

Problem #1:

Type J TC is to be used in a measurement system that provide an output of 2V at 20°C. A solid state sensor will be used to provide reference temp. compensation. the sensor has 3 terminals: supply voltage V_s , output V_T and ground. The output varies $8\text{ mV}/^\circ\text{C}$.

Solution:

J TC with 0°C reference its output 10.78 mV @ 20°C from tables.

$$V_{J_0}(20^\circ\text{C}) = 10.8\text{ mV}.$$

$$\text{overall gain} = \frac{2\text{ V}}{10.8\text{ mV}} = \underline{\underline{185.5}}$$

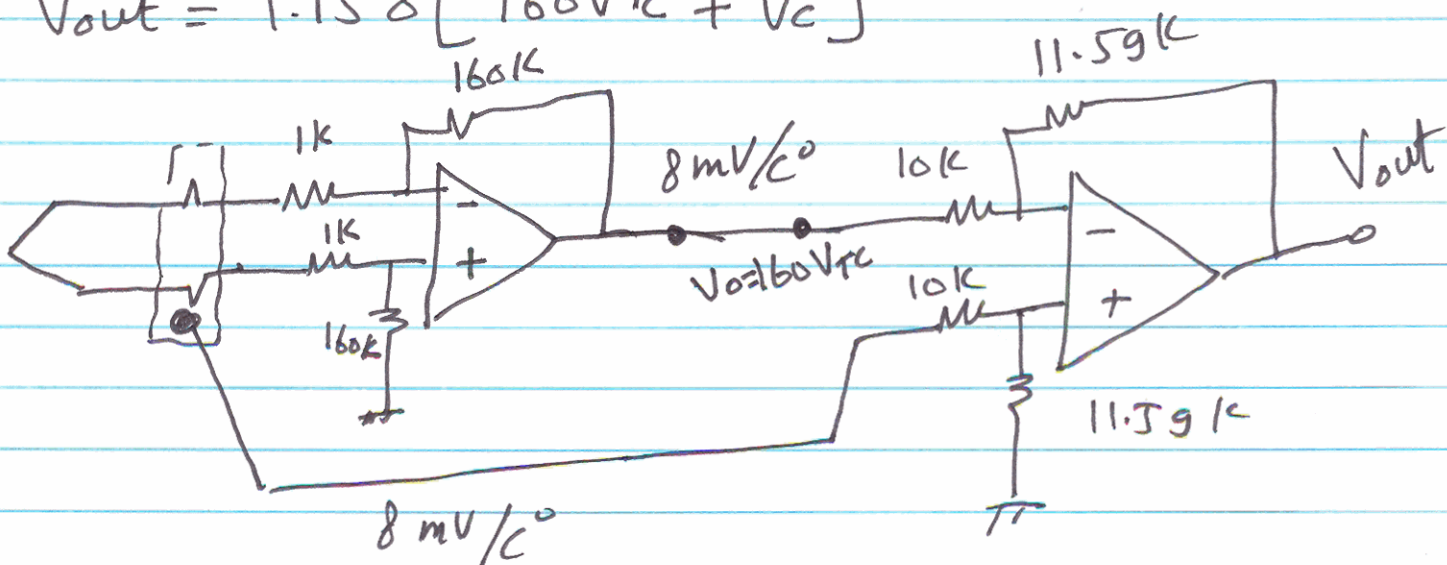
From tables of J TC slope is approx. $50\ \mu\text{V}/^\circ\text{C}$.
slope of sensor $8\text{ mV}/^\circ\text{C}$.

$$\frac{8\text{ mV}/^\circ\text{C}}{50\ \mu\text{V}/^\circ\text{C}} = 160 \text{ times larger}$$

to make the rest of the gain

$$\frac{185.5}{160} = \underline{\underline{1.159}}$$

$$V_{\text{out}} = 1.158 [160V_{TC} + V_c]$$



Problem 2:

Temperature for a plating operation must be measured for control within a range of $500 - 600 \text{ }^\circ\text{F}$. Develop measuring system that scales this temperature into 0 to 5V for an input to 8-bit ADC; measurement must be within $\pm 1\%$.

Solution:

Range: $260 - 315.6^\circ\text{C}$

Choosing the sensor: TC & RTD could fit to the problem

let us choose J TC with reference $25 \pm 5^\circ\text{C}$ to satisfy the accuracy. Correction circuit must be used to compensate the reference voltage.

From tables:

$$\text{For } 260^\circ\text{C}; V_{J_{25}}(260) = V_{J_0}(25) - V_{J_0}(25)$$

$$V_{J_{25}}(260) = 12.84 \text{ mV}$$

$$V_{J_{25}}(315.6) = 15.9 \text{ mV}$$

$$V_{\text{ADC}} = m V_{J_{25}} + V_0$$

$$0 = m(12.8 \text{ mV}) + V_0 \quad // \quad m = 1634$$

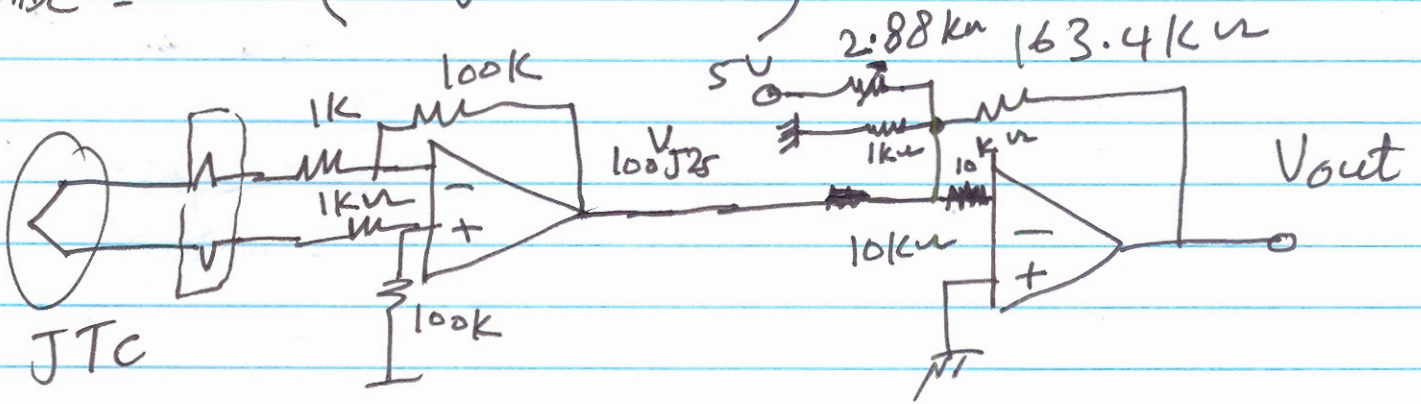
$$5 = m(15.9 \text{ mV}) + V_0 \quad // \quad V_0 = -21$$

$$V_{\text{ADC}} = 1634 V_{J_{25}} - 21$$

gain is so large, we make it 2 stages

$$100 \times 16.34$$

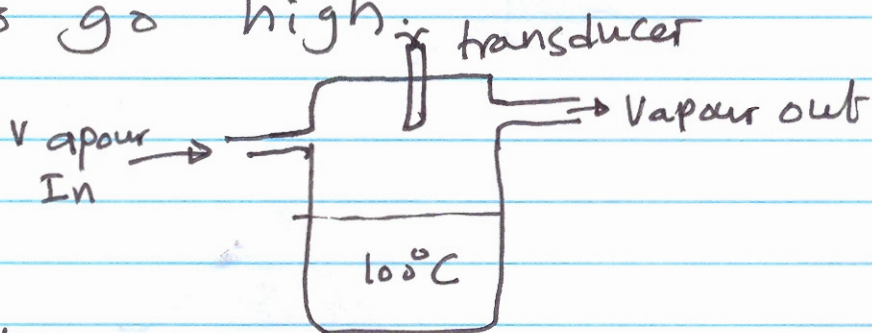
$$V_{ADC} = 16.34(100 V_{J25} - 1.29)$$



Problem #3:

Vapour flows through chamber containing liquid at 100°C . Control system will regulate the Vapour temperature, so a measurement must be provided to convert $50 - 80^{\circ}\text{C}$ into 0 to 2V.

the error should not exceed 1°C .
If the liquid level rises to the tip of the transducer, the temp. will suddenly rise to 100°C . The event should cause an alarm to go high.



Solution:

Selection of Sensor RTD is the best choice.

Let us choose RTD with the following Spec.

$$R @ 65^{\circ}\text{C} = 150\Omega$$

$$\alpha = .004/^{\circ}\text{C}$$

$$P_D = 30\text{mW}/^{\circ}\text{C}$$

$$\textcircled{a} \text{ @ } 50^{\circ}\text{C} \text{ RTD} = 150 [1 + .004 [50 - 65]] = 141\Omega$$

$$\textcircled{b} \text{ @ } 80^{\circ}\text{C} \text{ RTD} = 159\Omega$$

$$\textcircled{c} \text{ @ } 100^{\circ}\text{C} \text{ RTD} = 171\Omega$$

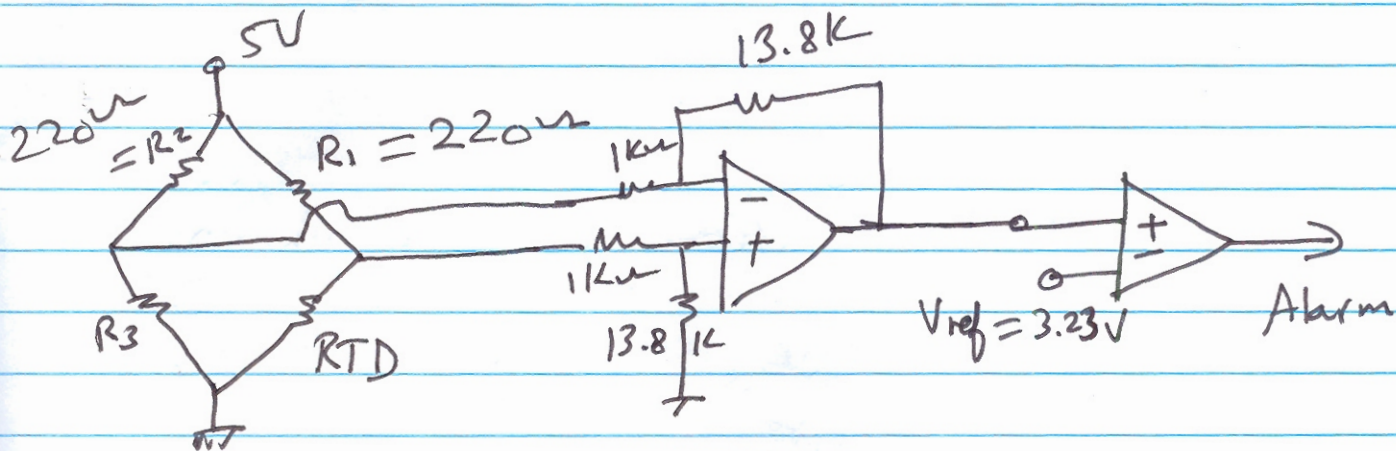
For 1°C error because of Self-heating
we can find max. current

$$P = P_D \Delta T = 30\text{mW}/^{\circ}\text{C} \times 1^{\circ}\text{C} = 30\text{mW}$$

max. Current

$$I = \sqrt{\frac{P}{R}} = \sqrt{\frac{30}{159}} = 13.7 \text{ mA}$$

Bridge should be used for RTD



Value of R_1 is determined by current $< 13.7 \text{ mA}$

$$V = IR = 13.7 \times 159 = 2.17 \text{ V}$$

$$R_1 = (5 - 2.17) / 159 = 206.5 \Omega$$

Let us choose $R_1 = 220\Omega$

To null the bridge @ 50°C we will make
 $R_2 = 220\Omega$ & $R_3 = 141\Omega$

$$\text{@ } 50^\circ\text{C} \Rightarrow \Delta V = 5 \left(\frac{141}{220+141} - \frac{141}{220+141} \right) = 0$$

$$\text{@ } 80^\circ\text{C} \Rightarrow \Delta V = 5 \left(\frac{159}{220+159} - \frac{141}{220+141} \right) = .1447 \text{ V}$$

$$\text{@ } 100^\circ\text{C} \Rightarrow \Delta V = .2338 \text{ V}$$

$$\text{gain needed} = \frac{2}{.1447} = \underline{\underline{13.8}}$$

$$V_{ref} = 13.8 \times .2338 = 3.23 \text{ V}$$

Problem # 4:

Develop a system that turns an alarm LED when the temperature in a chamber reaches $10 \pm .5^\circ\text{C}$. When the temperature drops below 8°C the LED should be turned off.

Solution:

it looks hysteresis comparator

because we are interested just in 2 temperatures Thermistor is the best choice.

we choose thermistor; $P_D = 5 \text{ mW}/^\circ\text{C}$.

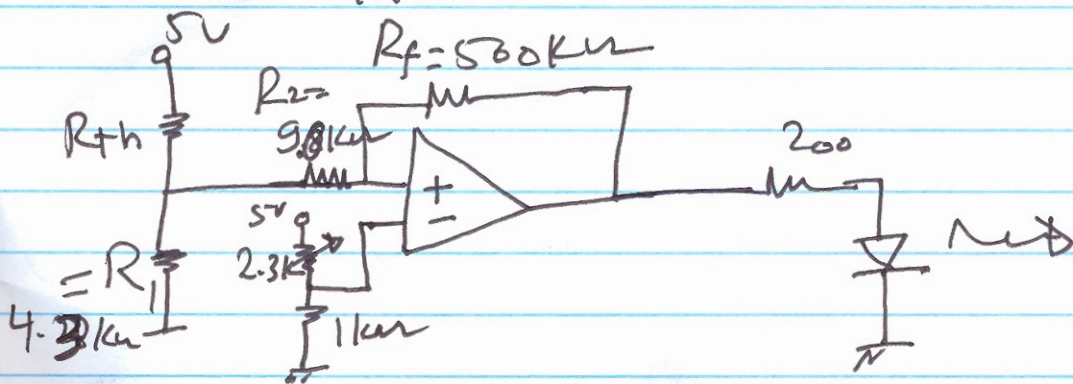
$$R_{th}|_{10^\circ\text{C}} = 10 \text{ k}\Omega; R_{th}|_{8^\circ\text{C}} = 11 \text{ k}\Omega$$

$\pm .5^\circ\text{C}$ requirement means that self heating must be kept below $\pm .5^\circ\text{C}$.

to be sure let us use $.25^\circ\text{C}$.

$$P = P_D \cdot \Delta T = 5 \text{ mW}/^\circ\text{C} \times .25^\circ\text{C} = 1.25 \text{ mW}$$

$$I = \sqrt{\frac{1.25 \text{ mW}}{10 \text{ k}\Omega}} = .354 \text{ mA}$$



$$V_{Th} = I R_1 = .35 \text{ mA} \times 10 \text{ k}\Omega = 3.5 \text{ V}$$

$$R_1 = \frac{5 - 3.5}{.35} = 4.28 \text{ k}\Omega \text{ we will use } 4.3 \text{ k}\Omega$$

For 10°C ; $V_D = 1.5\text{V}$

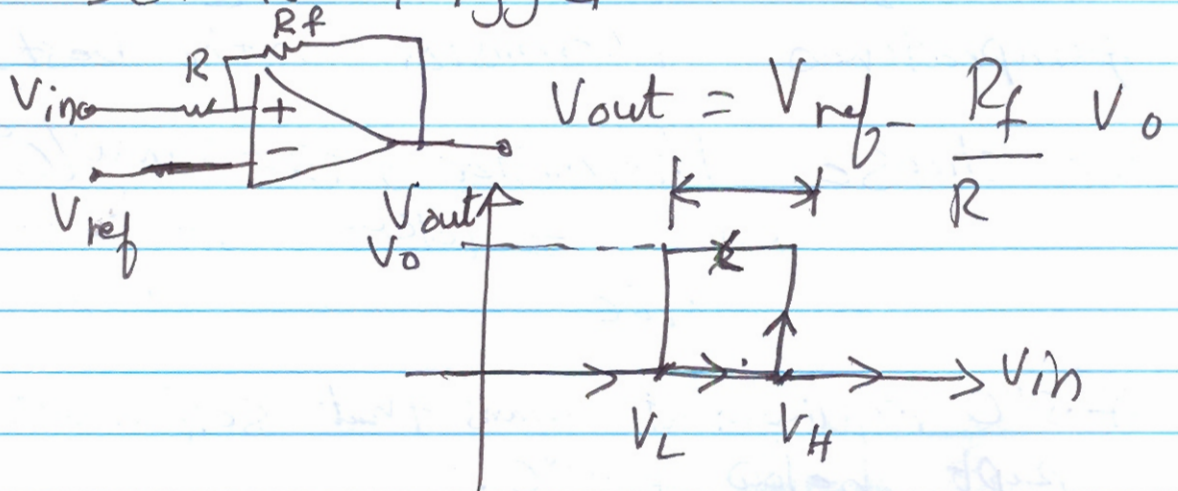
" 8°C ; $V_D = 1.41\text{V}$

difference is $.09\text{V}$ required for hysteresis

hysteresis $\left\{ \frac{R_2}{R_f} \times 5 = .09 \Rightarrow \frac{R_2}{R_f} = .018 \right.$

choose $R_f = 50\text{k}\Omega$; $\Rightarrow R_2 = 9\text{k}\Omega$

Note: Schmitt trigger



Solution Interfacing

2013/2014



ANSWER BOOKLET

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| Student : | Number : | |
| Course : | Department : | Number : |
| Division : | Instructor : | |
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For Instructor's Use

| Question | Grade |
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