sqrt{2t+6}}$$

$$2t+6 > 0$$

$$2t > -6$$

$$t > -3$$



$$2-t > 0$$

$$2 > t$$

$$I = (-3, 2)$$

Expt Consider the IVP : $\ddot{y} + p(t)\dot{y} + q(t)y = 0$, $y(t_0) = 0$
 where $p(t)$, $q(t)$ are cont. $\dot{y}(t_0) = 0$
 on an open interval I contains t_0 .
 Find the solution of this IVP. Is it unique?

- $g(t) = 0$ which is cont. on $\mathbb{R} \Rightarrow$ it's also cont. on I
- Conditions of Th3.2.1 hold $\Rightarrow \exists$ unique sol.
- The unique sol. must satisfy the DE and the IC's:

$y(t) = 0$ is the unique solution

Th3.2.2 (Principle of Superposition)

Suppose y_1 and y_2 are solutions for the DE :

$\ddot{y} + p(t)\dot{y} + q(t)y = 0$. Then the linear combination

$c_1 y_1 + c_2 y_2$ is also solution for any constants c_1 and c_2 .

Proof

$$\begin{aligned} (c_1 y_1 + c_2 y_2)'' + p(t)(c_1 y_1 + c_2 y_2)' + q(t)(c_1 y_1 + c_2 y_2) &= \\ c_1 \ddot{y}_1 + c_2 \ddot{y}_2 + p(t)(c_1 \dot{y}_1 + c_2 \dot{y}_2) + q(t)(c_1 y_1 + c_2 y_2) &= \\ c_1 (\underbrace{\ddot{y}_1 + p(t)\dot{y}_1 + q(t)y_1}_{\text{zero since } y_1 \text{ sol.}}) + c_2 (\underbrace{\ddot{y}_2 + p(t)\dot{y}_2 + q(t)y_2}_{\text{zero since } y_2 \text{ sol.}}) &= \end{aligned}$$

$$c_1(0) + c_2(0) = 0 \Rightarrow c_1 y_1 + c_2 y_2 \text{ is sol.}$$

Remark The linear combination $c_1 y_1 + c_2 y_2$ is called the general solution and we write $y(t) = c_1 y_1(t) + c_2 y_2(t)$

If the DE is supported by two IC's :

$$y(t_0) = y_0 \quad \text{and} \quad y'(t_0) = y'_0 \quad \text{then we can}$$

find the constants c_1 and c_2 in the general solution:

$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$

$$y'(t) = c_1 y'_1(t) + c_2 y'_2(t)$$

$$\begin{aligned} y(t_0) &= c_1 y_1(t_0) + c_2 y_2(t_0) = y_0 \quad \dots \textcircled{1} \\ y'(t_0) &= c_1 y'_1(t_0) + c_2 y'_2(t_0) = y'_0 \quad \dots \textcircled{2} \end{aligned}$$

We use Cramer's Rule to solve $\textcircled{1}$ and $\textcircled{2}$ for c_1 and c_2 :

$$c_1 = \frac{\begin{vmatrix} y_0 & y(t_0) \\ y'_0 & y'(t_0) \end{vmatrix}}{\begin{vmatrix} y_1(t_0) & y_1(t_0) \\ y'_1(t_0) & y'_1(t_0) \end{vmatrix}} = \frac{y_0 y'_2(t_0) - y_2(t_0) y'_0}{y'_1(t_0) y_2(t_0) - y_2(t_0) y'_1(t_0)} \quad \dots *^1$$

$$c_2 = \frac{\begin{vmatrix} y_1(t_0) & y_0 \\ y'_1(t_0) & y'_0 \end{vmatrix}}{\begin{vmatrix} y_1(t_0) & y_1(t_0) \\ y'_1(t_0) & y'_1(t_0) \end{vmatrix}} = \frac{y_1(t_0) y'_0 - y_0 y'_1(t_0)}{y'_1(t_0) y_2(t_0) - y_2(t_0) y'_1(t_0)} \quad \dots *^2$$

For c_1 and c_2 to be well defined, we must have
 $w(y_1, y_2)(t_0) = y_1(t_0) y'_2(t_0) - y_2(t_0) y'_1(t_0) \neq 0$

Def If y_1 and y_2 are solutions to the DE

$$y'' + p(t)y' + q(t)y = 0 \quad (2)$$

then the Wronskian of y_1 and y_2 is defined by

$$W(y_1, y_2)(t) = \begin{vmatrix} y_1(t) & y_2(t) \\ y'_1(t) & y'_2(t) \end{vmatrix} = y_1(t)y'_2(t) - y_2(t)y'_1(t) \quad t \in I.$$

Th 3.2.3 Assume y_1 and y_2 are solutions of (2).

Then $\exists c_1$ and c_2 s.t. $c_1 y_1 + c_2 y_2$ satisfies (2)
iff $W(y_1, y_2)(t_0) \neq 0$, $t_0 \in I$.

Proof \Rightarrow If $\exists c_1$ and c_2 s.t. $c_1 y_1 + c_2 y_2$ satisfies (2)
then c_1 and c_2 defined by $*^1$ and $*^2$
are well-defined
 $\Rightarrow W(y_1, y_2)(t_0) \neq 0$

\Leftarrow Assume y_1 and y_2 are solution of (2) \Rightarrow
by Th 3.2.2 $c_1 y_1 + c_2 y_2$ is also solution.

Since $W(y_1, y_2)(t_0) \neq 0$, $t_0 \in I \Rightarrow$ we can
find c_1 and c_2 using Cramer's Rule $*^1$ and $*^2$

Def. y_1, y_2, \dots, y_n are Linearly Dependent if \exists

c_1, c_2, \dots, c_n not all zeros s.t

$$c_1 y_1 + c_2 y_2 + \dots + c_n y_n = 0$$

• y_1, y_2, \dots, y_n are Linearly Independent if

whenever $c_1 y_1 + c_2 y_2 + \dots + c_n y_n = 0$ implies that

$$c_1 = c_2 = \dots = c_n = 0$$

Remark • If $w(y_1, y_2)(t) \neq 0$, then
 y_1 and y_2 are linearly independent

That is:

• If y_1 and y_2 are linearly dependent, then
 $w(y_1, y_2)(t) = 0$

Exp $y_1 = e^t$ and $y_2 = -e^{-t}$ are Linearly Independent

since $w(e^t, -e^{-t})(t) = \begin{vmatrix} e^t & -e^{-t} \\ t & -e^{-t} \end{vmatrix} = -1 - 1 = -2 \neq 0$

Or $c_1 y_1 + c_2 y_2 = 0 \Rightarrow c_1 e^t + c_2 -e^{-t} = 0$

$t=0 \Rightarrow c_1 + c_2 = 0 \quad \left. \begin{array}{l} c_1 = c_2 = 0 \\ t=\ln 2 \Rightarrow 2c_1 + \frac{1}{2}c_2 = 0 \end{array} \right\} \Rightarrow$

Exp $y_1 = \sin 2x$ and $y_2 = \sin x \cos x$ are L. dependent

$$c_1 y_1 + c_2 y_2 = 0 \Rightarrow c_1 \sin 2x + c_2 \sin x \cos x = 0 \Rightarrow c_1 = 1$$

$$c_2 = -2$$