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$$\omega = 0 \Rightarrow R^2 \begin{bmatrix} 2k & -k & -k \\ -k & 2k & -k \\ -k & -k & 2k \end{bmatrix} \begin{pmatrix} A_1 \\ A_2 \\ A_3 \end{pmatrix} = 0$$

$$A_1 = A_2 = A_3$$

$$\frac{1}{\sqrt{3mR^2}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\omega^2 = \frac{3k}{m} \Rightarrow \begin{pmatrix} -k & -k & -k \\ -k & -k & -k \\ -k & -k & -k \end{pmatrix} \begin{pmatrix} A_1 \\ A_2 \\ A_3 \end{pmatrix} = 0$$

$$A_1 + A_2 + A_3 = 0$$

The eigenvectors cannot be uniquely fixed.

$$\frac{1}{\sqrt{6mR^2}} \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix}, \quad \frac{1}{\sqrt{2mR^2}} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

Spherical Double pendulum

$$x_1 = \sin(\theta_1) \cos(\varphi_1)$$

$$y_1 = \sin(\theta_1) \sin(\varphi_1)$$

$$z_1 = -\cos(\theta_1)$$

$$x_2 = x_1 + \sin(\theta_2) \cos(\varphi_2)$$

$$y_2 = y_1 + \sin(\theta_2) \sin(\varphi_2)$$

$$z_2 = z_1 - \cos \theta_2$$

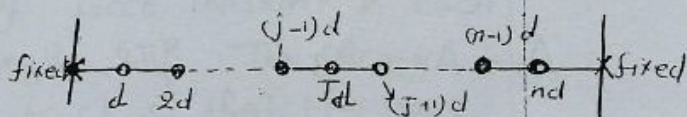
$$T = \frac{1}{2} (\dot{r}_1^2 + \dot{r}_2^2)$$

$$U = g(z_1 + z_2)$$

The Loaded String

- Equal masses & equally spaced

- Fixed endpoints

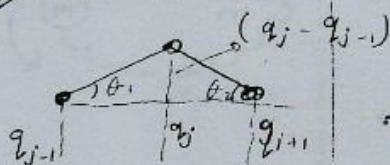


- Considering only nearest neighbour interaction.

⊕ Now, Consider the j -th particle that is displaced in transverse fashion from its equilibrium

$$F_j = T \sin \theta_1 - T \sin \theta_2$$

$$= -\frac{T}{d} (q_j - q_{j-1}) - \frac{T}{d} (q_j - q_{j+1}) \quad \theta: \text{small}$$



$$m \ddot{q}_j = \frac{T}{d} q_{j-1} - \frac{2T}{d} q_j + \frac{T}{d} q_{j+1}$$

on the other hand if we want to solve in Lagrangian method.

$$U = \frac{T}{2d} \sum_{j=1}^{n+1} (q_{j-1} - q_j)^2$$

$$F_j = -\frac{\partial U}{\partial q_j} = \frac{T}{d} (q_{j-1} - 2q_j + q_{j+1})$$

$$L = \frac{1}{2} \sum_{j=1}^{n+1} (m \dot{q}_j^2 - \frac{T}{d} (q_{j-1} - q_j)^2)$$

Equation of motion-

$$\frac{\partial}{\partial t} \left(\frac{\partial L}{\partial \dot{q}_j} \right) - \frac{\partial L}{\partial q_j} = 0$$

$$\frac{d}{dt} (m\dot{q}_j) - \frac{\tau}{d} (q_{j-1} - 2q_j + q_{j+1}) = 0$$

$$m\ddot{q}_j - \frac{\tau}{d} (q_{j-1} - 2q_j + q_{j+1}) = 0$$

يحلح على n من المعادلات

$$m\ddot{q}_{j-1} - \frac{\tau}{d} (q_{j-2} - 2q_{j-1} + q_j) = 0$$

$$m\ddot{q}_j - \frac{\tau}{d} (q_{j-1} - 2q_j + q_{j+1}) = 0$$

$$m\ddot{q}_{j+1} - \frac{\tau}{d} (q_j - 2q_{j+1} + q_{j+2}) = 0$$

$$\text{let } q_j = a_j e^{i\omega t}$$

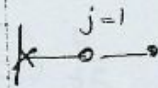
$$-m\omega^2 a_j - \frac{\tau}{d} (a_{j-1} - 2a_j + a_{j+1}) = 0$$

$$-\frac{\tau}{d} a_{j-1} + \left(\frac{2\tau}{d} - m\omega^2 \right) a_j - \frac{\tau}{d} a_{j+1} = 0$$

نفس = det(A) يكون غير تافه nontrivial solution ليس يحلح على n

A: coefficient matrix

ليس قبل هيك



For $j=1$ $(\frac{2T}{d} - m\omega^2)a_1 - \frac{T}{d}a_2 = 0$

For $j=n$ $-\frac{T}{d}a_{n-1} + (\frac{2T}{d} - m\omega^2)a_n = 0$

معادلة اول
جيم وآخر
جيم غير من
الباقي

Now, let us construct the Matrix of the coefficients

first, let $\frac{2T}{d} - m\omega^2 = \lambda$

$$\begin{vmatrix} \lambda & -\frac{T}{d} & 0 & 0 & 0 \\ -\frac{T}{d} & \lambda & -\frac{T}{d} & 0 & 0 \\ 0 & -\frac{T}{d} & \lambda & -\frac{T}{d} & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & -\frac{T}{d} & \lambda \end{vmatrix}_{n \times n} = 0$$

For $n=1$

$\frac{2T}{d} - m\omega^2 = 0 \Rightarrow \omega = \sqrt{\frac{2T}{md}}$



For $n=2$

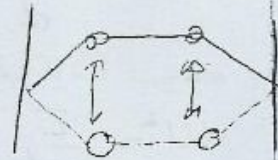
$\begin{vmatrix} \lambda & -T/d \\ -T/d & \lambda \end{vmatrix} = 0 \Rightarrow \frac{2T}{d} - m\omega^2 = \pm \frac{T}{d}$

$$\omega_{12}^2 = \frac{\tau}{md} (2\tau/d)$$

$$\boxed{\lambda = \frac{\tau}{d}} \quad \begin{bmatrix} \tau/d & -\tau/d \\ -\tau/d & \tau/d \end{bmatrix} \begin{bmatrix} a_{11} \\ a_{12} \end{bmatrix} = 0$$

$$\frac{\tau}{d} a_{11} - \frac{\tau}{d} a_{12} = 0$$

$$\boxed{a_{11} = a_{12}}$$



$$\lambda = -\frac{\tau}{d}$$



$$a_{12} = -a_{22}$$

For Large Number of particles.

عاد الورد الوحيه
بالسيفه
المستوى
المستوى

$$m \ddot{q}_j - \frac{\tau}{d} q_{j-1} + \frac{2\tau}{d} q_j - \frac{\tau}{d} q_{j+1} = 0$$

$$q_j = a_j e^{i\omega t} = \underbrace{a e^{i(j\delta - \sigma)}}_{a_i} e^{i\omega t}$$

$$q_{j-1} = a e^{i((j-1)\delta - \sigma)} e^{i\omega t}$$

$$q_{j+1} = a e^{i((j+1)\delta - \sigma)} e^{i\omega t}$$

$$m \ddot{q}_j - \frac{\tau}{d} q_{j-1} + \frac{2\tau}{d} q_j - \frac{\tau}{d} q_{j+1} = 0$$

$$-m\omega^2 a e^{i((j-1)\delta)} + \frac{2\tau}{d} e^{ij\delta} - \frac{\tau}{d} e^{i(j+1)\delta} = 0$$

$$-m\omega^2 \frac{\tau}{d} e^{-i\delta} + \frac{2\tau}{d} - \frac{\tau}{d} e^{i\delta} = 0$$

$$-m\omega^2 + \frac{\tau}{d} (e^{i\delta} + e^{-i\delta}) + \frac{2\tau}{d} = 0$$

$$\omega^2 = \frac{\tau}{md} (2 - e^{i\delta} + e^{-i\delta})$$

$$\omega^2 = \frac{2\tau}{md} (1 - \cos \delta)$$

$$= \frac{4\tau}{md} \sin^2 \left(\frac{\delta_r}{2} \right) \quad r=1, 2, \dots$$

$$\omega = 2 \sqrt{\frac{\tau}{md}} \sin \left(\frac{\delta_r}{2} \right)$$

عشان نوجد δ_r بنطبق BC's وهون BC's انه في الأجزاء fixed.

From last lecture

$$w = \frac{2}{m} \sqrt{\frac{E}{md}} \sin\left(\frac{\gamma_r}{2}\right)$$

$$\text{let } a_{j,r} = a_r e^{i(j\gamma_r - \delta_r)}$$

If we consider the real part

$$a_{j,r} = a_r \cos(j\gamma_r - \delta_r)$$

حسب BC's نطلب γ_r و δ_r

الظرفان
fixed

$$a_{0,r} = a_{(n+1),r} = 0$$

$$0 = a_r \cos(j\gamma_r - \frac{\pi}{2}) = a_r \sin(j\gamma_r)$$

$$a_r \sin((n+1)\gamma_r) = 0$$

$$(n+1)\gamma_r = s\pi$$

$$\gamma_r = \frac{s\pi}{n+1}, \quad s = 1, 2, 3, \dots$$

$$\gamma_r = \frac{r\pi}{n+1}$$

$$a_{j,r} = a_r \sin j\left(\frac{r\pi}{n+1}\right)$$

⊗ The General Solution

$$q_j = \sum \beta_r' a_r \sin j \left(\frac{r\pi}{n+1} \right) e^{i\omega_r t}$$

$$\begin{aligned} \omega_r &= 2\sqrt{\frac{L}{md}} \sin \left(\frac{\theta_r}{2} \right) \\ &= 2\sqrt{\frac{L}{md}} \sin \left(\frac{r\pi}{2(n+1)} \right) \end{aligned}$$

$$\eta_r(t) = \beta_r e^{i\omega_r t} \quad \& \quad \beta_r = \beta_r' a_r$$

$$q_j(t) = \sum_r \eta_r(t) \sin j \left(\frac{r\pi}{n+1} \right)$$

Real part $\text{Re} [q(t)]$

$$q_j = \sum \sin j \left(\frac{r\pi}{n+1} \right) \left(\sqrt{M} \cos \omega_r t - \nu \sin \omega_r t \right)$$

$$\beta_r = \sqrt{M} + i\nu$$

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