

Figure 3.27 Multilist implementation for registration problem

r n

1.

th ts. by

an ee

lly

We

or.

ler

its

icit

ced

red

ind

ind for

rst

eed

his

rse,

eni,

ent

and

3.2.8. Cursor Implementation of Linked Lists

Many languages, such as BASIC and FORTRAN, do not support pointers. If linked lists are required and pointers are not available, then an alternative implementation must be used. The method we will describe is known as a *cursor* implementation.

The two important features present in a pointer implementation of linked lists are as follows:

- 1. The data are stored in a collection of structures. Each structure contains data and a pointer to the next structure.
- 2. A new structure can be obtained from the system's global memory by a call to *malloc* and released by a call to *free*.

Our cursor implementation must be able to simulate this. The logical way to satisfy condition 1 is to have a global array of structures. For any cell in the array, its array index can be used in place of an address. Figure 3.28 gives the declarations for a cursor implementation of linked lists.

We must now simulate condition 2 by allowing the equivalent of *malloc* and *free* for cells in the *CursorSpace* array. To do this, we will keep a list (the *freelist*) of cells that are not in any list. The list will use cell 0 as a header. The initial configuration is shown in Figure 3.29.

A value of 0 for Next is the equivalent of a NULL pointer. The initialization of CursorSpace is a straightforward loop, which we leave as an exercise. To perform a malloc, the first element (after the header) is removed from the freelist. To perform

```
#ifndef _Cursor_H
 typedef int PtrToNode:
 typedef PtrToNode List:
 typedef PtrToNode Position;
 void InitializeCursorSpace( void );
 List MakeEmpty( List L );
 int IsEmpty( const List L );
 int IsLast( const Position P, const List L );
 Position Find( ElementType X, const List L );
 void Delete( ElementType X, List L );
 Position FindPrevious( ElementType X, const List L );
 void Insert( ElementType X, List L, Position P );
 void DeleteList( List L );
Position Header( const List L );
Position First( const List L );
Position Advance( const Position P );
ElementType Retrieve( const Position P );
#endif
            /* _Cursor_H */
/* Place in the implementation file */
struct Node
    ElementType Element:
    Position
                Next:
};
struct Node CursorSpace[ SpaceSize ];
```

Figure 3.28 Declarations for cursor implementation of linked lists

a free, we place the cell at the front of the freelist. Figure 3.30 shows the cursor implementation of malloc and free. Notice that if there is no space available, our routine does the correct thing by setting P = 0. This indicates that there are no more cells left, and also makes the second line of CursorAlloc a nonoperation (no-op).

Given this, the cursor implementation of linked lists is straightforward. For consistency, we will implement our lists with a header node. As an example, in Figure 3.31, if the value of L is 5 and the value of M is 3, then L represents the list a, b, e and M represents the list c, d, f.

To write the functions for a cursor implementation of linked lists, we must pass and return the identical parameters as the pointer implementation. The routines are straightforward. Figure 3.32 implements a function to test whether a list is empty. Figure 3.33 implements the test of whether the current position is the

Slot	Element	Next
0		1
	*1	
1 2 3		2 3 4 5 6
3		4
		5
4 5 6	.*	
6	ing.	7
- 7		8
8	-	9
9	į	10
10		0

Figure 3.29 An initialized CursorSpace

```
static Position
CursorAlloc( void )
{
    Position P;

    P = CursorSpace[ 0 ].Next;
    CursorSpace[ 0 ].Next = CursorSpace[ P ].Next;

    return P;
}

static void
CursorFree( Position P )
{
    CursorSpace[ P ].Next = CursorSpace[ 0 ].Next;
    CursorSpace[ 0 ].Next = P;
}
```

Figure 3.30 Routines: CursorAlloc and CursorFree

sor

our

or in

ist

iss

les

ist

he

last in a linked list. The function *Find* in Figure 3.34 returns the position of X in list L. The code to implement deletion is shown in Figure 3.35. Again, the interface for the cursor implementation is identical to the pointer implementation. Finally, Figure 3.36 shows a cursor implementation of *Insert*.

The rest of the routines are similarly coded. The crucial point is that these routines follow the ADT specification. They take specific arguments and perform specific operations. The implementation is transparent to the user. The cursor implementation could be used instead of the linked list implementation, with virtually no change required in the rest of the code. If relatively few Finds are

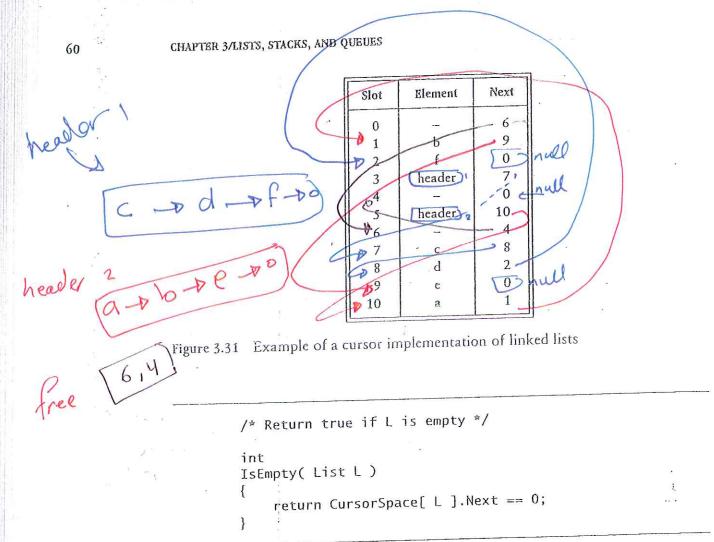


Figure 3.32 Function to test whether a linked list is empty—cursor implementation

```
/* Return true if P is the last position in list L */
/* Parameter L is unused in this implementation */
int
IsLast( Position P, List L )
{
    return CursorSpace[ P ].Next == 0;
}
```

Figure 3.33 Function to test whether P is last in a linked list—cursor implementation

Figure 3.34 Find routine—cursor implementation

Figure 3.35 Deletion routine for linked lists—cursor implementation

performed, the cursor implementation could be significantly faster because of the lack of memory management routines.

The freelist represents an interesting data structure in its own right. The cell that is removed from the freelist is the one that was most recently placed there by

```
/* Insert (after legal position P) */
        /* Header implementation assumed */
        /* Parameter L is unused in this implementation */
        void
        Insert( ElementType X, List L, Position P )
            Position TmpCell;
            TmpCell = CursorAlloc();
/* 1*/
            if( TmpCell == 0 )
/* 2*/
                FatalError( "Out of space!!!" );
/* 3*/
            CursorSpace[ TmpCell ]. Element = X;
            CursorSpace[ TmpCell ].Next = CursorSpace[ P ].Next;
/* 4*/
/* 5*/
            CursorSpace[ P ].Next = TmpCell;
/* 6*/
```

Figure 3.36 Insertion routine for linked lists—cursor implementation

virtue of free. Thus, the last cell placed on the freelist is the first cell taken off. The data structure that also has this property is known as a *stack*, and is the topic of the next section.

3.3. The Stack ADT

3.3.1. Stack Model

A stack is a list with the restriction that insertion and deletions can be performed in only one position, namely, the end of the list, called the top. The fundamental operations on a stack are Push, which is advalent to an insert, and Pop, which deletes the most recently inserted element. The most recently inserted element can be examined prior to performing a Push by use of the Top routine. A Pop or Top on an empty stack is generally considered an error in the stack ADT. On the other hand, running out of space when per tening a Push is an implementation error but nor an ADT error.

Stacks are sometimes known as LIFO (last in, first out) lists. The model depicted in Figure 3.37 signifies only that *Push*es are input operations and *Pops* and *Tops* are output. The usual operations to make empty stacks and test for emptiness are part of the reperture, but essentially all that you can do to a stack is *Push* and *Pop*.

Figure 3.38 shows an abstract stack after several operations. The general model is that here is some element that is at the top of the stack, and it is the only element that is visible.