

ENCS431 (DSP)  
Name:

Solution

QUIZ #2

When the input to a causal LTI system is

$$x[n] = -\frac{1}{3} \left(\frac{1}{2}\right)^n u[n] - \frac{4}{3} 2^n u[-n-1]$$

The z-transform of the output is

$$Y(z) = \frac{1+z^{-1}}{(1-z^{-1})(1+\frac{1}{2}z^{-1})(1-2z^{-1})}$$

- Find z-transform of  $x[n]$ ?
- What is the region of convergence (ROC) of  $Y(z)$ ?
- Find the system function of this system  $H(z)$ ? Plot its zero-pole diagram and indicate ROC?
- Is the system stable?

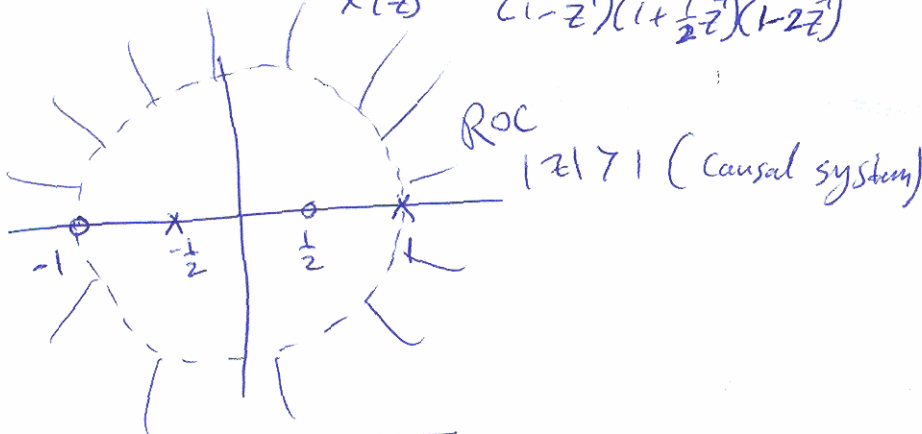
$$(a) X(z) = \frac{-\frac{1}{3}}{1-\frac{1}{2}z^{-1}} + \frac{4/3}{1-2z^{-1}} = \frac{-\frac{1}{3} + \frac{2/3z^{-1}}{1-\frac{1}{2}z^{-1}} + \frac{4}{3} - \frac{2/3z^{-1}}{1-2z^{-1}}}{(1-\frac{1}{2}z^{-1})(1-2z^{-1})} = \frac{1}{(1-\frac{1}{2}z^{-1})(1-2z^{-1})} \quad \frac{1}{2} < |z| < 2$$

(b)  $X(z)$  has two poles at  $z = \frac{1}{2}$  and at  $z = 2$   
 $Y(z)$  has three poles at  $z = 1$ ,  $z = -\frac{1}{2}$ , and  $z = 2$ , therefore the two poles  $z = 1$  and  $z = -\frac{1}{2}$  comes from the system function  $H(z)$ .

Since  $H(z)$  is causal  $\Rightarrow$  its ROC extends from outermost pole to  $\infty$   
 $\Rightarrow$  ROC of  $H(z)$  is  $|z| > 1$

We know, ROC of  $Y(z)$  is the common area of ROC of  $X(z)$  and ROC of  $H(z)$   
 which is  $1 < |z| < 2$ .

$$(c) H(z) = \frac{Y(z)}{X(z)} = \frac{1+z^{-1}}{(1-z^{-1})(1+\frac{1}{2}z^{-1})(1-2z^{-1})} \cdot \frac{(1-\frac{1}{2}z^{-1})(1-2z^{-1})}{1} = \frac{(1+z^{-1})(1-\frac{1}{2}z^{-1})}{(1-z^{-1})(1+\frac{1}{2}z^{-1})}$$



(d) system is unstable since its ROC doesn't include unit circle.