Electromagnetic Theory I

Abdallah Sayyed-Ahmad Department of Physics Birzeit University

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Chapter 1: Vector Analysis

- ✓ Vector Algebra
- Differential Calculus
- ✓ Integral Calculus
- ✓ Curvilinear Coordinates
- ✓ The Dirac Delta Function
- ✓ The Theory of Vector Fields



Differential Calculus

(i) Gradient

$$df = \frac{\partial f}{\partial x}dx + \frac{\partial f}{\partial y}dy + \frac{\partial f}{\partial z}dz$$
$$\left(\frac{\partial f}{\partial x}\hat{x} + \frac{\partial f}{\partial y}\hat{y} + \frac{\partial f}{\partial z}\hat{z}\right) \cdot (dx\hat{x} + dy\,\hat{y} + dz\,\hat{z}) = \overrightarrow{\nabla}f \cdot d\overrightarrow{l}$$
Gradient of f

What is the physical meaning of the gradient?

$$\vec{\nabla} f \cdot d\vec{l} = |\vec{\nabla} f| |d\vec{l}| \cos \theta$$

For a fixed distance |dl|, the greatest change in f occurs along the direction of the gradient **Gradient is a vector that points in the direction of maximum increase of a function. Its magnitude gives the slope (rate of increase) along this maximal direction.





Example: find the gradient of the magnitude of the position vector

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\frac{\partial r}{\partial x} = \frac{x}{\sqrt{x^2 + y^2 + z^2}} = \frac{x}{r} \qquad \frac{\partial r}{\partial y} = \frac{y}{\sqrt{x^2 + y^2 + z^2}} = \frac{y}{r} \qquad \frac{\partial r}{\partial z} = \frac{z}{\sqrt{x^2 + y^2 + z^2}} = \frac{z}{r}$$

$$\rightarrow \overline{\nabla}r = \frac{x}{r}\hat{x} + \frac{y}{r}\hat{y} + \frac{z}{r}\hat{z} = \frac{1}{r}(x\hat{x} + y\hat{y} + z\hat{z}) = \frac{\overline{r}}{r} = \hat{r}$$

The distance from the origin increases most rapidly in the radial direction



The del operator $(\vec{\nabla})$

$$\vec{\nabla} = \left(\frac{\partial}{\partial x}\hat{x} + \frac{\partial}{\partial y}\hat{y} + \frac{\partial}{\partial z}\hat{z}\right)$$

A vector operator (not a vector)

It can act on other scalar/vector functions as follows

- On scalar function f (gradient): $\vec{\nabla} f$
- On a vector function via dot product (divergence): $\vec{\nabla} \cdot \vec{v}$
- On a vector function via cross product (curl): $\vec{\nabla} \times \vec{\nu}$



The divergence ($div(\vec{v}) or \vec{\nabla} \cdot \vec{v}$)

For the vector field, $\vec{v} = v_x \hat{x} + v_y \hat{y} + v_z \hat{z}$

$$\vec{\nabla} \cdot \vec{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$$

A scalar, a measure of how much the vector field spread out (diverges) from the point of interest





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The divergence

Example: find the divergence of the following three vector fields: (a) $\vec{v} = \vec{r}$ (b) $\vec{v} = \hat{z}$ (c) $\vec{v} = z \hat{z}$ (d) $\vec{v} = y \hat{x} - x \hat{y}$

(a)
$$\vec{\nabla} \cdot \vec{v} = \vec{\nabla} \cdot \vec{r} = \frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} = 1 + 1 + 1 = 3$$

$$(b)\,\vec{\nabla}\cdot\vec{\nu}=0$$

$$(c)\vec{\nabla}\cdot\vec{\nu} = \frac{\partial z}{\partial z} = 1$$
$$(d)\vec{\nabla}\cdot\vec{\nu} = \frac{\partial y}{\partial x} - \frac{\partial x}{\partial y} = 0$$



The curl (rot (\vec{v}) or $\vec{\nabla} \times \vec{v}$)

For the vector field, $\vec{v} = v_x \hat{x} + v_y \hat{y} + v_z \hat{z}$

$$\vec{\partial} \times \vec{v} = egin{bmatrix} \hat{x} & \hat{y} & \hat{z} \\ rac{\partial}{\partial x} & rac{\partial}{\partial y} & rac{\partial}{\partial z} \\ rac{\partial}{v_x} & v_y & v_z \end{bmatrix}$$

A scalar, a measure of how much the vector field curl(or rotates) around the point of interest





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The curl

Example: find the curl of the following three vector fields: (a) $\vec{v} = x \hat{y}$ (b) $\vec{v} = -y \hat{x} + x \hat{y}$

$$(a) \vec{\nabla} \times \vec{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & x & 0 \end{vmatrix} = (0)\hat{x} + (0)\hat{y} + (1)\hat{z} = \hat{z}$$

$$(b) \vec{\nabla} \times \vec{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y & x & 0 \end{vmatrix} = (0)\hat{x} + (0)\hat{y} + (1+1)\hat{z} = 2\hat{z}$$



 $(a) \ \vec{\nabla}(fg) = f \ \vec{\nabla}g + g \ \vec{\nabla}f$ $(b) \ \vec{\nabla}(\vec{A} \cdot \vec{B}) = \vec{A} \times (\vec{\nabla} \times \vec{B}) + \vec{B} \times (\vec{\nabla} \times \vec{A}) + (\vec{A} \cdot \vec{\nabla})\vec{B} + (B \cdot \vec{\nabla})\vec{A}$ $(c) \ \vec{\nabla} \cdot (f \vec{A}) = \vec{A} \cdot \vec{\nabla}f + f (\vec{\nabla} \cdot \vec{A})$ $(d) \ \vec{\nabla} \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\vec{\nabla} \times \vec{A}) - \vec{A} \cdot (\vec{\nabla} \times \vec{B})$ $(e) \ \vec{\nabla} \times (f \vec{A}) = f (\vec{\nabla} \times \vec{A}) - \vec{A} \times \vec{\nabla}f$

 $(d) \, \vec{\nabla} \times \left(\vec{A} \times \vec{B} \right) = \left(B \cdot \vec{\nabla} \right) \vec{A} - \left(\vec{A} \cdot \vec{\nabla} \right) \vec{B} + \vec{A} \left(\vec{\nabla} \cdot \vec{B} \right) - \vec{B} \left(\vec{\nabla} \cdot \vec{A} \right)$

Quotient rules are easily obtained from the above rules



(a) Divergence of gradient: $\vec{\nabla} \cdot \vec{\nabla} f = \nabla^2 \mathbf{f} = \Delta \mathbf{f}$ (Laplacian of f) (b) Curl of graidents: $\vec{\nabla} \times \vec{\nabla} f = 0$

(c) Gradient of divergence: $\vec{\nabla}(\vec{\nabla} \cdot \vec{v})$ (d) Divergence of curl: $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{v}) = 0$

$$(e) \, \vec{\nabla} \times \left(\vec{\nabla} \times \vec{\vartheta} \right) = \vec{\nabla} \left(\vec{\nabla} \cdot \vec{\vartheta} \right) - \nabla^2 \vec{\vartheta}$$

