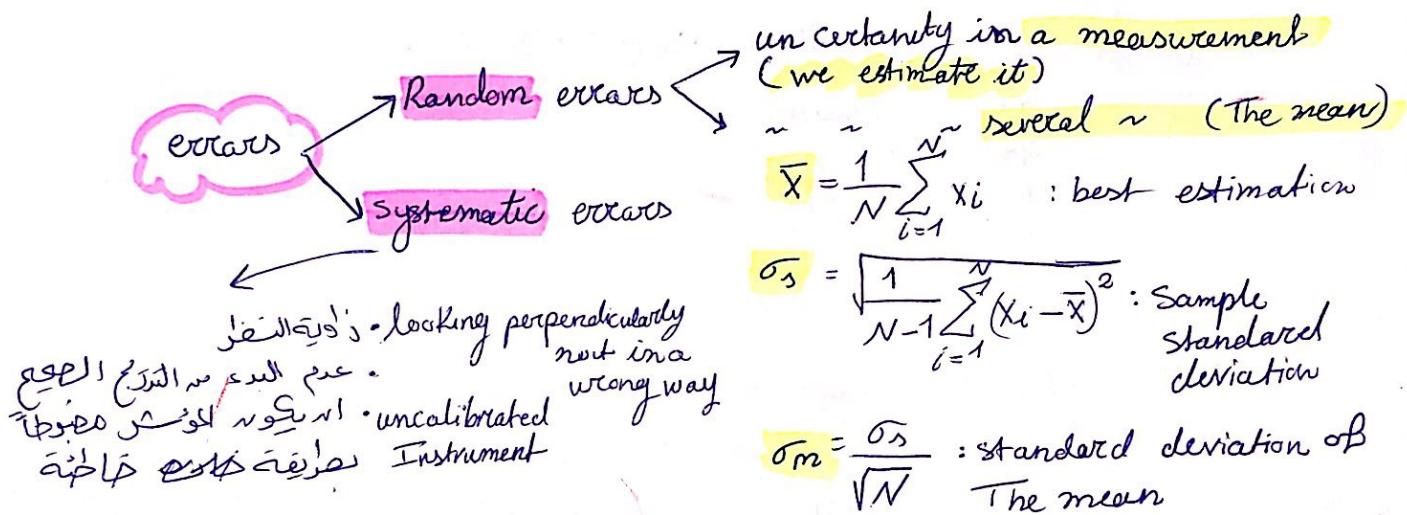


Measurements and Uncertainties

Sources of errors:-

- 1- Choice of instruments
- 2- The Experimenter
- 3- The Environment
- 4- The way The experiment is done
- 5- The way The physical quantity is measured

- A measurement can never be taken without any error. But it can be estimated when all errors are very small



Exp: 9.82 ± 0.5 less precise

Exp: 9.8 ± 0.1 more precise

Exp: True value: 9.86

$x_A = 9.87 \pm 0.01$ → More Accurate

$x_B = 10.1 \pm 0.1$ → Less Accurate

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Discrepancy test : accepted / not accepted

* True value X

* Result $\bar{X} \pm \Delta X$

- steps :

$$1 - D = |X - \bar{X}|$$

$$2 - 2^{\times} \Delta X$$

3 - if $D > 2\Delta X$ not accepted

if $D \leq 2\Delta X$ accepted

significant figures

• حس الارقام المكتوبة التي يمكن عدّها

Exp: 900: 1 significant

900: 3 ~

900.0: 4 sig

0.020: 2 sig

ΔX : should always be 1 sig figure

unless the leading digit was one

Then we keep the digit after Exp $0.123 \approx 0.12$

$0.16 \approx 0.17$

or 1.6

Roundling Rules :-

- any number less than 5 we fix the sig. fig
- " " more ~ 5 we round the last sig fig up
- If it was 5: Exp $3,5 \rightarrow 40$

$$\begin{array}{r} 45 \\ \text{drop off 8} \\ \hline 40 \end{array}$$

$$\begin{array}{r} 0.7251 \\ \text{drop off 5} \\ \hline 0.73 \end{array}$$

Values

* Addition and subtraction

- The no with the fewest decimal places limits the number of decimal places in the result
→ eg. 2.333

* Multiplication and division

- we find how much of sig fig there is in the numbers multiplied: The less controls the result
→ eg. 2.333

$$\sqrt{13} = \underline{3.682} \approx 3.7$$

$$\sqrt{2.4 + 10.2} = \sqrt{12.6} = 3.549 \text{ → } \begin{array}{l} \text{at least 3} \\ \text{sig fig} \end{array}$$

$$\sin(24) = (0.406) \approx 0.41$$

$$\cos(70) = \frac{0.342}{\approx 0.3}$$

Uncertainty

* Addition and subtraction

$$R = x \pm y \quad \Delta R = \Delta x + \Delta y : \text{general rule}$$

* Constant multipliers

$$R = ax \pm by \quad \Delta R = a \Delta x + b \Delta y$$

But if a and b are not const
Then
 $\Delta R = a \Delta x + x \Delta a + b \Delta y + b \Delta y$

* Multiplication and division

$$A = xy$$

$$\frac{\Delta A}{A} = \frac{y \Delta x + x \Delta y}{xy} \quad \text{for 2 values}$$

$$\frac{\Delta A}{A} = \frac{y \Delta x}{xy} + \frac{x \Delta y}{xy}$$

for more than 2 values

$$= \frac{\Delta x}{x} + \frac{\Delta y}{y}$$

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* Raising to powers

$$R = X^l Y^m Z^n$$

$$\frac{\Delta R}{R} = |l| \frac{\Delta X}{X} + |m| \frac{\Delta Y}{Y} + |n| \frac{\Delta Z}{Z}$$

* $R = e^x$

$$\hookrightarrow \Delta R = e^x \Delta x$$

* $R = \ln X$

$$\hookrightarrow \Delta R = \frac{1}{X} \Delta x$$

* $R = \sin \theta$

$$\hookrightarrow \Delta R = \cos \theta \Delta \theta$$

* $R = \cos \theta$

$$\hookrightarrow \Delta R = -\sin \theta \Delta \theta$$

Radius \rightarrow $\sqrt{x^2 + y^2}$ \rightarrow $\theta = \tan^{-1} \frac{y}{x}$

$2\pi \rightarrow 180^\circ$ طرفة عين

الاستعاضة الصغرى

$$\bullet R = R(X, Y, Z)$$

$$\hookrightarrow \bullet \Delta R = \left| \frac{\partial R}{\partial X} \right| \Delta x + \left| \frac{\partial R}{\partial Y} \right| \Delta y + \left| \frac{\partial R}{\partial Z} \right| \Delta z$$

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