

Sorting Algorithms

- There are many sorting algorithms, such as:
	- Selection Sort
	- Insertion Sort
	- Bubble Sort
	- Merge Sort
	- Quick Sort
	- Shell Srot

Selection Sort

- The list is divided into two sublists, *sorted* and *unsorted*, which are divided by an imaginary wall.
- We find the smallest element from the unsorted sublist and swap it with the element at the beginning of the unsorted data.
- After each selection and swapping, the imaginary wall between the two sublists move one element ahead, increasing the number of sorted elements and decreasing the number of unsorted ones.
- Each time we move one element from the unsorted sublist to the sorted sublist, we say that we have completed a sort pass.
- A list of n elements requires $n-1$ passes to completely rearrange the data.

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Selection Sort (cont.)

```
template <class Item>
void selectionSort( Item a[], int n) {
  for (int i = 0; i < n-1; i++) {
    int min = i;
   for (int j = i+1; j < n; j++)if (a[j] < a[\min]) min = j;
    swap(a[i], a[min]);
  }
}
template < class Object>
void swap( Object &lhs, Object &rhs )
{
  Object tmp = lhs;
  lhs = rhs;
  rhs = tmp;}
```


Insertion Sort Algorithm

```
void insertionSort(Item a[], int n)
{
   for (int i = 1; i < n; i++)
   { 
      Item tmp = a[i];
      for (int j=i; j>0 && tmp < a[j-1]; j--)
         a[j] = a[j-1];
      a[j] = tmp;}
}
```


Bubble Sort

- The list is divided into two sublists: sorted and unsorted.
- The smallest element is bubbled from the unsorted list and moved to the sorted sublist.
- After that, the wall moves one element ahead, increasing the number of sorted elements and decreasing the number of unsorted ones.
- Each time an element moves from the unsorted part to the sorted part one sort pass is completed.
- Given a list of n elements, bubble sort requires up to n-1 passes to sort the data.

Bubble Sort Algorithm

```
template <class Item>
void bubleSort(Item a[], int n)
{
  bool sorted = false; 
   int last = n-1;
   for (int i = 0; (i < last) && !sorted; i++){
      sorted = true;
      for (int j=last; j > i; j--)
         if (a[j-1] > a[j]swap(a[j],a[j-1]);
            sorted = false; // signal exchange
         }
    }
}
```


Mergesort • Mergesort algorithm is one of two important divide-and-conquer sorting algorithms (the other one is quicksort). • It is a recursive algorithm. – Divides the list into halves, – Sort each halve separately, and – Then merge the sorted halves into one sorted array.


```
Merge
const int MAX SIZE = maximum-number-of-items-in-array;void merge(DataType theArray[], int first, int mid, int last) 
  {
  DataType tempArray[MAX SIZE]; // temporary array
   int first1 = first; // beginning of first subarray
   int last1 = mid; // end of first subarray
   int first2 = mid + 1; // beginning of second subarray
   int last2 = last; // end of second subarray
   int index = first1; // next available location in tempArray
   for (; (first1 <= last1) &6k (first2 <= last2); ++index) {
     if (theArray[first1] < theArray[first2]) { 
        tempArray[index] = theArray[first1];
        ++first1;
      }
     else { 
          tempArray[index] = theArray[first2];++first2;
      } }
                                                            26
```
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Merge (cont.)

```
// finish off the first subarray, if necessary
   for (; first1 \le last1; ++first1, ++index)
      tempArray[index] = theArray[first1];
  // finish off the second subarray, if necessary
   for (; first2 \le last2; ++first2, ++index)
      tempArray[index] = theArray[first2];
  // copy the result back into the original array
   for (index = first; index \le last; ++index)
      theArray[index] = tempArray[index];
} // end merge
```
Mergesort

```
void mergesort(DataType theArray[], int first, int last) {
  if (first < last) {
     int mid = (first + last)/2; // index of midpoint
     mergesort(theArray, first, mid);
     mergesort(theArray, mid+1, last);
     // merge the two halves
     merge(theArray, first, mid, last);
   }
} // end mergesort
```


Mergesort – Analysis

• Mergesort is extremely efficient algorithm with respect to time.

 $-$ Both worst case and average cases are **O** (\mathbf{n} $*$ $\log_2 \mathbf{n}$)

- But, mergesort requires an extra array whose size equals to the size of the original array.
- If we use a linked list, we do not need an extra array
	- But, we need space for the links
	- And, it will be difficult to divide the list into half $(O(n))$


```
Shell Sort Code
int j, p, gap; comparable tmp;
for (gap = N/2; gap > 0; gap = gap/2)
for (p = gap; p < N; p++){
  tmp = a[p];
  for ( j = p; j>=gap && tmp<a[j-gap]; j=j-gap)
      a[ j ] = a[ j - gap ];
  a[j] = tmp;
 }
```


Shell Sort Analysis

Shellsort's **worst-case** performance using Hibbard's increments is $Θ(n^{3/2})$.

The **average** performance is thought to be about $O(n^{5/4})$

The exact complexity of this algorithm is still being debated

for **mid-sized** data : nearly as well if not better than the faster **(ⁿ log n)** sorts.

Animations: <http://www.sorting-algorithms.com/shell-sort> <http://www.cs.pitt.edu/~kirk/cs1501/animations/Sort2.html>

Comparison of Sorting Algorithms

