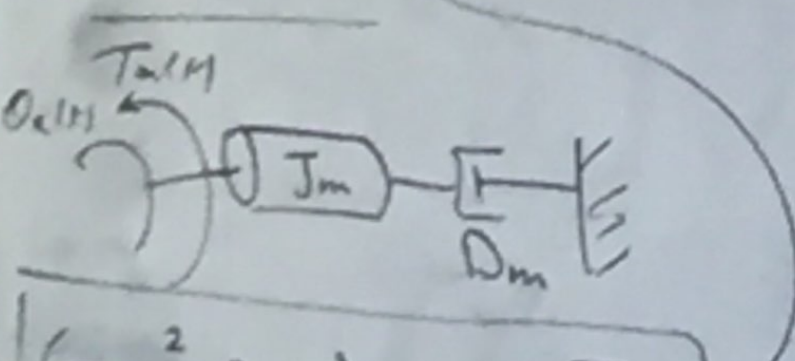


$$(R_a + sL_a) I_a(s) + V_b(s) = E_a(s)$$

$$(R_a + sL_a) \frac{T_m(s)}{k_t k_e} + K_b s \Theta_m(s) = E_a(s)$$



$$(J_m s^2 + D_m s) \Theta_m(s) = T_m(s)$$

$$(R_a + sL_a) \frac{(J_m s^2 + D_m s)}{k_t}$$

$$\Rightarrow R_a \gg L_a$$

$$\left(\frac{R_a}{k_t} (J_m s^2 + D_m s) \right)$$

$$\frac{\Theta_m(s)}{E_a(s)} = \frac{k_t / R_a}{J_m s^2 + D_m s}$$

$$= \frac{k_t / R_a}{s(s + \dots)}$$

$$(R_a + sL_a) \frac{(J_m s^2 + D_m s) \Theta_m(s) + K_b \Theta_m(s)}{k_t} = E_a(s)$$

$$\Rightarrow R_a \gg L_a$$

$$\left(\frac{R_a}{k_t} (J_m s^2 + D_m s) + K_b s \right) \Theta_m(s) = E_a(s)$$

$$\frac{\Theta_m(s)}{E_a(s)} = \frac{k_t / R_a}{J_m s^2 + D_m s + \frac{K_b k_t}{R_a} s}$$

$$= \frac{k_t / R_a J_m}{s \left(s + \frac{D_m}{J_m} + \frac{k_b k_t}{J_m R_a} \right)}$$

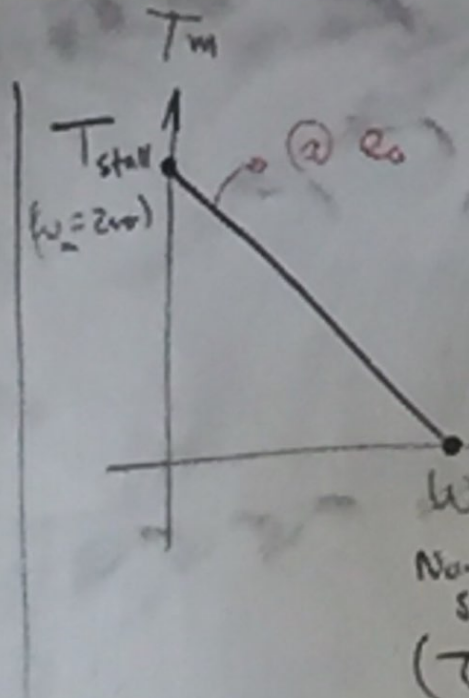
$$\frac{O_m(s)}{E_a(s)} = \frac{\frac{K_a}{R_a J_m}}{s \left(s + \frac{1}{J_m} \left(D_m + \frac{K_t K_b}{R_a} \right) \right)} = \frac{K}{s(s + \alpha)}$$

$$\left(\frac{R_a}{K_e} \right) T_m(s) + K_b \int \omega_m(s) ds = E_a(s)$$

$$\frac{R_a}{K_e} T_m(t) + k_b \underbrace{\frac{d}{dt} \omega_m(t)}_{\omega_m(t)} = e_a$$

$$\frac{R_a}{K_e} T_m + k_b \omega_m = e_a$$

$$T_m = - \frac{K_b K_t}{R_a} \omega_m + \frac{K_e}{R_a} e_a$$



@ $T_{stall} \Rightarrow \omega_m = ?$

$$T_{stall} = \frac{K_e}{R_a} e_a$$

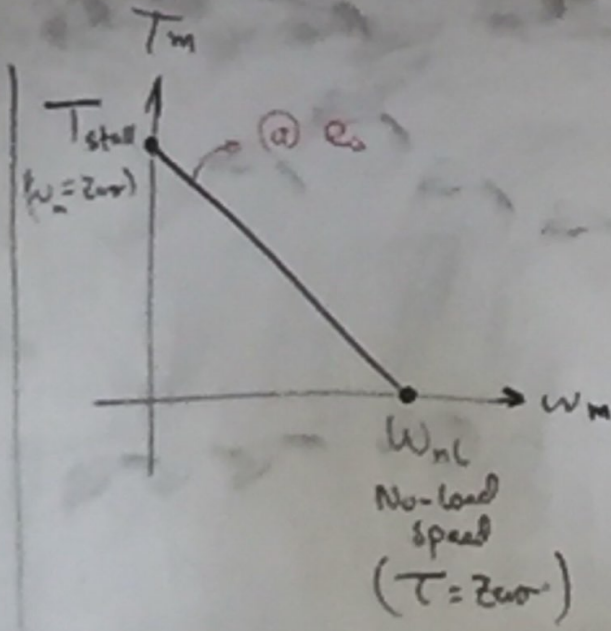
$$\frac{K_e}{R_a} = \frac{T_{stall}}{e_a}$$

$$e_a(\omega) = E - (s)$$

$$e_a(\omega) = e_a$$

$$e_a$$

$$\omega_m + \frac{k_t}{R_a} e_a$$



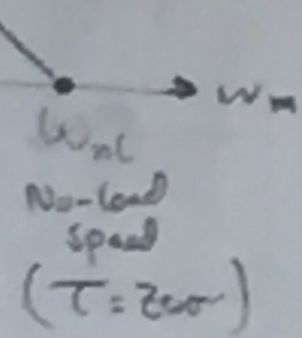
$$@ T_{stall} \Rightarrow \omega_m = 0$$

$$T_{stall} = \frac{k_t}{R_a} e_a$$

$$\frac{k_t}{R_a} = \frac{T_{stall}}{e_a}$$

$$@ \omega_{nl} \rightarrow T_m = 0$$

$$0 = \dots + \frac{k_t}{R_a} e_a$$

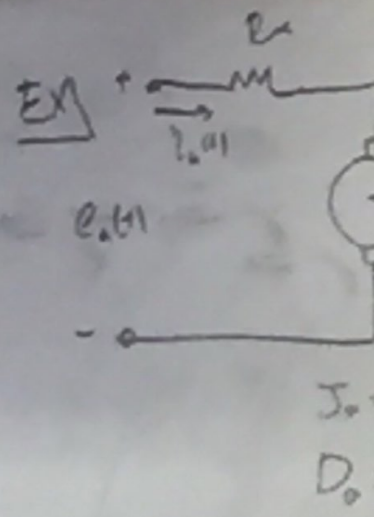


At $\omega_{nl} \rightarrow T_m = 0$

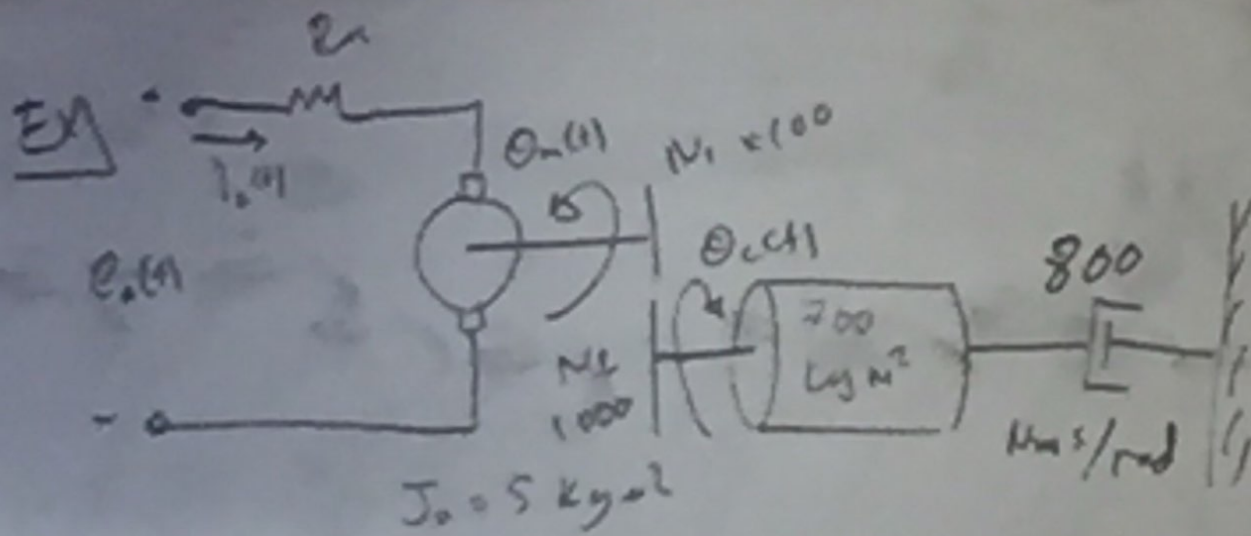
$$0 = -\frac{k_b k_t}{R_a} \omega_{nl} + \frac{k_t}{R_a} E_a$$

$$k_b \omega_{nl} = E_a$$

$$k_b = \frac{E_a}{\omega_{nl}}$$

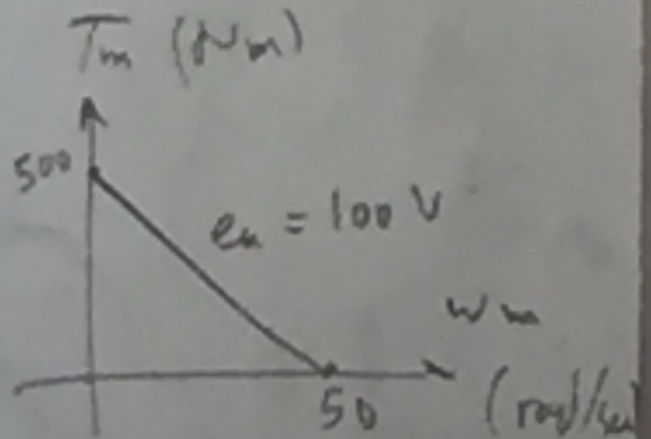


find $\frac{\omega_L(t)}{E_a(s)}$



$J_0 = 5 \text{ kg} \cdot \text{m}^2$
 $D_0 = 2 \text{ N} \cdot \text{m} \cdot \text{s} / \text{rad}$

Find $\frac{\theta_L(t)}{E_a(t)}$



$$\textcircled{1} \frac{k_t}{Z_a} = \frac{T_{stall}}{e_a} = \frac{500}{100} = 5$$

$$\textcircled{2} k_b = \frac{e_a}{\omega_{mc}} = \frac{100}{50} \times 2$$

$$\textcircled{3} J_m = J_a + J_L \left(\frac{N_1}{N_2} \right)^2 \\ = 5 + 700 \left(\frac{100}{1000} \right)^2 = \underline{\underline{12}}$$

$$\textcircled{4} D_m = D_a + D_L \left(\frac{N_1}{N_2} \right)^2 \\ = 2 + 800 \left(\frac{100}{1000} \right)^2 = \underline{\underline{10}}$$

$$\frac{\Theta_m(s)}{E_c(s)} = \frac{k_t}{R_a J_m} \frac{1}{s \left[s + \frac{1}{J_m} \left(D_a + \frac{k_t k_b}{R_a} \right) \right]} = \frac{0.417}{s(s + 66.2)}$$

$$\frac{\Theta_m}{\Theta_L} = \frac{N_2}{N_1} = \frac{10}{1}$$

$$\boxed{\Theta_m = 10 \Theta_L}$$

$$\frac{10 \Theta_L(s)}{E_c(s)} = \frac{0}{s}$$

$$\boxed{\frac{\Theta_L(s)}{E_c(s)} = \frac{0}{s}}$$

$$\frac{\theta_m}{\theta_L} = \frac{N_2}{N_1} = \frac{1000}{100} = 10$$

$$\boxed{\theta_m = 10 \theta_L}$$

$$\frac{10 \theta_L(s)}{E_a(s)} = \frac{0.417}{s(s+1.667)}$$

$$\boxed{\frac{\theta_L(s)}{E_a(s)} = \frac{0.0417}{s(s+1.667)}}$$

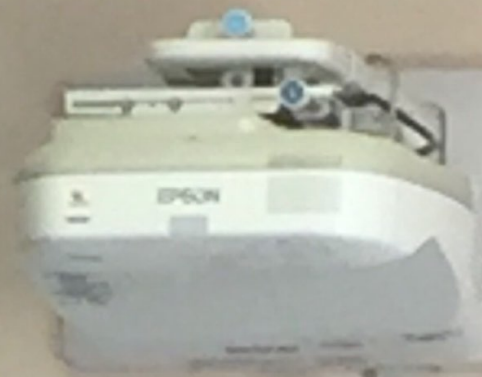
$$\rho w_{nl} \rightarrow T_w = 0$$

$$0 = -\frac{k_b k_t}{R_a} w_{nl} + \frac{k_t}{R_a}$$

$$k_b w_{nl} = e_a$$

$$\boxed{k_b = \frac{e_a}{w_{nl}}}$$

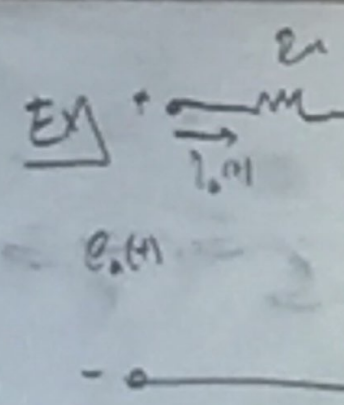
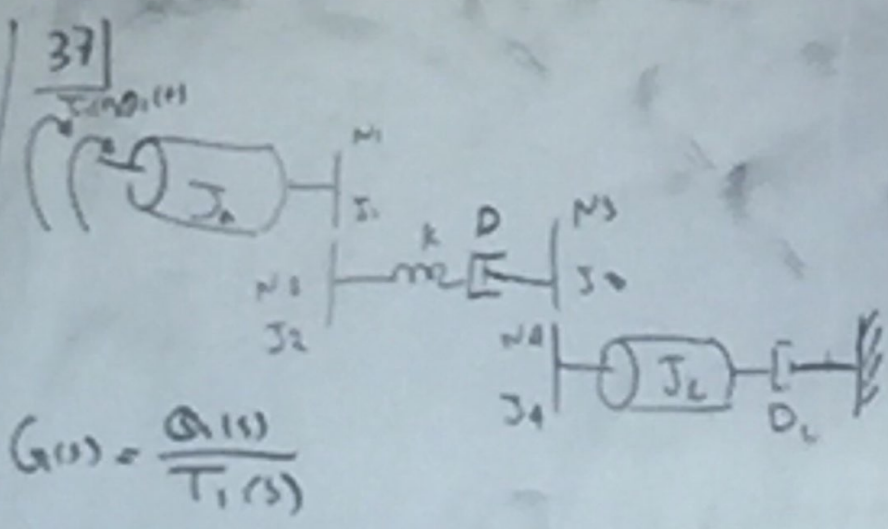
$$\left. \left. \left. \left. \frac{k_b k_t}{R_a} \right) \right) \right) = \frac{0.417}{s(s+1.667)}$$



$$\frac{1000}{100} = 10$$

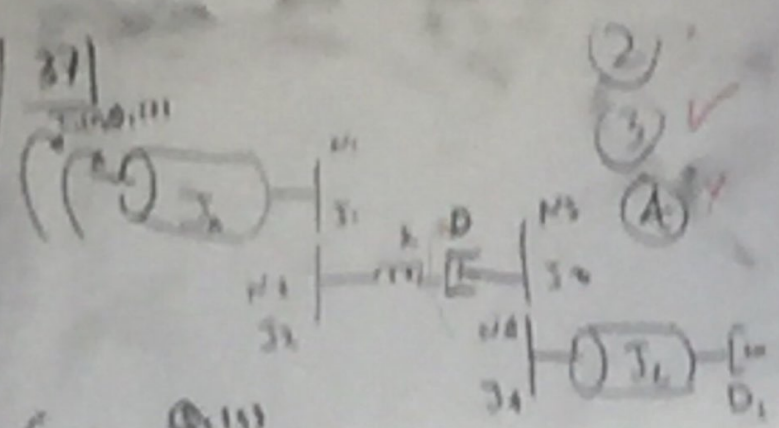
$$\frac{.417}{(s + 1.667)}$$

$$.0417$$



$\frac{0.0417}{s+1.667}$

$\frac{0.0417}{s+1.667}$



$G(s) = \frac{Q(s)}{T_1(s)}$

