

# Sinusoidal Steady-state Analysis

## The Sinusoidal Source

$$v_s(t) = V_m \sin \omega t$$

$V_m \equiv$  Amplitude of the sinusoid

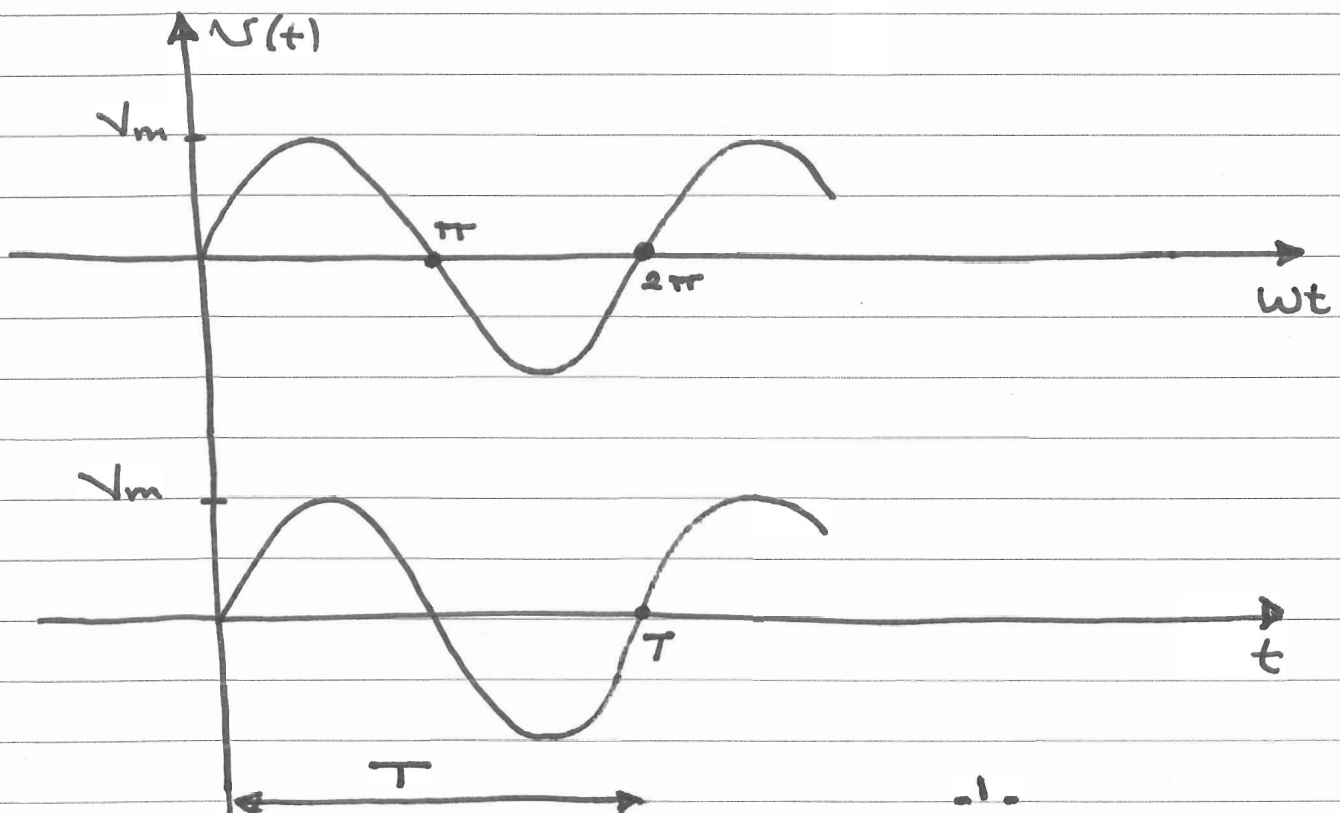
$\omega \equiv$  Angular frequency in radian/s

$$\omega = 2\pi f$$

$f \equiv$  frequency in Hertz

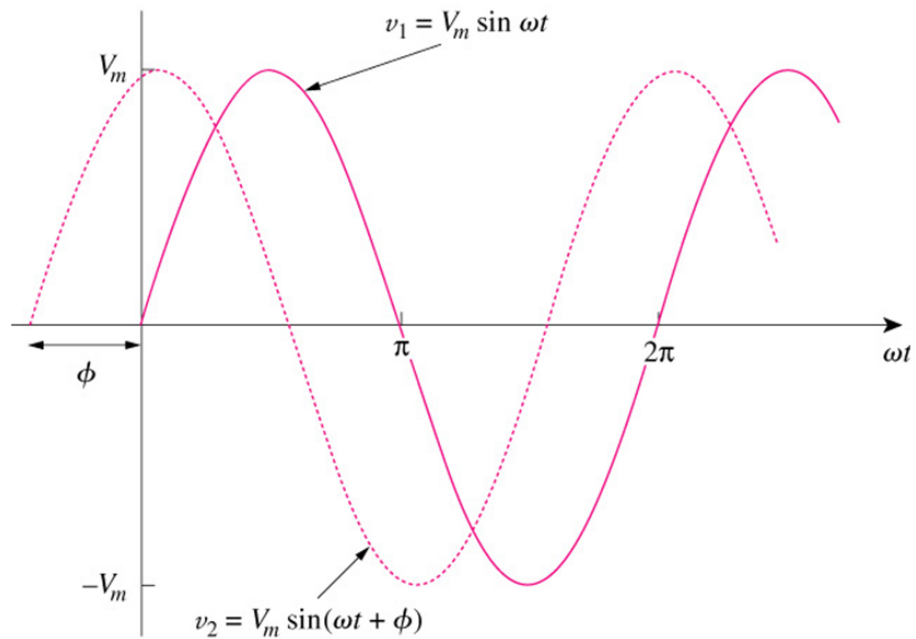
$$f = \frac{1}{T}$$

$T \equiv$  Period in seconds



# Phase of Sinusoids

➤ Consider the sinusoidal voltage having phase  $\phi$ ,  $v(t) = V_m \sin(\omega t + \phi)$



- $v_2$  LEADS  $v_1$  by phase  $\phi$ .
- $v_1$  LAGS  $v_2$  by phase  $\phi$ .
- $v_1$  and  $v_2$  are out of phase.

## Phase of Sinusoids

The terms Lead and Lag are used to indicate the relationship between two sinusoidal wave forms of the same frequency plotted on the same set of axes.

$$v_1(t) = V_m \sin \omega t$$

$$v_2(t) = V_m \sin (\omega t + \theta)$$

$\therefore v_2(t)$  Leads  $v_1(t)$  by  $\theta$

or

$v_1(t)$  Lags  $v_2(t)$  by  $\theta$

## Trigonometric Identities

$$\sin(A \pm B) = \sin A \cos B \pm \cos A \sin B$$

$$\cos(A \pm B) = \cos A \cos B \mp \sin A \sin B$$

$$\sin(\omega t \pm 180^\circ) = -\sin \omega t$$

$$\cos(\omega t \pm 180^\circ) = -\cos \omega t$$

$$\sin(\omega t \pm 90^\circ) = \pm \cos \omega t$$

$$\cos(\omega t \pm 90^\circ) = \mp \sin \omega t$$

$$A \cos \omega t + B \sin \omega t = C \cos(\omega t - \Theta)$$

Where

$$C = \sqrt{A^2 + B^2} \quad \text{and} \quad \Theta = \tan^{-1} \frac{B}{A}$$

$$\text{Let } v_1(t) = 10 \sin(5t - 30^\circ)$$

$$v_2(t) = 15 \sin(5t + 10^\circ)$$

$\therefore v_2(t)$  Leads  $v_1(t)$  by  $40^\circ$

$$\text{Let } i_1(t) = 2 \sin(377t + 45^\circ)$$

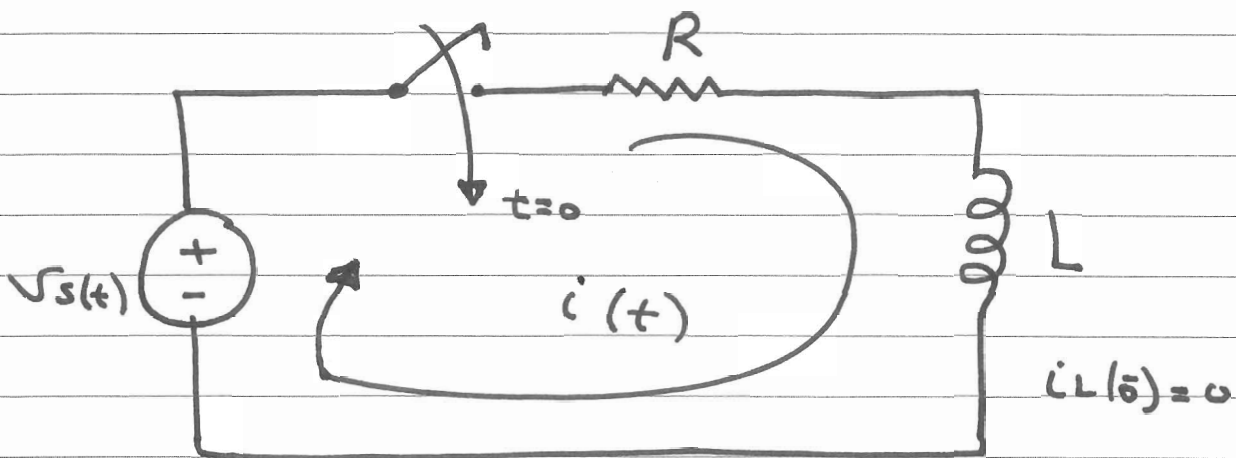
$$i_2(t) = 0.5 \cos(377t + 10^\circ)$$

$$\cos \alpha = \sin(\alpha + 90^\circ)$$

$$0.5 \cos(377t + 10^\circ) = 0.5 \sin(377t + 100^\circ)$$

$\therefore i_2(t)$  leads  $i_1(t)$  by  $55^\circ$

# The Sinusoidal Response



Find  $i(t)$  for  $t > 0$

given  $v_s(t) = V_m \cos \omega t$  ✓

KVL :

$$v_s(t) = Ri(t) + L \frac{di(t)}{dt}$$

$$V_m \cos \omega t = Ri(t) + L \frac{di(t)}{dt}$$

First order non homogenous differential equation

$$\therefore i(t) = i_n(t) + i_f(t)$$

$$i_n(t) = A e^{-t/\tau} + i_f(t)$$

$$i_f(t) = I_1 \cos \omega t + I_2 \sin \omega t$$

To find  $I_1$  and  $I_2$

$$V_m \cos \omega t = R i(t) + L \frac{di(t)}{dt}$$

$$V_m \cos \omega t = R \left[ I_1 \cos \omega t + I_2 \sin \omega t \right]$$

$$+ L\omega \left[ -I_1 \sin \omega t + I_2 \cos \omega t \right]$$

Collect the Cosine and Sine terms

$$0 = (-L I_1 \omega + R I_2) \sin \omega t + (L I_2 \omega + R I_1 - V_m) \cos \omega t$$

$$\therefore -\omega L I_1 + R I_2 = 0$$

$$\omega L I_2 + R I_1 - V_m = 0$$

$$I_1 = \frac{R V_m}{R^2 + \omega^2 L^2}$$

$$I_2 = \frac{\omega L V_m}{R^2 + \omega^2 L^2}$$

$$\therefore i(t) = \frac{R V_m}{R^2 + \omega^2 L^2} \cos \omega t + \frac{\omega L V_m}{R^2 + \omega^2 L^2} \sin \omega t$$

$$i_f(t) = I_1 \cos \omega t + I_2 \sin \omega t$$

$$i_f(t) = C \cos(\omega t - \phi)$$

$$i_f(t) = C \cos \omega t \cos \phi + C \sin \omega t \sin \phi$$

$$\therefore I_1 = C \cos \phi$$

$$I_2 = C \sin \phi$$

$$\frac{I_2}{I_1} = \tan \phi$$

$$\therefore \phi = \tan^{-1} \frac{I_2}{I_1} = \tan^{-1} \frac{\omega L}{R} \quad \text{--- (1)}$$

$$I_1^2 + I_2^2 = C^2 \cos^2 \phi + C^2 \sin^2 \phi$$

$$I_1^2 + I_2^2 = C^2$$

$$\therefore C = \sqrt{I_1^2 + I_2^2}$$

$$C = \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}} \quad \text{--- (2)}$$

$$\therefore i_f(t) = \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}} \cos\left(\omega t - \tan^{-1} \frac{\omega L}{R}\right)$$



$$\therefore i(t) = A e^{-t/\tau} + \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}} \cos\left(\omega t - \tan^{-1} \frac{\omega L}{R}\right)$$

$$i(0^+) = A + \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}} \cos\left(-\tan^{-1} \frac{\omega L}{R}\right) = 0$$

$$\therefore A = -\frac{V_m}{\sqrt{R^2 + \omega^2 L^2}} \cos\left(-\tan^{-1} \frac{\omega L}{R}\right)$$

$$\therefore i(t) = i_n(t) + i_f(t)$$

$i(t) =$  transient Component +  
Steady-state Component

\* The steady-state solution is a sinusoidal function with the same frequency as the source signal.

# Complex Numbers

A complex number may be written in three forms

1) Rectangular Form

$$Z = x + jy$$

$$j = \sqrt{-1}, \quad x = \operatorname{Re}(Z), \quad y = \operatorname{Im}(Z)$$

2) Exponential Form

$$Z = |Z| e^{j\theta}$$

$$|Z| = \text{Magnitude}, \quad \theta = \text{angle}$$

3) Polar Form

$$Z = |Z| \angle \theta$$

## Euler's Law

$$e^{j\theta} = \cos \theta + j \sin \theta$$

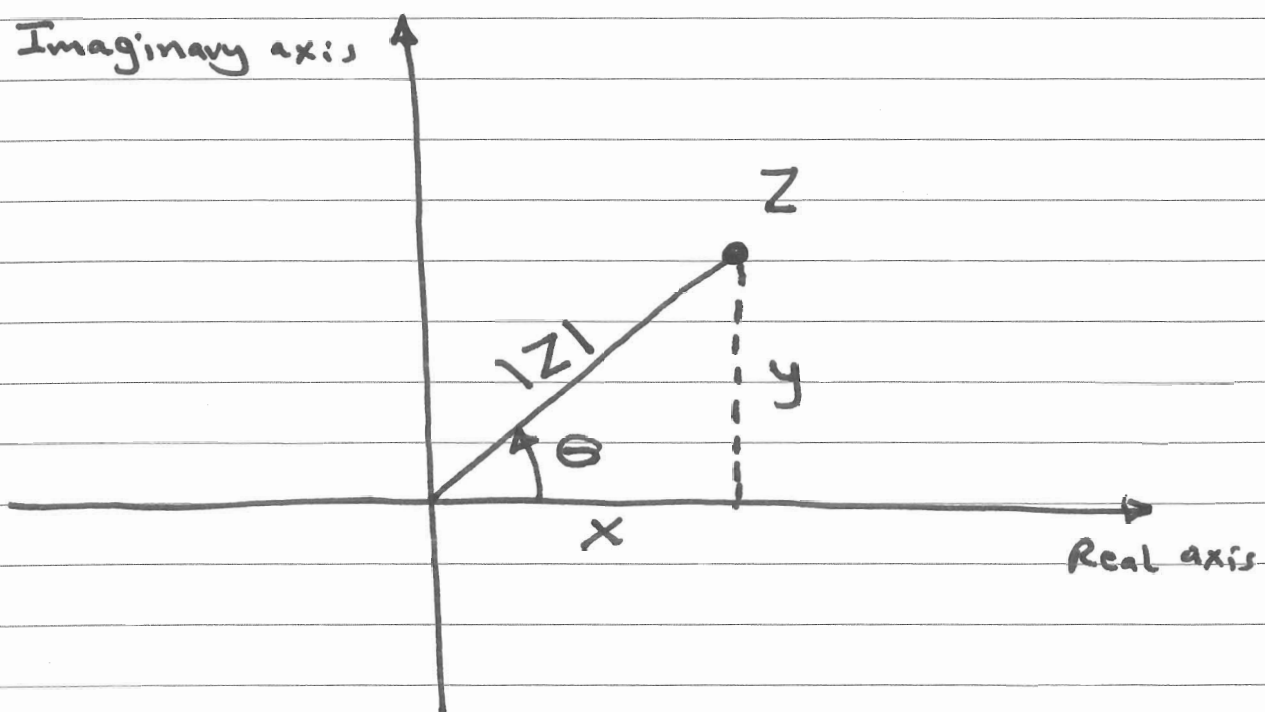
$$Z = |Z| e^{j\theta}$$

$$Z = |Z| \cos \theta + j |Z| \sin \theta$$

$$Z = x + j y$$

$$\therefore x = |Z| \cos \theta$$

$$y = |Z| \sin \theta$$



## Mathematical Operations of Complex numbers

$$\text{Addition : } Z_1 + Z_2 = (x_1 + x_2) + j(y_1 + y_2)$$

$$\text{Subtraction : } Z_1 - Z_2 = (x_1 - x_2) + j(y_1 - y_2)$$

$$\text{Multiplication : } Z_1 Z_2 = |Z_1| |Z_2| \angle \underline{\theta_1 + \theta_2}$$

$$\text{Division : } \frac{Z_1}{Z_2} = \frac{|Z_1|}{|Z_2|} \angle \underline{\theta_1 - \theta_2}$$

$$\text{Complex Conjugate : } Z^* = x - jy$$

$$= |Z| \angle \underline{-\theta}$$

$$x = |Z| \cos \theta$$

$$y = |Z| \sin \theta$$

$$x^2 + y^2 = |Z|^2 \cos^2 \theta + |Z|^2 \sin^2 \theta$$

$$x^2 + y^2 = |Z|^2 (\cos^2 \theta + \sin^2 \theta)$$

$$x^2 + y^2 = |Z|^2$$

$$\therefore |Z| = \sqrt{x^2 + y^2}$$

$$\frac{y}{x} = \frac{|Z| \sin \theta}{|Z| \cos \theta} = \tan \theta$$

$$\therefore \theta = \tan^{-1} \frac{y}{x}$$

$$Z_1 = 4 + j3 = 5 \angle 36.9^\circ$$

$$Z_2 = 3 + j4 = 5 \angle 53.1^\circ$$

$$Z_1 + Z_2 = 7 + j7$$

$$Z_1 - Z_2 = 1 - j1$$

$$Z_1 Z_2 = 5 \angle 36.9^\circ \cdot 5 \angle 53.1^\circ = 25 \angle 90^\circ$$

$$\frac{Z_1}{Z_2} = \frac{5 \angle 36.9^\circ}{5 \angle 53.1^\circ} = 1 \angle -16.2^\circ$$

OR

$$Z_1 Z_2 = (4 + j3)(3 + j4)$$

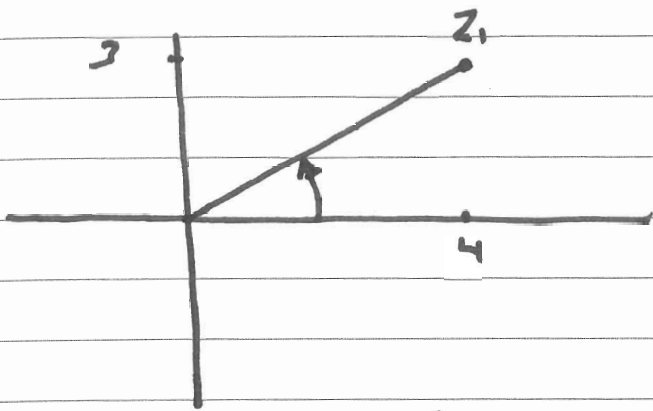
$$= 12 + j16 + j9 - 12$$

$$Z_1 Z_2 = j25$$

$$\frac{Z_1}{Z_2} = \frac{4 + j3}{3 + j4} \cdot \frac{3 - j4}{3 - j4} = \frac{12 - j16 + j9 + 12}{25}$$

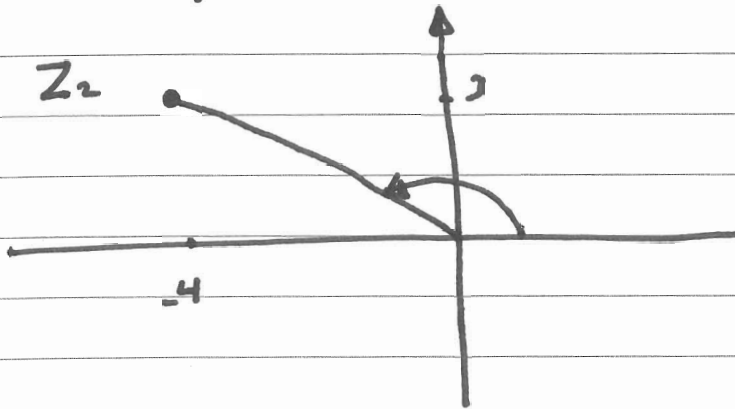
$$= \frac{24 - j5}{25} = \frac{24}{25} - j \frac{5}{25}$$

# The graphical Representation



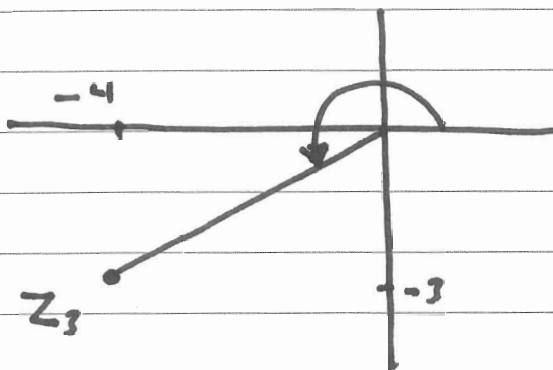
$$Z_1 = 4 + j3$$

$$Z_1 = 5 \angle 36.9^\circ$$



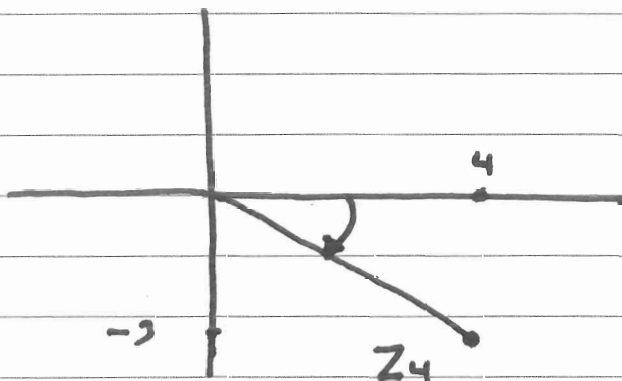
$$Z_2 = -4 + j3$$

$$Z_2 = 5 \angle 143.1$$



$$Z_3 = -4 - j3$$

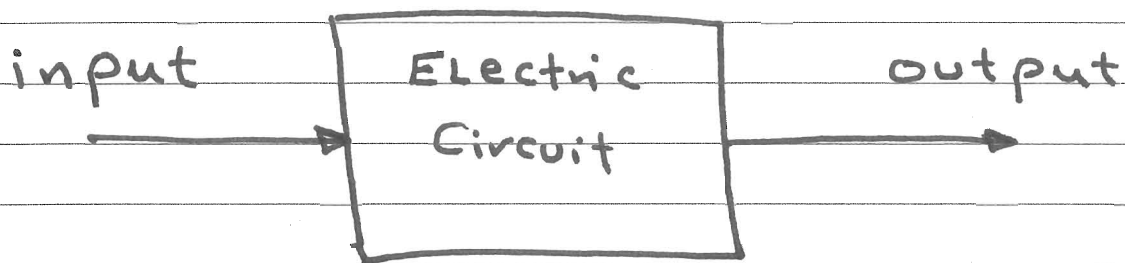
$$Z_3 = 5 \angle 216.9$$



$$Z_4 = 4 - j3$$

$$Z_4 = 5 \angle -36.9^\circ$$

# The phasor Concept



$$V_m \cos(\omega t + \theta) \longrightarrow I_m \cos(\omega t + \phi)$$

$$V_m \sin(\omega t + \theta) \longrightarrow I_m \sin(\omega t + \phi)$$

$$j V_m \sin(\omega t + \theta) \longrightarrow j I_m \sin(\omega t + \phi)$$

$$\begin{array}{ccc} V_m \cos(\omega t + \theta) & & I_m \cos(\omega t + \phi) \\ + & \Longrightarrow & + \end{array}$$

$$j V_m \sin(\omega t + \theta) \qquad j I_m \sin(\omega t + \phi)$$

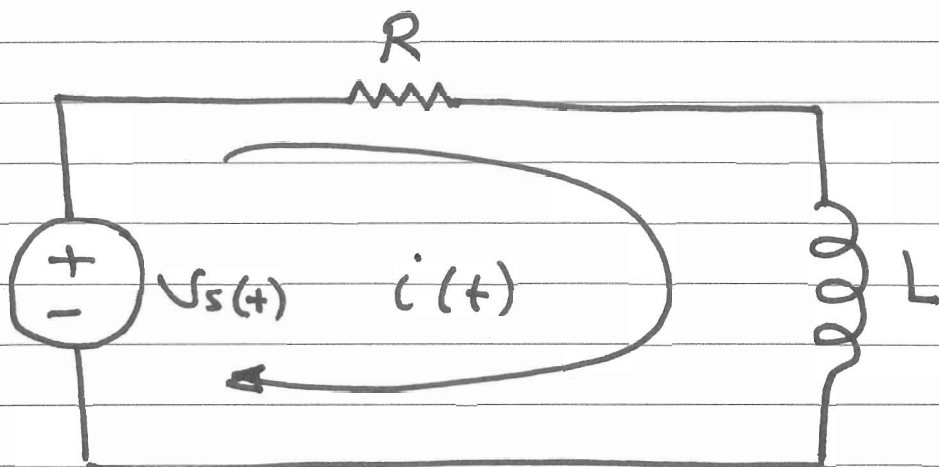
$$V_m e^{j(\omega t + \theta)} \longrightarrow I_m e^{j(\omega t + \phi)}$$



Instead of Applying a real forcing function to obtain the desired real response, we apply a Complex forcing function whose real part is the given real forcing function.

We obtain a Complex response whose real part is the desired real response.

# Sinusoidal and Complex forcing function



$$v_s(t) = V_m \cos \omega t$$

$$\therefore i(t) = I_m \cos(\omega t + \phi)$$

$$v_s(t) \longrightarrow V_m e^{j\omega t}$$

$$i(t) \longrightarrow I_m e^{j(\omega t + \phi)}$$

KVL :

$$v_s(t) = R i(t) + L \frac{di(t)}{dt}$$

$$V_m e^{j\omega t} = R I_m e^{j(\omega t + \phi)} + j\omega L I_m e^{j(\omega t + \phi)}$$

a Complex algebraic equation

To find  $I_m$  and  $\phi$  ; divide by  $e^{j\omega t}$

$$V_m = R I_m e^{j\phi} + j\omega L I_m e^{j\phi}$$

$$V_m = I_m e^{j\phi} (R + j\omega L)$$

$$\therefore I_m e^{j\phi} = \frac{V_m}{R + j\omega L}$$

$$I_m e^{j\phi} = \frac{V_m}{\sqrt{R^2 + \omega^2 L^2} e^{j \tan^{-1} \frac{\omega L}{R}}}$$

$$I_m e^{j\phi} = \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}} e^{-j \tan^{-1} \frac{\omega L}{R}}$$

$$\therefore I_m = \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}}$$

$$\phi = - \tan^{-1} \frac{\omega L}{R}$$

$$\therefore i(t) = I_m \cos(\omega t + \phi)$$

$$i(t) = \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}} \cos(\omega t + \phi)$$