

Q1): Using cylindrical coordinates

r, θ, z

velocity in cylindrical coordinates:

$$v^2 = (\dot{r})^2 + r^2(\dot{\theta})^2 + (\dot{z})^2$$

$$T = \frac{1}{2} m \dot{v}^2$$

$$U = mgz = mgr$$

$$L = T - U = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2 + \dot{z}^2) - mgr$$

$\dot{r} = \dot{z}$

(a) $\Rightarrow L = \frac{1}{2} m (2\dot{r}^2 + r^2 \dot{\theta}^2) - mgr$

the generalized coordinates are: r, θ

$$r: \frac{\partial L}{\partial r} - \frac{d}{dt} \frac{\partial L}{\partial \dot{r}} = 0$$

$$\frac{\partial L}{\partial r} = m r \dot{\theta}^2 - mg$$

$$\frac{\partial L}{\partial \dot{r}} = 2 m \dot{r}$$

$$\Rightarrow m r \dot{\theta}^2 - mg - 2 m \ddot{r} = 0 \quad \text{--- (1)}$$

$$\Rightarrow m r \dot{\theta}^2 - mg - 2 m \ddot{r} = 0$$

$$\theta: \frac{\partial L}{\partial \theta} - \frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}} = 0$$

$$\frac{\partial L}{\partial \theta} = 0$$

$$\frac{\partial L}{\partial \dot{\theta}} = m r^2 \dot{\theta} = m r^2 \Omega$$

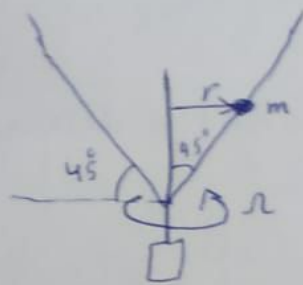
$$\Rightarrow \frac{d}{dt} (m r^2 \dot{\theta}) = 0 \quad \text{--- (2)}$$

$$m r^2 \dot{\theta} = \text{constant}$$

$P_{\theta} = \text{constant}$ (constant of motion)

(b) The two constants of motion are:

$$P_{\theta}, \quad \theta = 45^\circ \Rightarrow \tan 45^\circ = \frac{z}{r} \Rightarrow z = r$$



$$\tan \frac{\pi}{4} = 1 = \frac{z}{r} \Rightarrow z = r$$

$$\Omega = \dot{\theta}$$

(c)

$$(Q2) \quad p = \frac{\partial L}{\partial \dot{y}} = m \dot{y}$$

$$-\dot{p} = \frac{\partial H}{\partial y} = -m \dot{y}$$

$$H = -m y \dot{y}$$

$$(a) \quad \begin{aligned} H &= T + V \\ &= \frac{1}{2} m \dot{y}^2 + mgy e^{\delta t} \\ &= \frac{p^2}{2m} + mgy e^{\delta t} \end{aligned}$$

Hamilton's eqs:

$$(b) \quad \begin{aligned} \square \quad -\dot{p} &= \frac{\partial H}{\partial y} = mgy e^{\delta t} \\ &\Rightarrow mgy e^{\delta t} + \dot{p} = 0 \\ &\quad mgy e^{\delta t} + m \dot{y} = 0 \quad - (1) \text{ which is first order diff. eq.} \\ \square \quad \dot{y} &= \frac{\partial H}{\partial p} = \frac{p}{m} \end{aligned}$$

$$p = m \dot{y} \quad - (2) \text{ which is as calculated above}$$

$$(c) \quad \frac{dH}{dt} = \frac{\partial H}{\partial t} = \delta mgy e^{\delta t} \quad \text{which is dependent of time } t$$

Hence, H is not a constant of motion

$$Q3): n(x, y) = n_0(1 + ky)$$

$$v = \frac{c}{n} = \frac{c}{n_0(1 + ky)}$$

$$v = \frac{ds}{dt}$$

$$dt = \frac{ds}{v}$$

$$t = \int_{(x_0, y_0)}^{(x_1, y_1)} \frac{ds}{v} = \int \frac{(dx^2 + dy^2)^{1/2} (n_0(1 + ky))}{c}$$

$$= \int \frac{n_0}{c} (1 + ky) (1 + y'^2)^{1/2} dx$$

$$\text{Let } f = \frac{n_0}{c} (1 + ky) (1 + y'^2)^{1/2}$$

which is the function that describes the path of light in this medium.

Using the second form of the Euler-Lagrange equation:

$$\frac{\partial f}{\partial x} - \frac{d}{dx} \left(f - y' \frac{\partial f}{\partial y'} \right) = 0$$

$$\text{Note that } \frac{\partial f}{\partial x} = 0 \Rightarrow f - y' \frac{\partial f}{\partial y'} = \text{constant} = A$$

$$\frac{\partial f}{\partial y'} = y' (1 + y'^2)^{-3/2}$$

$$\Rightarrow \frac{n_0}{c} (1 + ky) (1 + y'^2)^{1/2} - y'^2 (1 + y'^2)^{-3/2} = A$$

$$\left. \begin{array}{l} x(0) = 0 \\ y(0) = 0 \end{array} \right\} \text{start from origin}$$

Q1 (d):

d) : First, we need to determine the effective potential:
that is,

$$\begin{aligned} H &= T + U \\ &= m\dot{r}^2 + \frac{p_\theta^2}{2mr^2} + mgr \\ &= \frac{1}{2}\delta\dot{r}^2 + \underbrace{\frac{p_\theta^2}{\delta r^2} + \frac{\delta gr}{2}}_{U_{\text{eff}}} \end{aligned}$$

where $\delta = 2m$

$$\frac{\partial U_{\text{eff}}}{\partial r} = -\frac{2p_\theta^2}{\delta r^3} + \frac{\delta g}{2} = 0$$

$$\Rightarrow r^3 = \frac{4p_\theta^2}{\delta^2 g} = \frac{r^4 \dot{\theta}^2}{g} = \frac{r^4 \Omega^2}{g}$$

$$\Rightarrow r = \frac{g}{\Omega^2}$$