

Self generating / natural  
no need for power supply

natural sensor need a power supply

## Passive and active sensors

Like Thermocouple

### Passive or self-generating

- Directly generate an electrical signal in response to an external stimuli without the need for an external power supply

- Output signal power comes from the stimulus

- Examples

examples

- Thermocouple
- Piezoelectric sensors

### Active or modulating

- These sensors require external power supply or an excitation signal for their operation

- Output signal power comes from the power supply

- Examples

حساسات تحتاج الى طاقة مع الحرارة  
with Temp.

- Thermistors
- Chemo-resistors



LDR → active sensor. needs power.  
with light

continuous

discrete.

## Analog and digital sensors

### Analog sensors

- Provide a signal that is continuous in both its magnitude and temporal or spatial content

- Most of the physical measurands are analog in nature

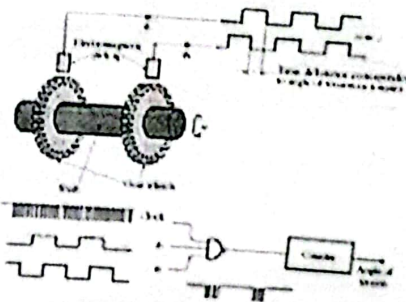
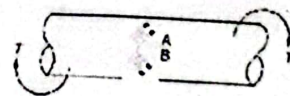
- Examples: Temperature, displacement, light intensity

### Digital sensors

- Their output takes the form of discrete steps or states

- Digital signals are more repeatable, reliable and easier to transmit

- Examples: Shaft encoder, contact switch



Deflectm → الی لکھنے لگی  
Null mode → الی لکھنے لگی

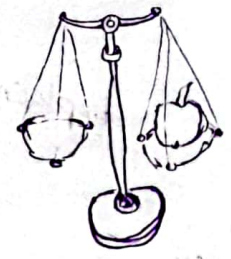
# Operational modes

- ▶ **Deflection mode** → الی لکھنے لگی فکرہ، پکیزان
  - The sensor or instrument generates a response that is a deflection or a deviation from the initial condition of the instrument
  - The deflection is proportional to the measurand of interest
- ▶ **Null mode** → الی لکھنے لگی معیاری
  - The sensor or instrument exerts an influence on the measured system so as to oppose the effect of the measurand
  - The influence and measurand are balanced (typically through feedback) until they are equal but opposite in value, yielding a null measurement



Benefits & disadvantages

Null mode instrumentation can produce very accurate measurements, but are not as fast as deflection instruments  
→ used in Widstand bridge.



زمرہ وارہ

# Mechanical measurands

- ▶ **Displacement**
  - Resistive sensors
  - Capacitive sensors
  - Inductive sensors
- ▶ **Force and acceleration**
  - Strain gauges ⇒ has a R/GF =  $\frac{\Delta R}{R}$
  - Cantilever beam-based sensors

الزمرہ

$$GF = \frac{\Delta R}{R} \rightarrow \text{المقاومہ}$$

$$\frac{\Delta L}{L} \rightarrow \text{Stress}$$



مثال حساسية في الاستجابة  
 زسجل بعد كل تغير في الاستجابة

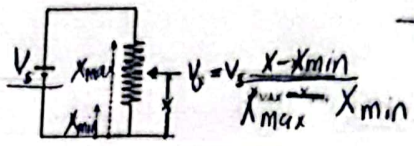
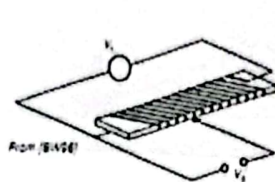
$$V_o = \frac{X - X_{min}}{X_{max} - X_{min}} V_s$$

# Resistive displacement sensors

- ▶ A resistance with a movable contact (a potentiometer) may be used to measure linear or rotational displacements
  - A known voltage is applied to the resistor ends
  - The contact is attached to the moving object of interest
  - The output voltage at the contact is proportional to the displacement

## Notes

- Restrictions
- Non-linearities as a result of loading effects
  - Resolution due to limited number of turns per unit distance
  - Contact wear as a result of frictions



العلاقة بين  
 Position  
 Input Voltage &  
 Output Voltage

$$V_o = V_s \frac{X - X_{min}}{X_{max} - X_{min}}$$

تغير اقسام displacement

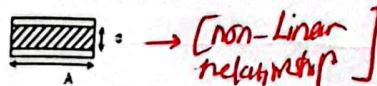
## Capacitive Sensors

قانون  
 القياس

# Capacitive displacement sensors

- ▶ The capacitance of a parallel plate capacitor is

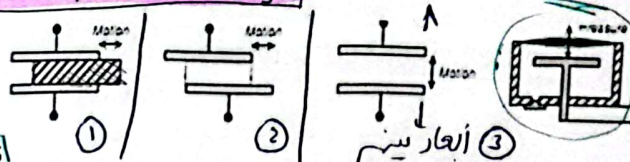
$$C = \frac{\epsilon_0 \epsilon_r A \epsilon_{eq}}{\text{distance}} \quad C = \frac{\epsilon_0 \epsilon_r A}{d}$$



[non-linear relationship]

- d is the separation between the plates, A is the area of the plates,  $\epsilon_0$  is the permittivity of air and  $\epsilon_r$  is the relative permittivity of the dielectric
- ▶ A moving object is attached to the dielectric or the plates to generate capacitance changes

تغير اقسام في  
 C عن طريق  
 العبا في C عند  
 حركته  
 motion  
 بتغير قيمته ل C ومنها  
 بعد اعمل استماع  
 للمركه

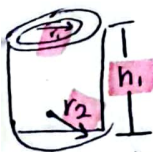


## Notes

- Variable distance (d) sensors operate over a range of a few millimeters
- Cross-sensitivity to temperature and humidity (specially if the dielectric is air)
- Capacitive sensors are also commonly used to measure pressure
- "Condenser" microphones measure changes in air pressure of incoming sound waves

Example on Capacitive Sensors

How to Find Cap when A is cylindrical  
 $C = \frac{2\pi h \epsilon_0 \epsilon_r}{\ln(r_2/r_1)}$



الطريقة الثالثة  
 اعمل overlap Area  
 الطريقة الثالثة اعرفي ل d

why touch screen uses just finger? finger is capacitive

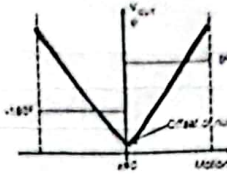
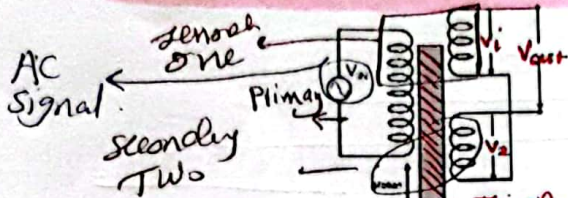
مربع ثالثة لقياس العلاقة

# Inductive displacement sensors

Screen needs capacitor sensor

## Linear Variable Differential Transformer (LVDT)

Motion of a magnetic core changes the mutual inductance of two secondary coils relative to a primary coil



Linear output Vout of core displacement

This core change coupling of secondary 1 & 2

- Primary coil voltage:  $V_s \sin(\omega t)$
- Secondary coil induced emf:  $V_1 = k_1 \sin(\omega t + \phi)$  and  $V_2 = k_2 \sin(\omega t + \phi)$
- $k_1$  and  $k_2$  depend on the amount of coupling between the primary and the secondary coils, which is proportional to the position of the coil
- When the coil is in the central position,  $k_1 = k_2 \Rightarrow V_{OUT} = V_1 - V_2 = 0$  → #1
- When the coil is displaced  $x$  units,  $k_1 \neq k_2 \Rightarrow V_{OUT} = (k_1 - k_2) \sin(\omega t + \phi)$  → #2
- Positive or negative displacements are determined from the phase of  $V_{OUT}$

<https://www.elprocus.com/lvdt-working-principle-construction-types-applications-advantages-and-disadvantages/>

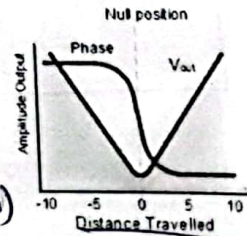
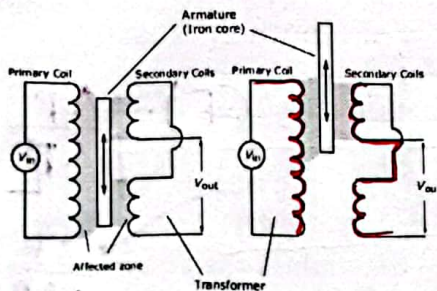
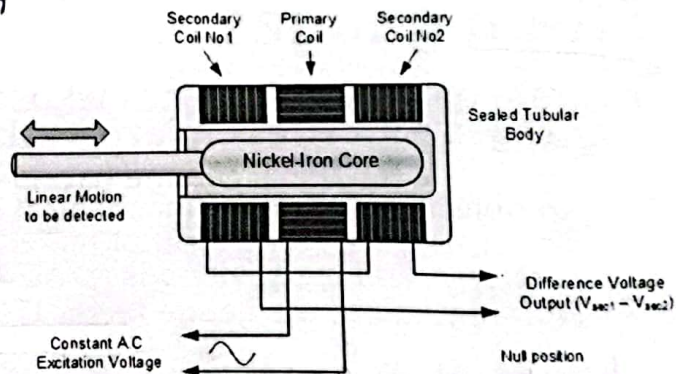
<https://www.fierceelectronics.com/components/modern-lvdt-new-applications-air-ground-and-sea>

Aseel Deck

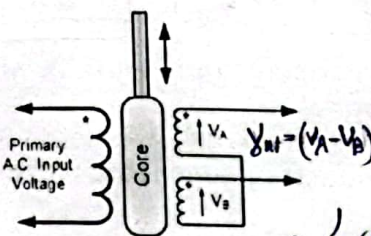
she is cute. I like her. hehehe.

بكون جوال هو احد transformer بقول  
من التيار وكو ليعتد AC له

magnetic effect



Long time  
resistive



output voltage

direction distance

Engineer A

[بالتالي او العكس]

~~...~~

# Inductive displacement sensors (cont)

## LVDT Characteristics

- Typical LVDTs run at 5V, 2kHz
- LVDTs can measure from mm down to  $\mu\text{m}$
- Due to small variations in the windings, a small residual voltage appears at the output when the coil is in the central position

## Advantages of the LVDT over other displacement sensors

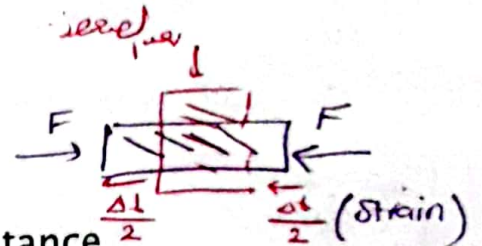
- No mechanical wear ensures a long life
- Complete electrical isolation
- DC versions with integrated oscillators are available



Stress ب  $\mu\text{m}/\text{A}$   
 strain  
 plastic region  
 سنيون

## Strain gauges

stress =  $F/A$



Strain gauges are devices whose resistance changes with stress (piezo-resistive effect)

- Strain is a fractional change ( $\Delta L/L$ ) in the dimensions of an object as a result of mechanical stress (force/area)
- The resistance  $R$  of a strip of material of length  $L$ , cross-section  $A$  and resistivity  $\rho$  is  $R = \rho L/A$
- Differentiating, the gauge factor  $G$  becomes  $(GF) = \frac{\Delta R}{R} \frac{L}{\Delta L}$

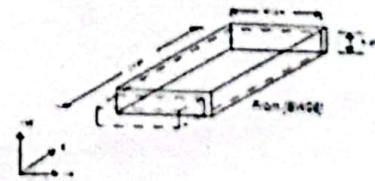
$$\frac{\Delta R}{R} = \frac{\Delta L}{L} - \frac{\Delta A}{A} - \frac{\Delta \rho}{\rho} = (1+2\nu) \frac{\Delta L}{L} - \frac{\Delta \rho}{\rho} = G = \frac{\Delta R/R}{\Delta L/L} = (1+2\nu) + \frac{\Delta \rho}{\rho \Delta L}$$

GEOMETRIC EFFECT
PIEZO-RESISTIVE EFFECT

Where  $\nu$  is the Poisson's ratio ( $\nu \approx 0.3$ ), which determines the strain in directions normal to  $L$

- In metal foil gauges, the geometric term dominates ( $G \approx 2$ )
- In semiconductor gauges, the piezo-resistive term dominates ( $G \approx 100$ )

$\frac{\Delta P}{\Delta L P}$  Poisson's ratio



Piezoresistive material  
 د تغییر نسبتاً و استرس  
 لفره و استرس

change  $\frac{\Delta R}{R} = \text{Strains}$

$R = \frac{\rho \cdot L}{A \cdot \rho}$

لا افریح کن  $\frac{\Delta R}{R}$  لفره و استرس  
 ای ای افریح کن  $\frac{\Delta R}{R}$  لفره و استرس  
 Integrated stress bord

$GF = \frac{\Delta R/R}{\Delta L/L}$

change  $\frac{\Delta R}{R}$  استرس  
resistance

$\Rightarrow$  Semicond. یعنی GF  
 در تگون باغاره تگن لفره و استرس  
 اما تگن  $\frac{\Delta R}{R}$  مافریه vertical  
 افریح 1.6

$GF = \frac{\Delta R/R}{\Delta L/L}$       Strain =  $\Delta L/L$

Strain =  $160 \text{ mm/m} = 0.16$

For  $GF_{\text{meg}} = \frac{\Delta R/R}{\Delta L/L} \Rightarrow \frac{\Delta R}{R} = GF_{\text{meg}} (\Delta L/L)$

$\frac{\Delta R}{R} = \frac{2.13}{160} \times 10^{-3}$

$\Delta R = 40.896$

For  $GF_{\text{semic}} = \frac{\Delta R/120}{0.16} = -162$

$\frac{\Delta R}{120} = -162 \times 0.16$

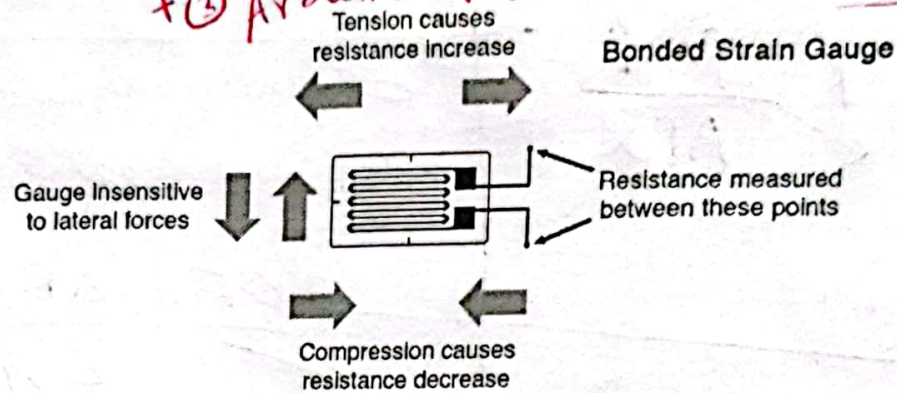
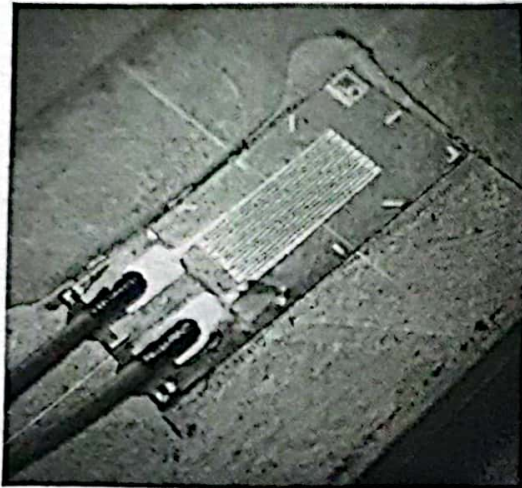
$\frac{\Delta R}{120} = -25.92$

$\Delta R = 3091.2$

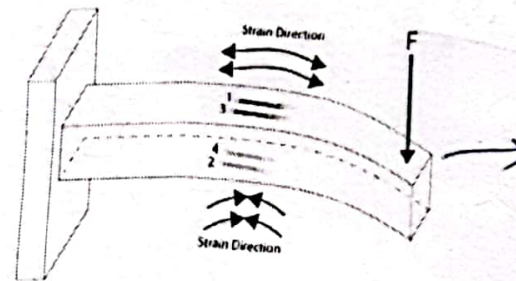
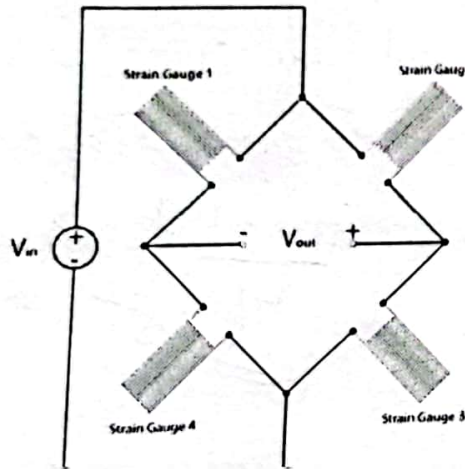
+ ① load cell  
+ ③ conditioning circuit → Bridge + Amplification

### How Strain Gauges Work?

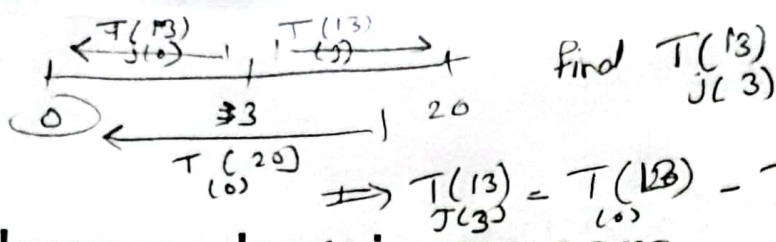
+ ② Arduino + LCP → ميزان



[https://www.youtube.com/watch?v=LRd3W\\_p8PJ4](https://www.youtube.com/watch?v=LRd3W_p8PJ4)



صاف ننه  
ای فرجانا یا  
الذکتر، کثیبه ای  
خود لجه



'low bit' not used

arr

# Thermoelectric sensors

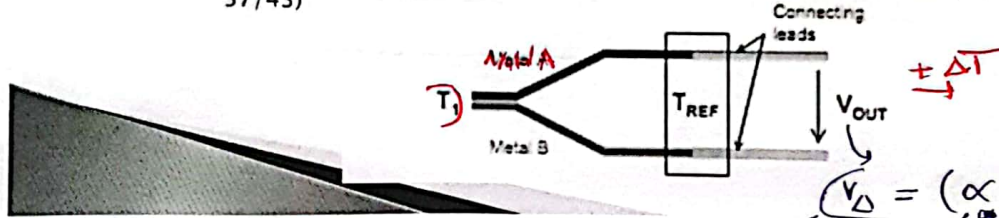
Seebeck عالم اسمه

- بجيب نويس مختلفات عند الجوار كل وحدة حدها  $\alpha$  تكاثره فيها، ليه  $\Delta T$

▶ **The Seebeck effect** → When a pair of dissimilar metals are joined at one end and there is a temperature difference between the joined ends and the open ends, thermal emf is generated, which can be measured in the open ends
- ▶ **The Peltier effect**

  - When a current passes through the junction of two different conductors, heat can be either absorbed or released depending on the direction of current flow
- ▶ **Thermocouples**

  - Based on the Seebeck effect
  - Open ends must be kept at a constant reference temperature  $T_{REF}$
  - A number of standard TCs are used
  - These are denominated with different letter codes: T, J, K, S, R...
    - i.e., type J (the most popular) is made of Iron and Constantan (Cu/Ni alloy: 57/43)



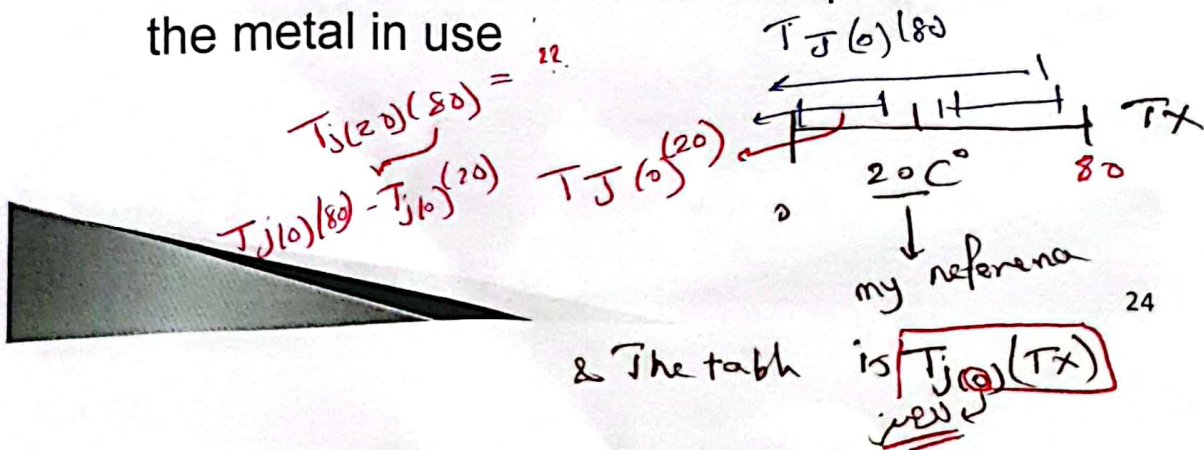
$$V_{\Delta} = (\alpha_A - \alpha_B)(T_1 - T_2)$$

Positive ← negative  
will produce very large  $\Delta V$

$$\Delta V = (\alpha_A - \alpha_B)(T_A - T_B)$$

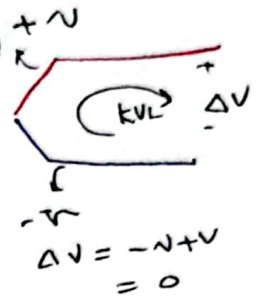
## Thermocouples

- Based on the Seebeck effect
- When any conductor is subjected to a thermal gradient, it will generate a voltage
- The magnitude of the effect depends on the metal in use





- To measure the generated voltage we need to connect another conductor
- This conductor also experiences the Seebeck effect and its voltage tends to oppose the original
- So the conductor used to measure the voltage must be different *the meaning of it.*
- A small difference voltage can be made available by use of dissimilar metals
- Difference increases with temperature, and can typically be between 1 and 70  $\mu\text{V}/^\circ\text{C}$



\* if my table is reference to (0) & i want reference from (20) (80)  
 Then first

$T_j(20)$  ←  $J(0)$        $T_j(80)$  ←  $J(20)$        $T_j(80)$  ←  $J(20)$   
 ←  $J(0)$       ←  $J(20)$       ←  $J(20)$

Answer

$$T_{j(20)}(80) = T_{j(0)}(80) - T_{j(0)}(20)$$

- A Thermocouples measure the temperature
- difference between two points and not the absolute temperature
  - The relationship between the temperature difference and the output voltage of a thermocouple is nonlinear and is approximated by polynomial:

$\Delta T$  &  $\Delta V$   
 is not linear.

$$\Delta T = \sum_{n=0}^N a_n v^n \rightarrow \neq 1$$

To achieve accurate measurements the equation is usually implemented in a digital controller or stored in a look-up table

I appreciate

<https://srdata.nist.gov/its90/download/download.html>

[https://www.nist.gov/jlap/sbaa274/sbaa274.pdf?ts=1602672527665&ref\\_url=https%253A%252F%252Fwww.gob.gov%252F](https://www.nist.gov/jlap/sbaa274/sbaa274.pdf?ts=1602672527665&ref_url=https%253A%252F%252Fwww.gob.gov%252F)

## Advantages and Disadvantages

- They are simple, rugged, need no batteries, measure over very wide temperature ranges
- The main limitation is accuracy: System errors of less than  $1^{\circ}\text{C}$  can be difficult to achieve

hazardous conditions  
Need no batteries.

السفوف

~~السفوف~~

## Applications

- Thermocouples are most suitable for measuring over a large temperature range, up to  $1800^{\circ}\text{C}$
- These are widely used in the steel industry, heating appliances, manufacturing of electrical equipments like switch gears etc

# Thermistor (Thermo resistor)

مقاومة حرارية

عشان نقيس لغير على المقاومة لازم نستخدم voltage و current

فرق مقاومة بولدفولت بالسه لتغيره  $\Delta RT$

A thermistor is a type of resistor with resistance varying according to its temperature. The resistance is measured by passing a small, measured direct current through it and measuring the voltage drop produced.

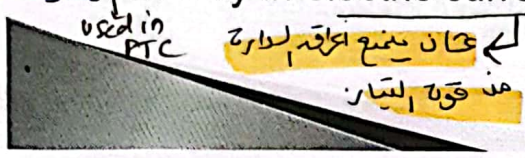
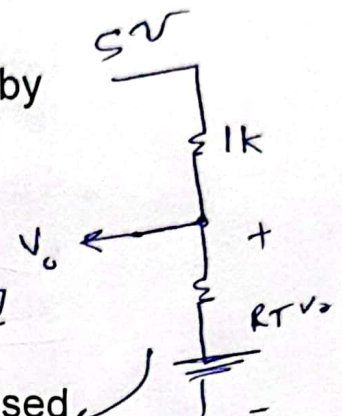
There are basically two broad types

زيادة درجة الحرارة المقاومة بتقل

1. **NTC** Negative Temperature Coefficient used mostly in temperature sensing

زيادة درجة الحرارة المقاومة بتزيد

2. **PTC** Positive Temperature Coefficient used mostly in electric current control.



The Thermistor.

using  $V = IR$

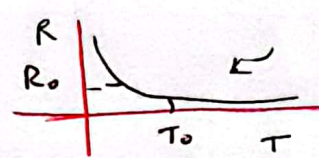
$$V = \frac{RT}{RT + 1k} \times 5V$$

كل ما تغيرت R بتغير RT

**NTC** thermistor is one in which the zero-power resistance decreases with an increase in temperature

constant  $B$   $\left( \frac{1}{T} - \frac{1}{T_0} \right)$

$$R_T = R_0 \exp \left[ B \left( \frac{1}{T} - \frac{1}{T_0} \right) \right]$$



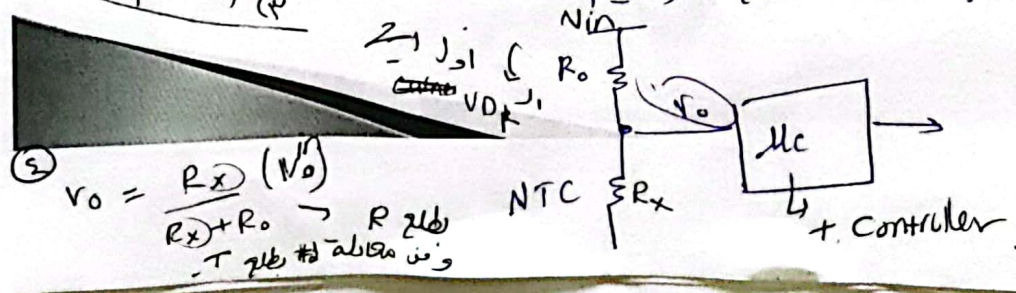
Thermistors ("thermally sensitive resistor")

The material is a semiconductor

A composite of a ceramic and a metallic oxide (Mn, Co, Cu or Fe)

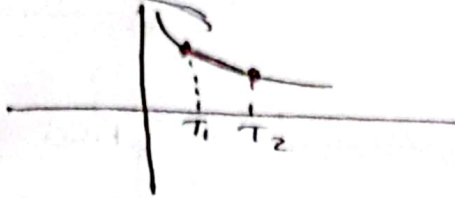
A **PTC** thermistor is one in which the zero-power resistance increases with an increase in temperature

عندى NTC اشارة من (0-50) c و اعلى ل circuit



$$V_0 = \frac{R_x}{R_x + R_0} (V_0)$$

منه معادلة  $R$  بتغير  $T$



- Assuming, as a first-order approximation, that the relationship between resistance and temperature is linear, then:

→  $\Delta R = k\Delta T$  *one way of linearization.*

where

- $\Delta R$  = change in resistance
- $\Delta T$  = change in temperature
- $k$  = first-order temperature coefficient of resistance
- ✗ For PTC  $k$  is positive while negative for NTC



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## Advantages and Disadvantages

- Thermistors, since they can be very small, are used inside many other devices as temperature sensing and correction devices
- Thermistors typically work over a relatively small temperature range, compared to other temperature sensors, and can be very accurate and precise within that range

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# Applications

- 1. PTC thermistors can be used as current-limiting devices for circuit protection, as replacements for fuses. Current through the device causes a small amount of resistive heating. This creates a self-reinforcing effect that drives the resistance upwards
- 2. PTC thermistors can be used as heating elements in small temperature-controlled ovens. As the temperature rises, resistance increases, decreasing the current and the heating, resulting in a steady state
- NTC thermistors are used as resistance thermometers in low-temperature measurements of the order of 10 K.
- NTC thermistors can be used as inrush-current limiting devices in power supply circuits. They present a higher resistance initially which prevents large currents from flowing at turn-on, and then heat up and become much lower resistance to allow higher current flow during normal operation.
- NTC thermistors are regularly used in automotive applications.
- 3. Thermistors are also commonly used in modern digital thermostats and to monitor the temperature of battery packs while charging.

PTC thermistors

Fuses → to prevent short circuits  
عرق السيار

كل طرازه غير ارضه  
بيزاد و المقاومة  
التي



بفصلنا نلاحظ ان  
R تزداد مع T

RTDs → Metals

Thermistor → Semiconductor  
مع عكس اتجاه  
المعادلة

## RTD Resistance Temperature Detectors (RTDs)

- Resistance Temperature Detectors (RTD), as the name implies, are sensors used to measure temperature by correlating the resistance of the RTD element with temperature
- As they are almost invariably made of platinum, they are often called platinum resistance thermometers (PRTs)

$$R_T = R_0 (1 + \alpha (T - T_0))$$

$$R(20) = 7$$

$$R(85) = ??$$

$$R_T = R_0 (1 + \alpha (T - T_0))$$

$$= 7 (1 + 0.004043 (85 - 20))$$

الخصائص التي تتميز بها (characteristic) Linear

Based on materials whose resistance changes in accordance with temperature

- Resistance Temperature Detectors (RTDs)
  - The material is a metal
    - Platinum, Nickel, Copper are typically used
  - Positive temperature coefficients

$$R_T = R_0 [1 + \alpha_1 T + \alpha_2 T^2 + \dots + \alpha_n T^n] \approx R_0 [1 + \alpha_1 T]$$

$$\Rightarrow R_T \approx R_0 [1 + \alpha T]$$

0.4

المعادلة العامة للمعادلة

$$R(T) = R(T_0) [1 + \alpha(T - T_0)]$$

المعادلة العامة للمعادلة  
 $y - y_0 = m(x - x_0)$   
 من صيغة المعادلة



## Construction

Typical RTD Design  
 coiled resistance element

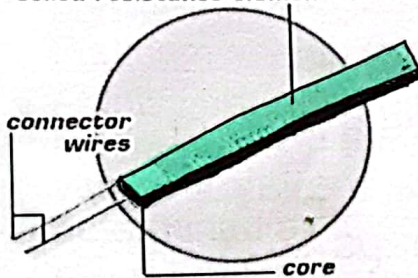
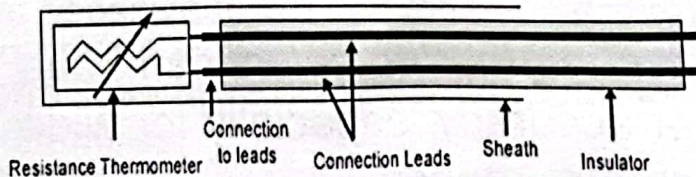


Image obtained from [www.omega.com](http://www.omega.com)

Common Resistance Materials for RTDs:

- Platinum (most popular and accurate)
- Nickel
- Copper
- Tungsten (rare)

$$m_{avg} = \frac{\text{max out}}{\text{sensitivity}}$$



$$S_{NR} = 20 \log \left( \frac{\text{out}}{\text{noise}} \right)$$

$$\begin{aligned} 4V &\rightarrow 10 \\ X &\rightarrow 7.5 \end{aligned}$$

$$\Rightarrow X = \frac{4 \times 7.5}{10} \Rightarrow \underline{3k}$$

$$\begin{aligned} 10 &\rightarrow 100 \times 10^{-38} \\ 7.5 &\rightarrow X \end{aligned}$$

$$X = \frac{7.5 \times 0.1}{10}$$

# Semiconductor Thermometer Devices

TMP35, TMP36

IC + VCC + ground  
V<sub>out</sub> | طول منحنى

مراجعة  
 \*  
 -

- Semiconductor thermometers are usually produced in the form of ICs, Integrated Circuits with very high linearity.
- These devices have temperature measurement ranges that are small compared to thermocouples and RTD, but, they can be quite accurate and inexpensive and very easy to interface with other electronics for display and control.

مواد تتأثر بدرجة الحرارة [ Thermocouples, RTD, Thermistors ]  
 كنا زمان نحول Temperature sensors على أساس التغير



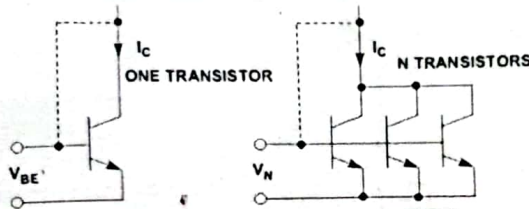
49  
 أما IC لا أدخلت عقلت فرق  
 new evaluation كبر

# Integrates Temperature Sensor

If we take  $N$  transistors identical to the first and allow the total current  $I_c$  to be shared equally among them, we find that the new base-emitter voltage is given by the equation

$$V_N = \frac{kT}{q} \ln\left(\frac{I_c}{N \cdot I_s}\right)$$

## BASIC RELATIONSHIPS FOR SEMICONDUCTOR TEMPERATURE SENSORS



#1 ←  $V_{BE} = \frac{kT}{q} \ln\left(\frac{I_c}{I_s}\right)$        $V_N = \frac{kT}{q} \ln\left(\frac{I_c}{N \cdot I_s}\right)$  →  $N$  : Transistors.

$$\Delta V_{BE} = V_{BE} - V_N = \frac{kT}{q} \ln(N)$$

$$\frac{kT}{q} \ln\left(\frac{I_c}{I_s}\right) - \frac{kT}{q} \ln\left(\frac{I_c}{N I_s}\right)$$

$$\left[ \Delta V_{BE} = \frac{kT}{q} \ln\left(\frac{N}{1}\right) \right]$$

$$\frac{kT}{q} \left( \frac{\ln\left(\frac{I_c}{I_s}\right)}{\ln\left(\frac{I_c}{N I_s}\right)} \right) \Rightarrow \frac{kT}{q} \ln(N)$$

Neither of these circuits is of much use by itself because of the strongly temperature dependent current  $I_s$ , but if we have equal currents in one BJT and  $N$  similar BJTs then the expression for the difference between the two base-emitter voltages is proportional to absolute temperature and does not contain  $I_s$ .

$$\Delta V_{BE} = V_{BE} - V_N = \frac{kT}{q} \ln\left(\frac{I_c}{I_s}\right) - \frac{kT}{q} \ln\left(\frac{I_c}{N \cdot I_s}\right)$$

$$\Delta V_{BE} = V_{BE} - V_N = \frac{kT}{q} \left[ \ln\left(\frac{I_c}{I_s}\right) - \ln\left(\frac{I_c}{N \cdot I_s}\right) \right]$$

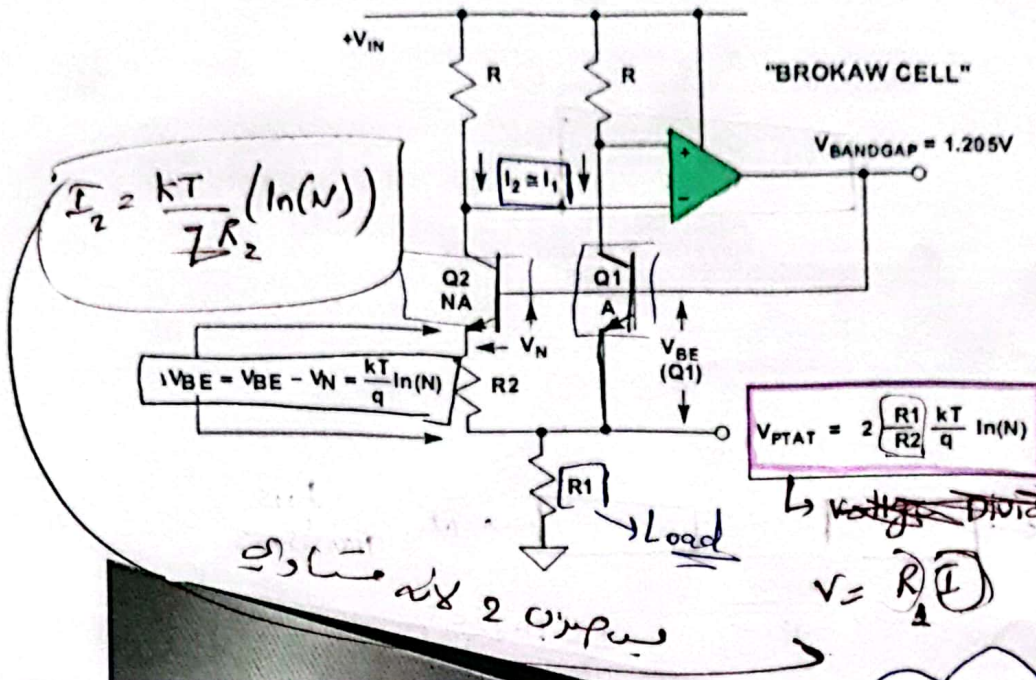
$$\frac{kT}{q} \ln(N)$$

$$\Delta V_{BE} = V_{BE} - V_N = \frac{kT}{q} \ln\left[ \frac{\left(\frac{I_c}{I_s}\right)}{\left(\frac{I_c}{N \cdot I_s}\right)} \right] = \frac{kT}{q} \ln(N)$$



Thermocouples	RTD	Thermistor	Integrated Circuits
-270 → 1800 °C	-250 - 900 °C	-100 - 440 °C	-55 - 150 °C
	Very high accuracy		

**CLASSIC BANDGAP TEMPERATURE SENSOR**



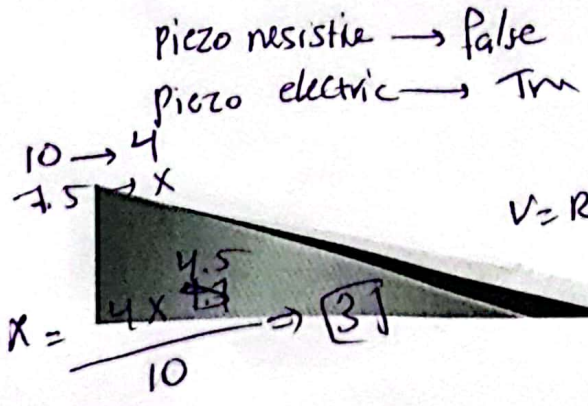
$$I_2 = \frac{kT}{qR_2} (\ln(N))$$

$$V_{PTAT} = 2 \frac{R_1}{R_2} \frac{kT}{q} \ln(N)$$

The voltage  $DV_{BE} = V_{BE} - V_N$  appears across resistor  $R_2$ . The emitter current in  $Q_2$  is therefore  $DV_{BE} / R_2$ . The op amp's servo loop and the resistors,  $R$ , force the same current to flow through  $Q_1$ . The  $Q_1$  and  $Q_2$  currents are equal and are summed and flow into resistor  $R_1$ . The corresponding voltage developed across  $R_1$  is proportional to absolute temperature (PTAT) and given by:

$$V_{PTAT} = \frac{2R_1(V_{BE} - V_N)}{R_2} = 2 \frac{R_1}{R_2} \frac{kT}{q} \ln(N).$$

The bandgap cell reference voltage,  $V_{BANDGAP}$ , appears at the base of  $Q_1$  and is the sum of  $V_{BE}(Q_1)$  and  $V_{PTAT}$ .  $V_{BE}(Q_1)$  is complementary to absolute temperature (CTAT), and summing it with  $V_{PTAT}$  causes the bandgap voltage to be constant with respect to temperature (assuming proper choice of  $R_1/R_2$  ratio and  $N$  to make the bandgap voltage equal to 1.205V). This circuit is the basic band-gap temperature sensor, and is widely used in semiconductor temperature sensors.



$$V_0 = \frac{RT}{RT_0}$$

