

# Digital Signal Processing (DSP), Fall 2014

## Lecture 1: Introduction,

## Discrete-time signals and systems

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# Part I: Introduction

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- Introduction (Course overview)
- Discrete-time signals
- Discrete-time systems
- Linear time-invariant systems

# General information

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- **Prerequisites:**

Background in advanced calculus including complex variables, Laplace- and Fourier transforms.

- **Required Textbook**

- Discrete-Time Signal Processing,
- Prentice Hall, 2nd Edition
- Alan Oppenheim, Ronald Schafer, John Buck

- **Grading**

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|------------------------------|-----------|
| – Attendance / participation | 5%        |
| – Project                    | 15%       |
| – Quizzes                    | 10%       |
| – <b>Assignments</b>         | <b>0%</b> |
| – Midterm Exam               | 30%       |
| – Final Exam                 | 40%       |

# Useful References

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- [1] Digital Signal Processing, Sanjit H. Mitra. Mc Graw Hill, 3rd Ed. 2006
- [2] Dimitris G. Manolakis and Vinay K. Ingle, Applied Digital Signal Processing, Cambridge University Press, 2011.
- [3] Real-Time Digital Signal Processing, Sen M. Kuo and Bob H. Lee, Wiley, 2001.
- [4] Digital Signal Processing, A. Oppenheim and R. Schaffer, Prentice Hall, 1986 .
- [5] Optimum Signal Processing, S. Orfanidis, MacMillan,

# Useful References

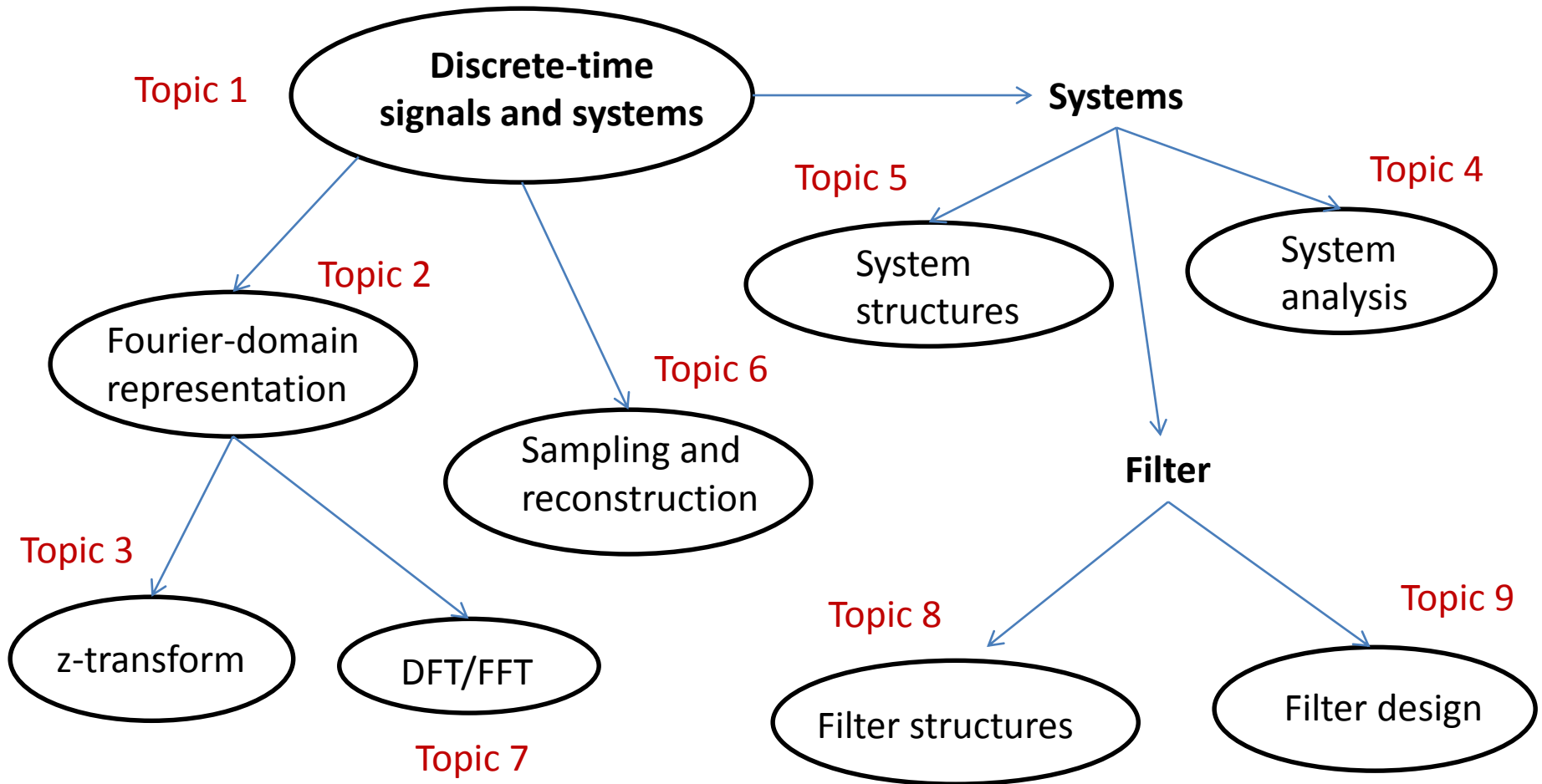
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- [6] Digital Signal Processing: Principles, Algorithms, and Applications, J.G. Proakis and D.G Manolakis. Prentice Hall, 1996
- [7] Digital Signal Processing, R.A. Roberts and C.T. Mullis. Addison-Wesley, 1996
- [8] Matrix Computations, G. Golub, C. Van Loan, Johns Hopkins University Press, 1983.
- [9] MATLAB Reference Guide: High-Performance Numeric Computation and Visualization Software, The MathWorks, Inc., South Natick, MA.

# Course at a glance

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# Course objectives (Part I)

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- ❑ To give the students a comprehension of the concepts of discrete-time signals and systems.
- ❑ To give the students a comprehension of the Z- and the Fourier transform and their inverse.
- ❑ To give the students a comprehension of the relation between digital filters, difference equations and system functions.
- ❑ To give the students knowledge about the most important issues in sampling and reconstruction.

# Course objectives (Part II)

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- ❑ To make the students able to apply digital filters according to known filter specifications.
- ❑ To provide the knowledge about the principles behind the discrete Fourier transform (DFT) and its fast computation.
- ❑ To make the students able to apply Fourier analysis of stochastic signals using the DFT.
- ❑ To be able to apply the MATLAB program to digital processing problems and Presentations.



# Where is DSP

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# DSP is Everywhere

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- Sound applications
  - Compression, enhancement, special effects, synthesis, recognition, echo cancellation,...
  - Cell Phones, MP3 Players, Movies, Dictation, Text-to-speech,...
- Communication
  - Modulation, coding, detection, equalization, echo cancellation,...
  - Cell Phones, dial-up modem, DSL modem, Satellite Receiver,...
- Automotive
  - ABS, GPS, Active Noise Cancellation, Cruise Control, Parking,...

# DSP Application

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- Medical
  - Magnetic Resonance, Tomography, Electrocardiogram,...
- Military
  - Radar, Sonar, Space photographs, remote sensing,...
- Image and Video Applications
  - DVD, JPEG, Movie special effects, video conferencing,...
- Mechanical
  - Motor control, process control, oil and mineral prospecting,...

# What is a signal ?

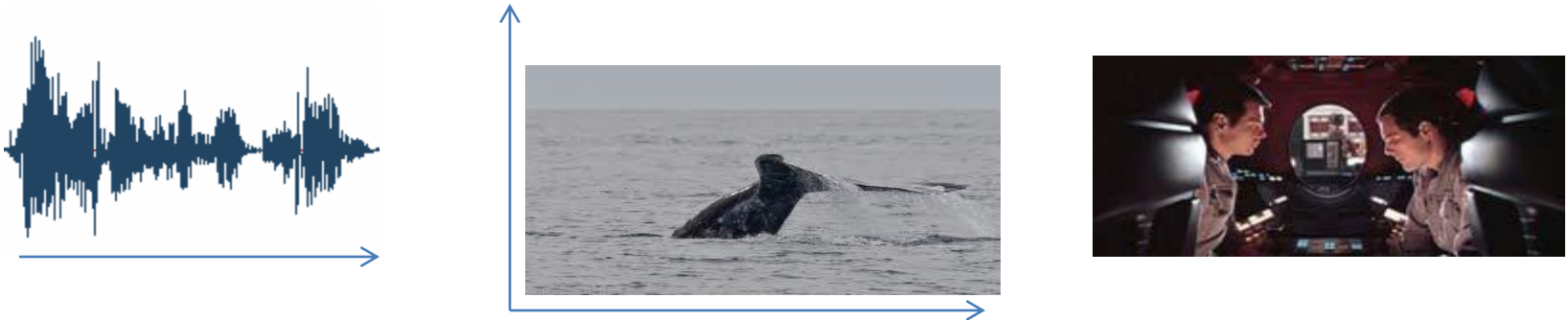
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- ❑ A flow of information
- ❑ (mathematically represented as) a function of independent variables such as time (e.g. speech signal), position (e.g. image), etc.
- ❑ A common convention is to refer to the independent variable as time, although may in fact not.

# Example signals

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- ❑ Speech: 1-Dimension signal as a function of time  $s(t)$ ;
- ❑ Grey-scale image: 2-Dimension signal as a function of space  $i(x,y)$
- ❑ Video: 3 x 3-Dimension signal as a function of space and time  $\{r(x,y,t), g(x,y,t), b(x,y,t)\}$  .

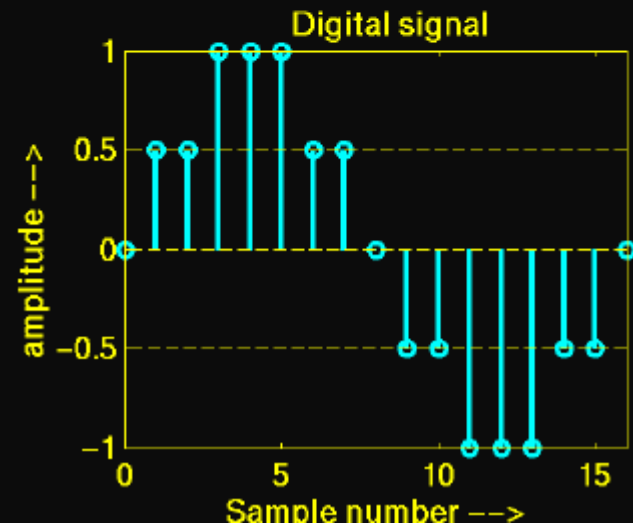
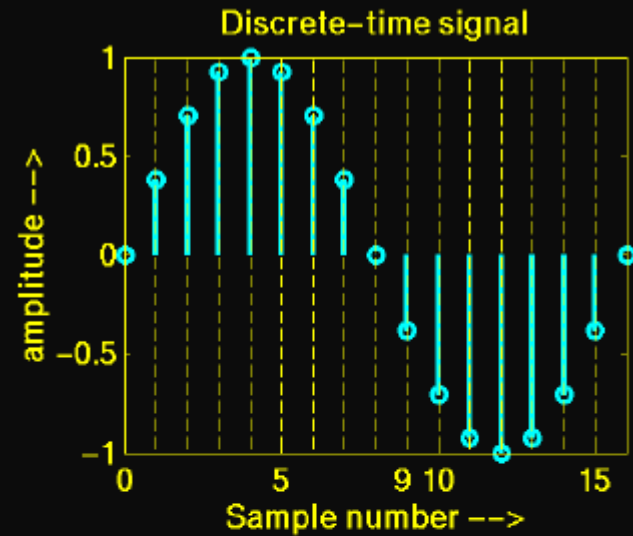
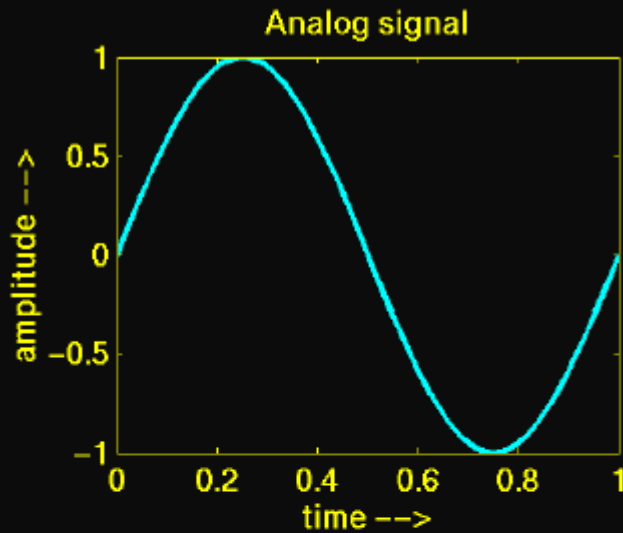


# Types of signals

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- ❑ The independent variable may be either continuous or discrete
  - Continuous-time signals
  - Discrete-time signals are defined at discrete times and represented as sequences of numbers
- ❑ The signal amplitude may be either continuous or discrete
  - Analog signals: both time and amplitude are continuous
  - Digital signals: both are discrete
- ❑ Computers and other digital devices are restricted to discrete time
- ❑ Signal processing systems classification follows the same lines

# Types of signals



# Digital signal processing

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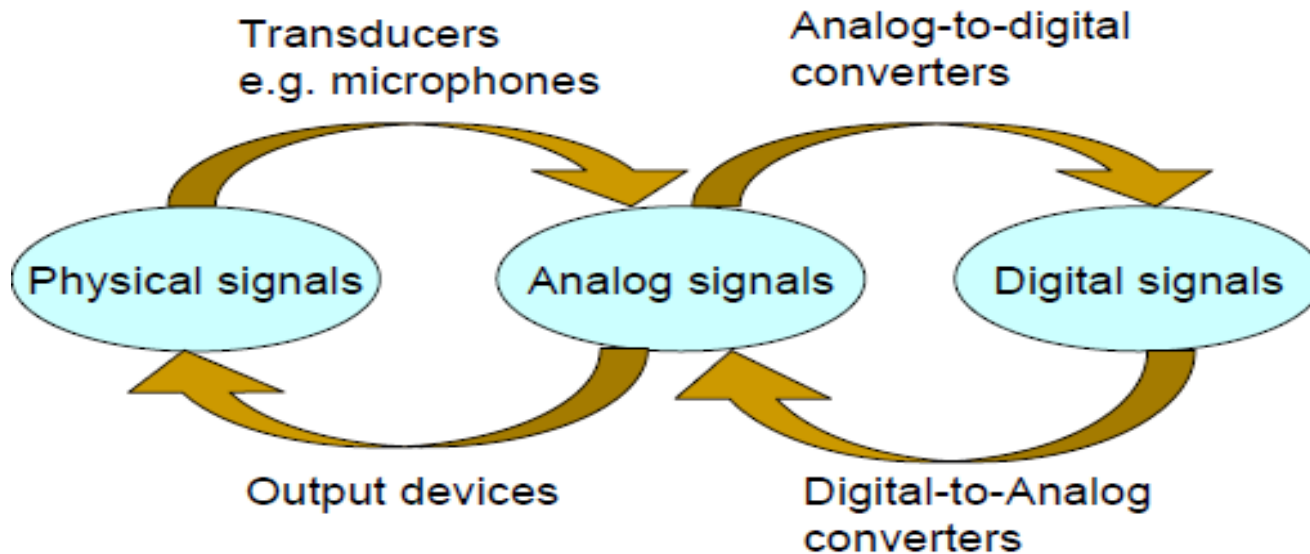
- ❑ Modifying and analyzing information with computers – so being measured as sequences of numbers.
- ❑ Representation, transformation and manipulation of signals and information they contain



# Typical DSP system components

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- ❑ Input lowpass filter to avoid aliasing
- ❑ Analog to digital converter (ADC)
- ❑ Computer or DSP processor
- ❑ Digital to analog converter (DAC)



# Limitations of Analog Signal Processing

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- Accuracy limitations due to
  - Component tolerances
  - Undesired nonlinearities
- Limited repeatability due to
  - Tolerances
  - Changes in environmental conditions
    - Temperature
    - Vibration

# Limitations of Analog Signal Processing

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- Sensitivity to electrical noise
- Inflexibility to changes
- Limited dynamic range for voltage and currents
- Difficulty of implementing certain operations
  - Nonlinear operations
  - Time-varying operations
- Difficulty of storing information

# Pros and cons of DSP

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## **Pros:**

- Easy to duplicate
- Stable and robust: not varying with temperature, storage without deterioration
- Flexibility and upgrade: use a general computer or microprocessor

## **Cons:**

- Limitations of ADC and DAC
- High power consumption and complexity of a DSP implementation: Unsuitable for simple, low power applications
- Limited to signals with relatively low bandwidth

# History of DSP

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- ❑ Prior to 1950's: analog signal processing using electronic circuits or mechanical devices
- ❑ 1950's: computer simulation before analog implementation, thus cheap to try out
- ❑ 1965: Fast Fourier Transforms (FFTs) by Cooley and Tukey
  - make real time DSP possible
- ❑ 1980's: IC technology boosting DSP