Mustafa Jarrar: Lecture Notes on Linear Regression Birzeit University, 2018

Version 1

# Machine Learning Linear Regression

#### Mustafa Jarrar

**Birzeit** University



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Acknowledgement: This lecture is based on (but not limited to) Andrew Ng's course about Machine Learning https://www.youtube.com/channel/UCMoXOGX9mgrYNEwpclQUcag Mustafa Jarrar: Lecture Notes on Linear Regression Machine Learning Birzeit University, 2018

# Machine Learning Linear Regression

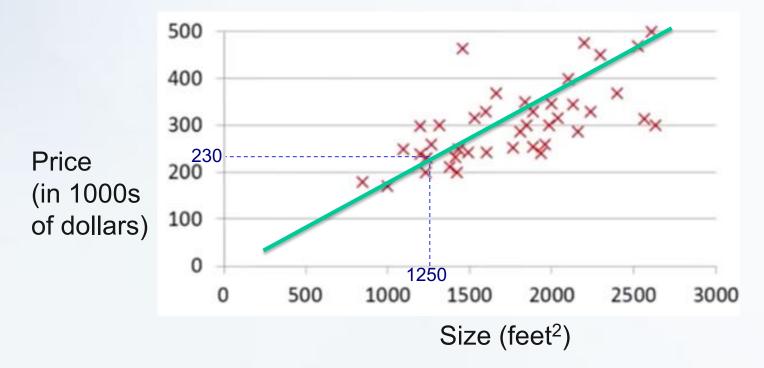
In this lecture:

Part 1: Motivation (Regression Problems)

- Part 2: Linear Regression
- Part 3: The Cost Function
- Part 4: The Gradient Descent Algorithm
- Part 5: The Normal Equation
- Part 6: Linear Algebra overview
- Part 7: Using Octave
- Part 8: Using R

#### **Motivation**

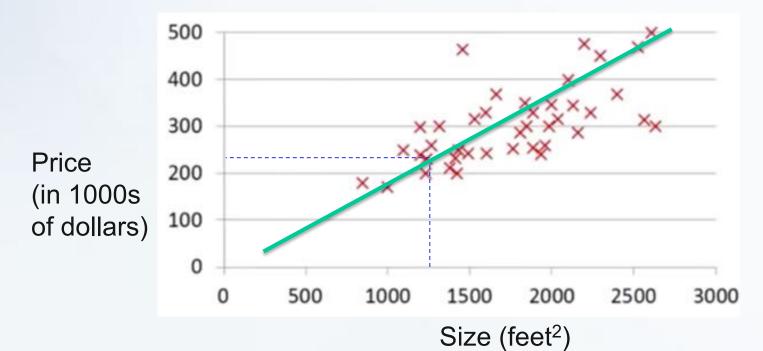
#### Given the following housing prices,



How much a house of 1250ft<sup>2</sup> costs? We may assume a linear curve, So, conclude that a house with 1250ft<sup>2</sup> costs 230K\$.

#### **Motivation**

#### Given the following housing prices



**Supervised Learning:** 

Given the right answers for each example in the data (training data)

#### **Regression Problem:**

Predict real-valued output Remember that classification (not regression) refers to predicting discrete-valued output

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## **Motivation**

#### Given the following training set of housing prices:

	Size in feet <sup>2</sup> (x)	Price (\$) in 1000s (y)
Our job is to learn from this data how to predict prices	2104	460
	1416	232
	1534	315
	852	178

#### **Notation:**

m = Number of training examples x's = "input" variable/features y's = output variable/target variable (x, y) : a training example  $(x^{i}, y^{i})$  : the i<sup>th</sup> training example

For example:  $x^{1} = 2104$  $y^{1} = 460$ 

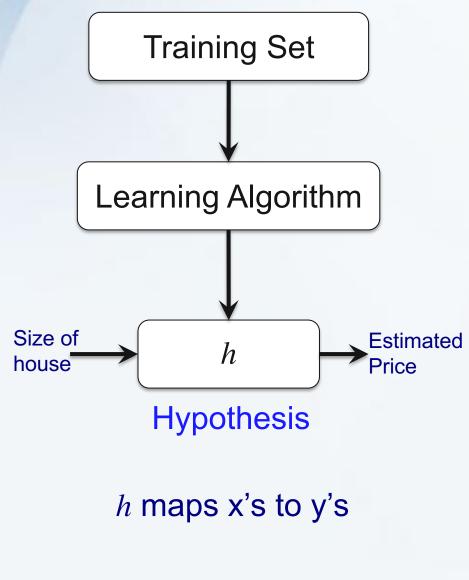
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## **Linear Regression**



How to represent *h*?  $h(x) = \theta_0 + \theta_1 x$ h(x) $\mathcal{Y}$  $\boldsymbol{\chi}$ 

- This is a linear function.
- Also called linear regression with one variable.

## **Linear Regression with Multiple Features**

Linear regression with multiple features is also called *multiple linear regression* 

#### Suppose we have the following features

$x_1$	$x_2$	$x_3$	$x_4$	У
Size ft <sup>2</sup>	bedrooms	floors	Age	Price
2104	5	1	45	460
1416	3	2	40	232
1534	3	2	30	315
852	2	1	36	178

A hypothesis function h(x) might be:

 $h(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3 + \ldots + \theta_n x_n$ 

or  $h(x) = \theta_0 x_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3 + \ldots + \theta_n x_n$   $(x_0=1)$ 

e.g.,  $h(x) = 80 + 0.1 \cdot x_1 + 0.01 \cdot x_2 + 3 \cdot x_3 - 2 \cdot x_4$ 

## **Polynomial Regression**

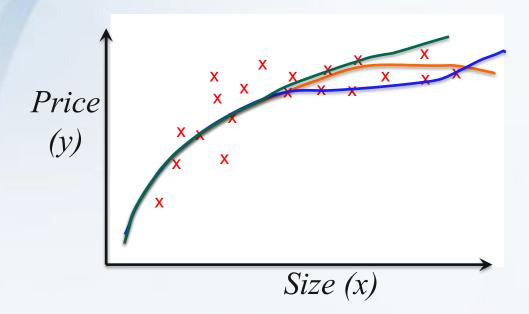
#### Suppose we have the following features

$x_1$	$x_2$	$x_3$	$x_4$	У
Size ft <sup>2</sup>	bedrooms	floors	Age	Price
2104	5	1	45	460
1416	3	2	40	232
1534	3	2	30	315
852	2	1	36	178

Another hypothesis function h(x) might be (*polynomial*):

$$h(x) = \theta_0 x_0 + \theta_1 x_1 + \theta_2 x_2^2 + \theta_2 x_3^3 + \dots + \theta_n x_n^n \qquad (x_0 = 1)$$

## **Polynomial Regression**



 $h(x) = \theta_0 + \theta_1 x + \theta_2 x^2$  $h(x) = \theta_0 + \theta_1 x + \theta_2 \sqrt[2]{x}$  $h(x) = \theta_0 + \theta_1 x + \theta_2 x^2 + \theta_3 x^3$ 

- We may combine features (e.g., size = width \* depth).
- We have the option of what features and what models (quadric, cubic,...) to use.
- Deciding which features and models that best fit our data and application, is beyond the scope of this course, but there are several algorithms for this.

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# Machine Learning Linear Regression

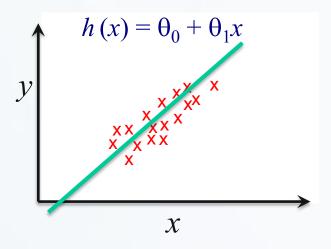
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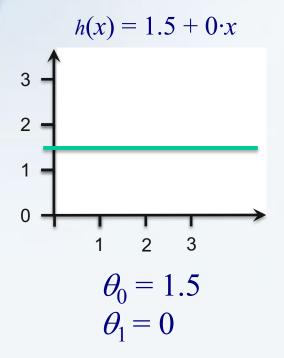
## **Understanding** $\theta$ **s** Values

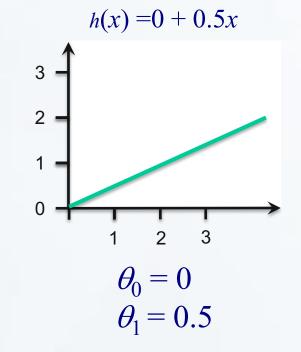
 $\theta_i$ 's: Parameters

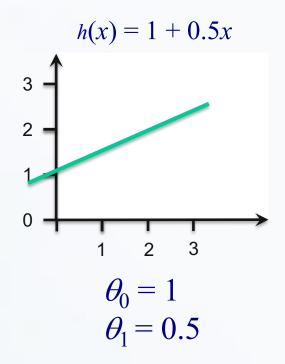
How to choose  $\theta_i$ 's?



## **Understanding** $\theta$ **s** Values

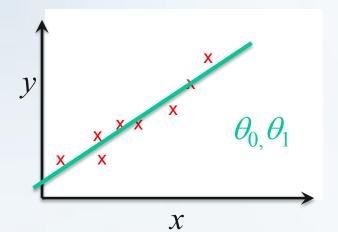






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## **The Cost Function**



Idea: Choose  $\theta_{0,}\theta_{1}$  so that h(x) is close to y for our training examples (x,y).

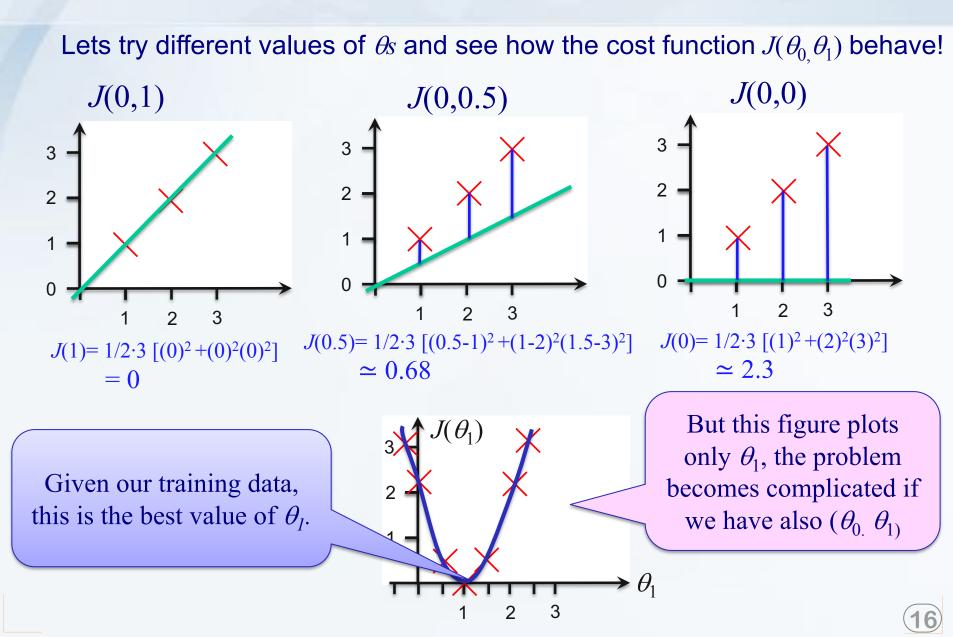
*y*: is the actual value.*h(x)*: is the estimated value.

The **Cost Function** *J* aims to find  $\theta_0, \theta_1$  that minimizes the error.

$$\mathbf{J}(\theta_{0,}\theta_{1}) = \frac{1}{2m} \sum_{i=1}^{m} (h(x^{i}) - y^{i})^{2}$$

# This cost function is also called a **Squared Error function**

#### **Undersetting the Cost Function**



Remember that our goal is find the minimum values of  $\theta_0$  and  $\theta_1$ 

**Hypothesis:**  $h(x) = \theta_0 + \theta_1$ 

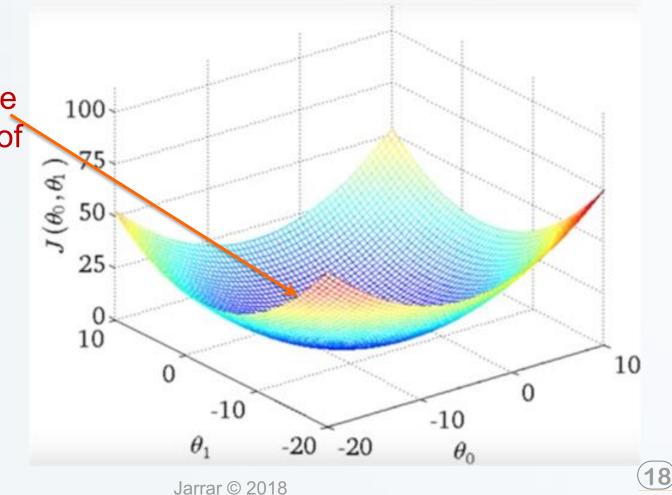
**Parameters:**  $\theta_0, \theta_1$ 

**Cost Function:**  $J(\theta_{0}, \theta_{1}) = \frac{1}{2m} \sum_{i=1}^{m} (h(x^{i}) - y^{i})^{2}$ 

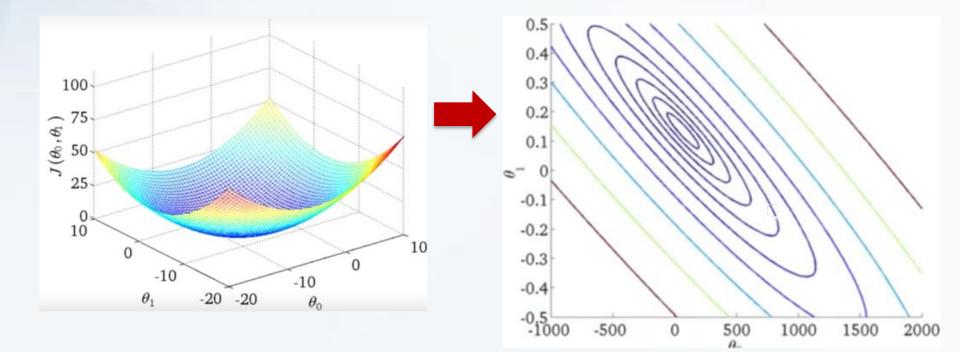
**Our Goal:** minimize  $J(\theta_0, \theta_1)$ 

Given any dataset, when we try to draw the cost function  $J(\theta_0, \theta_1)$ , we may get this 3D shape:

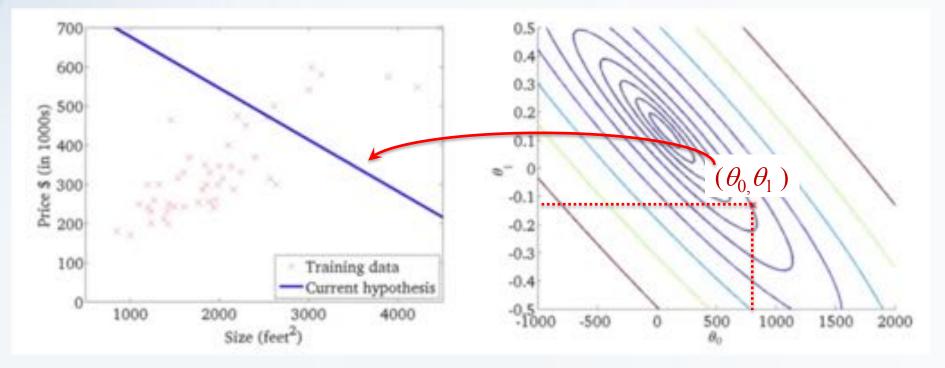
Given a dataset, our goal is find the minimum values of  $J(\theta_0, \theta_1)$ 



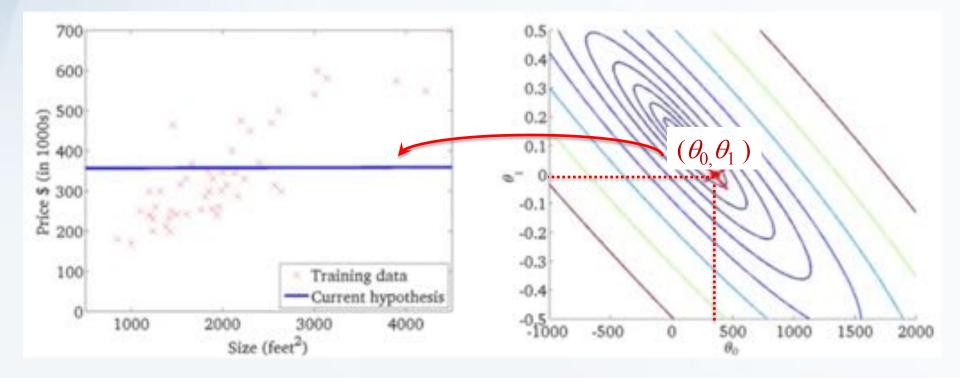
#### We may draw the cost function also using contour figures:

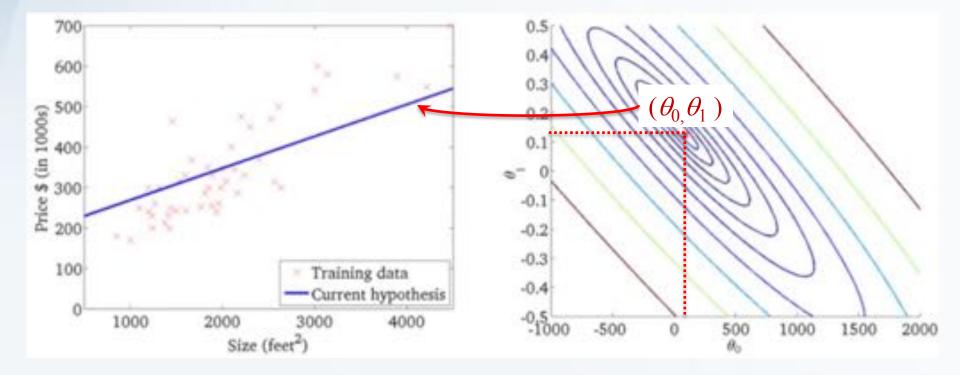


 $h(x) = 800 + 0.15 \cdot x$ 



 $h(x) = 360 + 0 \cdot x$ 





Is there any way/algorithm to find  $\theta_s$  automatically? Yes, e.g., the **Gradient Descent** Algorithm

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# Machine Learning Linear Regression

In this lecture:

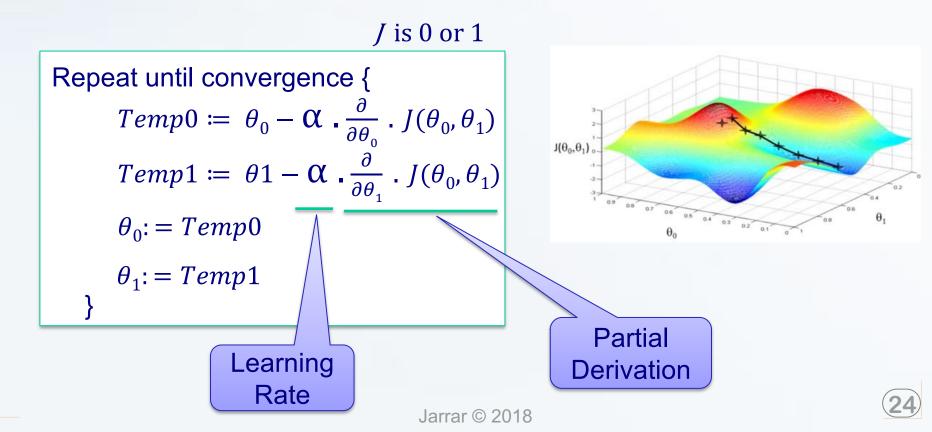
- Part 1: Motivation (Regression Problems)
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Part 4: The Gradient Descent Algorithm

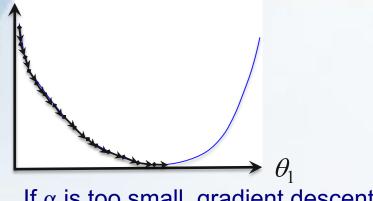
- Part 5: The Normal Equation
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#### The Gradient Descent Algorithm

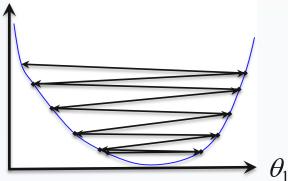
Starts with some initial values of  $\theta_0$  and  $\theta_1$ Keep changing  $\theta_0$  and  $\theta_1$  to reduce  $J(\theta_0, \theta_1)$ Until hopefully we end up at a minimum



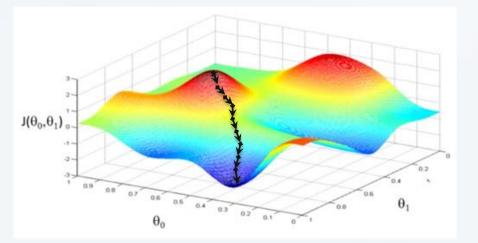
#### The Problem of the Gradient Descent algo.



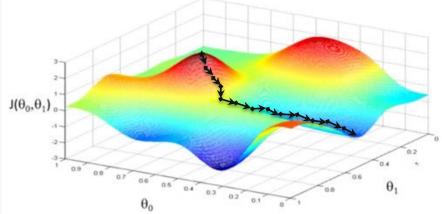
If  $\alpha$  is too small, gradient descent can be slow



If  $\alpha$  is too large, gradient decent can overshoot the minimum. It may fail to converge or even diverge



May converge to global minimum



May converge to a local minimum

#### **The Gradient Descent for Linear Regression**

Simplified version for linear regression

Repeat until convergence {  $\theta_0 \coloneqq \theta_0 - \alpha \cdot \frac{1}{m} \cdot \sum_{i=1}^m (h(x^i) - y^i)$   $\theta_1 \coloneqq \theta_1 - \alpha \cdot \frac{1}{m} \cdot \sum_{i=1}^m (h(x^i) - y^i) \cdot x^i$ }

Next, we will try to use Linear Algebra to *numerically* minimize  $\theta s$  (called **Normal Equation**) without needing to use iterating algorithms like Gradient Descent. However Gradient Descent scales better for bigger datasets.

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## **Minimizing** $\theta s$ **numerically**

Another way to numerically (using linear algebra) estimate the optimal values of  $\theta s$ .

Given the following features:

$x_1$	$x_2$	$x_3$	$X_4$	У
Size ft <sup>2</sup>	bedrooms	floors	Age	Price
2104	5	1	45	460
1416	3	2	40	232
1534	3	2	30	315
852	2	1	36	178

Convert the features and the target value into matrixes:

$$X = \begin{bmatrix} 2104 & 5 & 1 & 45 \\ 1416 & 3 & 2 & 40 \\ 1534 & 3 & 2 & 30 \\ 852 & 2 & 1 & 36 \end{bmatrix} \qquad y = \begin{bmatrix} 460 \\ 232 \\ 315 \\ 178 \end{bmatrix}$$
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## **Minimizing** $\theta s$ **numerically**

$x_1$	$x_2$	$x_3$	$x_4$	У
Size ft <sup>2</sup>	bedrooms	floors	Age	Price
2104	5	1	45	460
1416	3	2	40	232
1534	3	2	30	315
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add  $x_0$ , so to represent  $\theta_0$ 

$$X = \begin{bmatrix} 1 & 2104 & 5 & 1 & 45 \\ 1 & 1416 & 3 & 2 & 40 \\ 1 & 1534 & 3 & 2 & 30 \\ 1 & 852 & 2 & 1 & 36 \end{bmatrix} \quad y = \begin{bmatrix} 460 \\ 232 \\ 315 \\ 178 \end{bmatrix}$$

#### **The Normal Equation**

To obtain the optimal values (minimized) of  $\theta_s$ , Use the following **Normal Equation**:

$$\boldsymbol{\theta} = (\mathbf{X}^{\mathrm{T}} \cdot \mathbf{X})^{-1} \cdot \mathbf{X}^{\mathrm{T}} \cdot \mathbf{y}$$

Where:

- $\theta$ : the set of  $\theta$ s we want to minimize
  - X: the set of features in the training set
  - y: the output values we try to predict
  - X<sup>T</sup>: the transpose of X
  - X<sup>-1</sup>: the inverse of X

In Octave: pinv(X'\*X)\*X' \*y

## **Gradient Descent Vs Normal Equation**

#### *m* training examples, *n* features

#### **Gradient Descent**

- Needs to choose the learning rate (α)
- Needs many iterations
- Works well even when *n* is large

#### Normal Equation

- No need to choose (α)
- Don't need to iterate
- Need to compute (X<sup>T</sup>X), which takes about O(*n*<sup>3</sup>)
- Slow if *n* is very large
- Some matrices (e.g., singular) are non-invertible

**Recommendation**: use the Normal Equation If the number of features in less than 1000, otherwise the Gradient Descent.

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#### **Matrix Vector Multiplication**

$$\begin{bmatrix} 1 & 3 \\ 4 & 0 \\ 2 & 1 \end{bmatrix} \times \begin{bmatrix} 1 \\ 5 \end{bmatrix} = \begin{bmatrix} 16 \\ 4 \\ 7 \end{bmatrix}$$

 $1 \times 1 + 3 \times 5 = 16$  $4 \times 1 + 0 \times 5 = 4$  $2 \times 1 + 1 \times 5 = 7$ 

#### **Matrix Matrix Multiplication**

$$\begin{bmatrix} 1 & 3 & 2 \\ 4 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 3 \\ 0 & 1 \\ 5 & 2 \end{bmatrix} = \begin{bmatrix} 11 & 10 \\ 9 & 14 \end{bmatrix}$$

Multiple with the first column  

$$\begin{bmatrix} 1 & 3 & 2 \\ 4 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 \\ 0 \\ 5 \end{bmatrix} = \begin{bmatrix} 11 \\ 9 \end{bmatrix}$$

Multiple with the second column  $\begin{bmatrix} 1 & 3 & 2 \\ 4 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 10 \\ 14 \end{bmatrix}$ 

#### **Matrix Inverse**

If A is an  $m \times m$  matrix, and if it has an inverse, then

$$\mathbf{A} \times \mathbf{A}^{-1} = \mathbf{A}^{-1} \times \mathbf{A} = \mathbf{I}$$

The multiplication of a matrix with its inverse produce an identity matrix:

$$\begin{bmatrix} 3 & 4 \\ 2 & 16 \end{bmatrix} \times \begin{bmatrix} 0.4 & -0.1 \\ -0.05 & 0.075 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Some matrices do not have inverses e.g., if all cells are zeros For more, please review Linear Algebra

#### **Matrix Transpose**

Example: 
$$A = \begin{bmatrix} 1 & 2 & 0 \\ 3 & 5 & 9 \end{bmatrix}$$
  $A^{T} = \begin{bmatrix} 1 & 3 \\ 2 & 5 \\ 0 & 9 \end{bmatrix}$ 

Let A be an  $m \times n$  matrix, and let  $B = A^T$ Then B is an  $n \times m$  matix, and  $B_{ij} = A_{ji}$  Mustafa Jarrar: Lecture Notes on Linear Regression Machine Learning Birzeit University, 2018

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#### Octave



- Download from <u>https://www.gnu.org/software/octave/</u>
- High-level Scientific Programming Language
- Free alternatives to (and compatible with) Matlab
- helps in solving linear and nonlinear problems numerically

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Online Tutorial <a href="https://www.youtube.com/playlist?list=PLnnr1080Wc6aAjSc50lzzPVWgjzucZsSD">https://www.youtube.com/playlist?list=PLnnr1080Wc6aAjSc50lzzPVWgjzucZsSD</a>

#### **Compute the normal equation using Octave**

Given 
$$X = \begin{bmatrix} 1 & 2104 & 5 & 1 & 45 \\ 1 & 1416 & 3 & 2 & 40 \\ 1 & 1534 & 3 & 2 & 30 \\ 1 & 852 & 2 & 1 & 36 \end{bmatrix}$$
  $y = \begin{bmatrix} 460 \\ 232 \\ 315 \\ 178 \end{bmatrix}$   
In Octave: load X.txt  
load y.txt  
 $C = pinv(X' * X) * X' * y$   
Save  $\theta$ .txt

$$\theta = \begin{bmatrix} 188.4 \\ 0.4 \\ -56 \\ -93 \\ -3.7 \end{bmatrix}$$

These are the values of  $\theta$ s we need to use in our hypothesis function h(x)  $h(x) = \theta_0 + \theta_1 x + \theta_2 x^2 + \theta_3 x^3 + \theta_4 x^4$  $h(x) = 188.4 + 0.4x - 56x^2 - 93x^3 - 3.7x^4$ 

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# **R** (programming language)

Free software environment for statistical computing and graphics that is supported by the R Foundation for Statistical Computing.

R comes with many functions that can do sophisticated stuff, and the ability to install additional packages to do much more.

Download R: <a href="https://cran.r-project.org/">https://cran.r-project.org/</a>

A very good IDE for R is the RStudio: <u>https://www.rstudio.com/products/rstudio/download/</u>

R basics tutorial: https://www.youtube.com/playlist?list=PLjgj6kdf\_snYBkIsWQYcYt UZiDpam7ygg



## **Compute the normal equation using R**

Given
$$X =$$
 $\begin{bmatrix} 1 & 2104 & 5 & 1 & 45 \\ 1 & 1416 & 3 & 2 & 40 \\ 1 & 1534 & 3 & 2 & 30 \\ 1 & 852 & 2 & 1 & 36 \end{bmatrix}$  $y =$  $\begin{bmatrix} 460 \\ 232 \\ 315 \\ 178 \end{bmatrix}$ 

#### In R:

X = as.matrix(read.table("~/x.txt", header=F, sep=","))
Y = as.matrix(read.table("~/y.txt", header=F, sep=","))

```
thetas = solve( t(X) %*% X ) %*% t(X) %*% Y
```

*t*(*X*): is the transpose of matrix X. *solve*(*X*): is the inverse of matrix X.

#### References

[1] Andrew Ng's course about Machine Learning https://www.youtube.com/channel/UCMoXOGX9mgrYNEwpcIQUcag

[2] Sami Ghawi, Mustafa Jarrar: Lecture Notes on Introduction to Machine Learning, Birzeit University, 2018

[3] Mustafa Jarrar: Lecture Notes on Decision Tree Machine Learning, Birzeit University, 2018

[4] Mustafa Jarrar: Lecture Notes on Linear Regression Machine Learning, Birzeit University, 2018