Electromagnetic Theory I

Abdallah Sayyed-Ahmad **Department of Physics Birzeit University**

March 1, 2021

Chapter 1: Vector Analysis

- √ Vector Algebra
- √ Differential Calculus
- \checkmark Integral Calculus
- ← Curvilinear Coordinates
- \checkmark The Dirac Delta Function
- \checkmark The Theory of Vector Fields

Differential Calculus

(i) Gradient

$$
df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz
$$

$$
\left(\frac{\partial f}{\partial x}\hat{x} + \frac{\partial f}{\partial y}\hat{y} + \frac{\partial f}{\partial z}\hat{z}\right) \cdot (dx\hat{x} + dy\hat{y} + dz\hat{z}) = \vec{\nabla}f \cdot d\vec{l}
$$
Gradient of f

What is the physical meaning of the gradient?

$$
\vec{\nabla} f \cdot d\vec{l} = |\vec{\nabla} f| |d\vec{l}| \cos \theta
$$

For a fixed distance $\left| d\vec{l} \right|$, the greatest change in f occurs along the direction of the gradient **Gradient is a vector that points in the direction of maximum increase of a function. Its magnitude gives the slope (rate of increase) along this maximal direction.

Example: find the gradient of the magnitude of the position vector

$$
r = \sqrt{x^2 + y^2 + z^2}
$$
\n
$$
\frac{\partial r}{\partial x} = \frac{x}{\sqrt{x^2 + y^2 + z^2}} = \frac{x}{r} \qquad \frac{\partial r}{\partial y} = \frac{y}{\sqrt{x^2 + y^2 + z^2}} = \frac{y}{r} \qquad \frac{\partial r}{\partial z} = \frac{z}{\sqrt{x^2 + y^2 + z^2}} = \frac{z}{r}
$$
\n
$$
\Rightarrow \overline{y}_r = \frac{x}{r}\hat{x} + \frac{y}{r}\hat{y} + \frac{z}{r}\hat{z} = \frac{1}{r}(x\hat{x} + y\hat{y} + z\hat{z}) = \frac{\overline{r}}{r} = \hat{r}
$$

The distance from the origin increases most rapidly in the radial direction

The del operator (\vec{V})

$$
\vec{\nabla} = \left(\frac{\partial}{\partial x}\hat{x} + \frac{\partial}{\partial y}\hat{y} + \frac{\partial}{\partial z}\hat{z}\right)
$$

A vector operator (not a vector)

It can act on other scalar/vector functions as follows

- **n** On scalar function f (gradient): $\overline{\nabla}f$
- **n** On a vector function via dot product (divergence): $\vec{\nabla} \cdot \vec{v}$
- **n** On a vector function via cross product (curl): $\vec{\nabla} \times \vec{v}$

The divergence (div (v) or $\vec{\nabla}$

For the vector field, $\vec{v} = v_x \hat{x} + v_y \hat{y} + v_z \hat{z}$

$$
\vec{\nabla} \cdot \vec{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}
$$

A scalar, a measure of how much the vector field spread out (diverges) from the point of interest

The divergence

Example: find the divergence of the following three vector fields: (a) \vec{v} = $\vec{r}(b) \vec{v} = \hat{z}(c) \vec{v} = z \, \hat{z}(d) \vec{v} = y \, \hat{x} - x \hat{y}$

$$
(a) \overrightarrow{\nabla} \cdot \overrightarrow{v} = \overrightarrow{\nabla} \cdot \overrightarrow{r} = \frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} = 1 + 1 + 1 = 3
$$

$$
(b) \overrightarrow{\nabla} \cdot \vec{v} = 0
$$

$$
(\mathbf{c})\vec{\nabla} \cdot \vec{v} = \frac{\partial z}{\partial z} = 1
$$

$$
(\mathbf{d})\vec{\nabla} \cdot \vec{v} = \frac{\partial y}{\partial x} - \frac{\partial x}{\partial y} = 0
$$

The curl (rot (\vec{v}) or $\vec{\nabla}\times\vec{v}$)

For the vector field, $\vec{v} = v_x \hat{x} + v_y \hat{y} + v_z \hat{z}$

$$
\vec{j} \times \vec{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}
$$

A scalar, a measure of how much the vector field curl(or rotates) around the point of interest

The curl

Example: find the curl of the following three vector fields: $(a) \vec{v} = x \hat{y} (b) \vec{v} = -y \hat{x} + x \hat{y}$

$$
(a) \overrightarrow{\nabla} \times \overrightarrow{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & x & 0 \end{vmatrix} = (0)\hat{x} + (0)\hat{y} + (1)\hat{z} = \hat{z}
$$

$$
(b) \overrightarrow{\nabla} \times \overrightarrow{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y & x & 0 \end{vmatrix} = (0)\hat{x} + (0)\hat{y} + (1+1)\hat{z} = 2\hat{z}
$$

 $\overline{v}(fg) = f \overline{y}g + g \overline{y}f$ $\overrightarrow{B}(\vec{A}\cdot\vec{B}) = \vec{A}\times(\vec{\nabla}\times\vec{B}) + \vec{B}\times(\vec{\nabla}\times\vec{A}) + (\vec{A}\cdot\vec{\nabla})\vec{B} + (\vec{B}\cdot\vec{\nabla})\vec{A}$ $(c) \vec{\nabla} \cdot (f\vec{A}) = \vec{A} \cdot \vec{\nabla} f + f(\vec{\nabla} \cdot \vec{A})$ $(d)\vec{\nabla}\cdot(\vec{A}\times\vec{B})=\vec{B}\cdot(\vec{\nabla}\times\vec{A})-\vec{A}\cdot(\vec{\nabla}\times\vec{B})$ $\overrightarrow{Q}(\overrightarrow{e})\overrightarrow{\nabla}\times(\overrightarrow{f}\overrightarrow{A}) = f(\overrightarrow{\nabla}\times\overrightarrow{A}) - \overrightarrow{A}\times\overrightarrow{\nabla}f$ $(d)\vec{\nabla}\times(\vec{A}\times\vec{B})=(B\cdot\vec{\nabla})\vec{A}-(\vec{A}\cdot\vec{\nabla})\vec{B}+\vec{A}(\vec{\nabla}\cdot\vec{B})-\vec{B}(\vec{\nabla}\cdot\vec{A})$

Quotient rules are easily obtained from the above rules

(a) Divergence of gradient: $\vec{\nabla} \cdot \vec{\nabla} f = \nabla^2 f = \Delta f$ (Laplacian of f) (b) Curl of graidents: $\vec{\nabla} \times \vec{\nabla} f = 0$

(c) Gradient of diveregence: $\vec{\nabla}(\vec{\nabla} \cdot \vec{v})$ (d) Divergence of curl: $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{v}) = 0$

$$
(e)\ \vec{\nabla}\times(\vec{\nabla}\times\vec{v})=\vec{\nabla}\left(\vec{\nabla}\cdot\vec{v}\right)-\nabla^2\vec{v}
$$

