

Solution of Homework 3

Problem 1:

a. $C(s) = \frac{5}{s(s+5)} = \frac{1}{s} - \frac{1}{s+5}$. Therefore, $c(t) = 1 - e^{-5t}$.

Also, $T = \frac{1}{5}$, $T_r = \frac{2.2}{a} = \frac{2.2}{5} = 0.44$, $T_s = \frac{4}{a} = \frac{4}{5} = 0.8$.

b. $C(s) = \frac{20}{s(s+20)} = \frac{1}{s} - \frac{1}{s+20}$. Therefore, $c(t) = 1 - e^{-20t}$. Also, $T = \frac{1}{20}$,

$T_r = \frac{2.2}{a} = \frac{2.2}{20} = 0.11$, $T_s = \frac{4}{a} = \frac{4}{20} = 0.2$.

Program:

```
' (a) '  
num=5;  
den=[1 5];  
Ga=tf(num,den)  
subplot(1,2,1)  
step(Ga)  
title(' (a) '  
' (b) '  
num=20;  
den=[1 20];  
Gb=tf(num,den)  
subplot(1,2,2)  
step(Gb)  
title(' (b) ')
```

Problem 2:

Writing the equation of motion,

$$(Ms^2 + 6s)X(s) = F(s)$$

Thus, the transfer function is,

$$\frac{X(s)}{F(s)} = \frac{1}{Ms^2 + 6s}$$

Differentiating to yield the transfer function in terms of velocity,

$$\frac{sX(s)}{F(s)} = \frac{1}{Ms + 6} = \frac{1/M}{s + \frac{6}{M}}$$

Thus, the settling time, T_s , and the rise time, T_r , are given by

$$T_s = \frac{4}{6/M} = \frac{2}{3}M = 0.667M; \quad T_r = \frac{2.2}{6/M} = \frac{1.1}{3}M = 0.367M$$

Program:

```

clf
M=1
num=1/M;
den=[1 6/M];
G=tf(num,den)
step(G)
pause
M=2
num=1/M;
den=[1 6/M];
G=tf(num,den)
step(G)

```

Problem 3:

- a. Pole: -2; $c(t) = A + Be^{-2t}$; first-order response.
- b. Poles: -3, -6; $c(t) = A + Be^{-3t} + Ce^{-6t}$; overdamped response.
- c. Poles: -10, -20; Zero: -7; $c(t) = A + Be^{-10t} + Ce^{-20t}$; overdamped response.
- d. Poles: $(-3+j3\sqrt{15})$, $(-3-j3\sqrt{15})$; $c(t) = A + Be^{-3t} \cos(3\sqrt{15}t + \phi)$; underdamped.
- e. Poles: $j3$, $-j3$; Zero: -2; $c(t) = A + B \cos(3t + \phi)$; undamped.
- f. Poles: -10, -10; Zero: -5; $c(t) = A + Be^{-10t} + Cte^{-10t}$; critically damped.

Problem 4:

The equation of motion is: $(Ms^2 + f_v s + K_s)X(s) = F(s)$. Hence, $\frac{X(s)}{F(s)} = \frac{1}{Ms^2 + f_v s + K_s} = \frac{1}{s^2 + s + 5}$.

The step response is now evaluated: $X(s) = \frac{1}{s(s^2 + s + 5)} = \frac{1/5}{s} - \frac{\frac{1}{5}s + \frac{1}{5}}{(s + \frac{1}{2})^2 + \frac{19}{4}} =$

$$\frac{\frac{1}{5}(s + \frac{1}{2}) + \frac{1}{5\sqrt{19}} \frac{\sqrt{19}}{2}}{(s + \frac{1}{2})^2 + \frac{19}{4}}$$

Taking the inverse Laplace transform, $x(t) = \frac{1}{5} - \frac{1}{5} e^{-0.5t} \left(\cos \frac{\sqrt{19}}{2} t + \frac{1}{\sqrt{19}} \sin \frac{\sqrt{19}}{2} t \right)$

$$= \frac{1}{5} \left[1 - 2\sqrt{\frac{5}{19}} e^{-0.5t} \cos \left(\frac{\sqrt{19}}{2} t - 12.92^\circ \right) \right].$$

Problem 5:

$$X(s) = \frac{100^2}{s(s^2 + 100s + 100^2)} = \frac{1}{s} - \frac{s+100}{(s+50)^2 + 7500} = \frac{1}{s} - \frac{(s+50) + 50}{(s+50)^2 + 7500} = \frac{1}{s} - \frac{(s+50) + \frac{50}{\sqrt{7500}}\sqrt{7500}}{(s+50)^2 + 7500}$$

$$\text{Therefore, } x(t) = 1 - e^{-50t} \left(\cos \sqrt{7500} t + \frac{50}{\sqrt{7500}} \sin \sqrt{7500} t \right)$$

$$= 1 - \frac{2}{\sqrt{3}} e^{-50t} \cos \left(50\sqrt{3} t - \tan^{-1} \frac{1}{\sqrt{3}} \right)$$

Problem 6:

a. $\omega_n^2 = 16 \text{ r/s}$, $2\zeta\omega_n = 3$. Therefore $\zeta = 0.375$, $\omega_n = 4$. $T_s = \frac{4}{\zeta\omega_n} = 2.667 \text{ s}$; $T_P = \frac{\pi}{\omega_n\sqrt{1-\zeta^2}} =$

0.8472 s ; $\%OS = e^{-\zeta\pi} / \sqrt{1-\zeta^2} \times 100 = 28.06 \%$; $\omega_n T_R = (1.76\zeta^3 - 0.417\zeta^2 + 1.039\zeta + 1) = 1.4238$;

therefore, $T_R = 0.356 \text{ s}$.

b. $\omega_n^2 = 0.04 \text{ r/s}$, $2\zeta\omega_n = 0.02$. Therefore $\zeta = 0.05$, $\omega_n = 0.2$. $T_s = \frac{4}{\zeta\omega_n} = 400 \text{ s}$; $T_P = \frac{\pi}{\omega_n\sqrt{1-\zeta^2}} =$

15.73 s ; $\%OS = e^{-\zeta\pi} / \sqrt{1-\zeta^2} \times 100 = 85.45 \%$; $\omega_n T_R = (1.76\zeta^3 - 0.417\zeta^2 + 1.039\zeta + 1)$; therefore,

$T_R = 5.26 \text{ s}$.

c. $\omega_n^2 = 1.05 \times 10^7 \text{ r/s}$, $2\zeta\omega_n = 1.6 \times 10^3$. Therefore $\zeta = 0.247$, $\omega_n = 3240$. $T_s = \frac{4}{\zeta\omega_n} = 0.005 \text{ s}$; $T_P =$

$\frac{\pi}{\omega_n\sqrt{1-\zeta^2}} = 0.001 \text{ s}$; $\%OS = e^{-\zeta\pi} / \sqrt{1-\zeta^2} \times 100 = 44.92 \%$; $\omega_n T_R = (1.76\zeta^3 - 0.417\zeta^2 + 1.039\zeta +$

$1)$; therefore, $T_R = 3.88 \times 10^{-4} \text{ s}$.

Problem 7:

$$\text{a. } \zeta = \frac{-\ln\left(\frac{\%OS}{100}\right)}{\sqrt{\pi^2 + \ln^2\left(\frac{\%OS}{100}\right)}} = 0.56, \omega_n = \frac{4}{\zeta T_s} = 11.92. \text{ Therefore, poles} = -\zeta\omega_n \pm j\omega_n\sqrt{1-\zeta^2}$$

$$= -6.67 \pm j9.88.$$

$$\text{b. } \zeta = \frac{-\ln\left(\frac{\%OS}{100}\right)}{\sqrt{\pi^2 + \ln^2\left(\frac{\%OS}{100}\right)}} = 0.591, \omega_n = \frac{\pi}{T_p\sqrt{1-\zeta^2}} = 0.779.$$

$$\text{Therefore, poles} = -\zeta\omega_n \pm j\omega_n\sqrt{1-\zeta^2} = -0.4605 \pm j0.6283.$$

$$\text{c. } \zeta\omega_n = \frac{4}{T_s} = 0.571, \omega_n\sqrt{1-\zeta^2} = \frac{\pi}{T_p} = 1.047. \text{ Therefore, poles} = -0.571 \pm j1.047.$$

Problem 8:

$$\text{Re} = \frac{4}{T_s} = 4; \zeta = \frac{-\ln(12.3/100)}{\sqrt{\pi^2 + \ln^2(12.3/100)}} = 0.5549$$

$$\text{Re} = \zeta\omega_n = 0.5549\omega_n = 4; \therefore \omega_n = 7.21$$

$$\text{Im} = \omega_n\sqrt{1-\zeta^2} = 6$$

$$\therefore G(s) = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2} = \frac{51.96}{s^2 + 8s + 51.96}$$

Problem 9:

$$\text{a. Writing the equation of motion yields, } (5s^2 + 5s + 28)X(s) = F(s)$$

Solving for the transfer function,

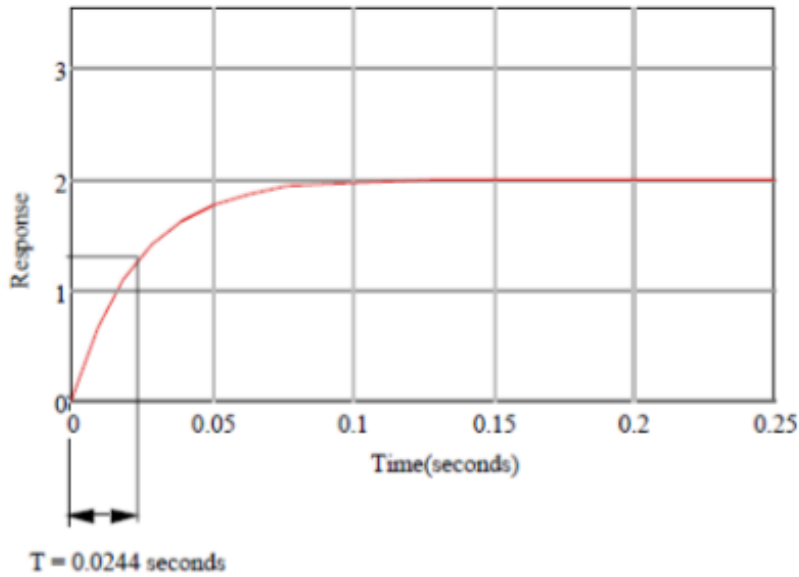
$$\frac{X(s)}{F(s)} = \frac{1/5}{s^2 + s + \frac{28}{5}}$$

$$\text{b. } \omega_n^2 = 28/5 \text{ r/s, } 2\zeta\omega_n = 1. \text{ Therefore } \zeta = 0.211, \omega_n = 2.37. T_s = \frac{4}{\zeta\omega_n} = 8.01 \text{ s; } T_p = \frac{\pi}{\omega_n\sqrt{1-\zeta^2}} =$$

$$1.36 \text{ s; } \%OS = e^{-\zeta\pi} / \sqrt{1-\zeta^2} \times 100 = 50.7 \%; \omega_n T_r = (1.76\zeta^3 - 0.417\zeta^2 + 1.039\zeta + 1); \text{ therefore, } T_r = 0.514 \text{ s.}$$

Problem 10:

a. Measuring the time constant from the graph, $T = 0.0244$ seconds.

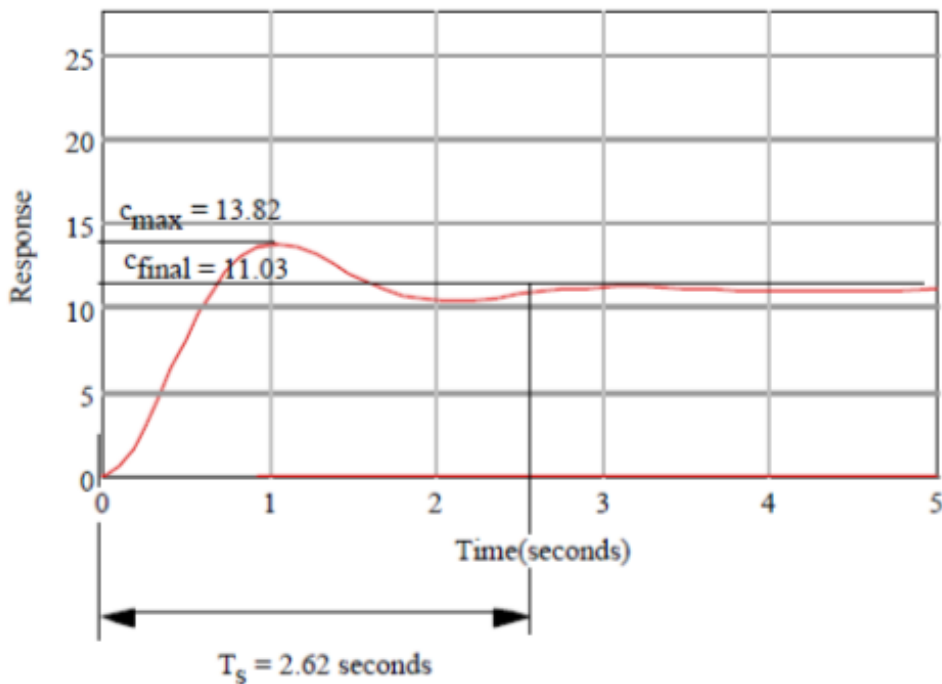


Estimating a first-order system, $G(s) = \frac{K}{s+a}$. But, $a = 1/T = 40.984$, and $\frac{K}{a} = 2$. Hence, $K = 81.967$.

Thus,

$$G(s) = \frac{81.967}{s+40.984}$$

b. Measuring the percent overshoot and settling time from the graph: $\%OS = (13.82-11.03)/11.03 = 25.3\%$,



and $T_s = 2.62$ seconds. Estimating a second-order system, we use Eq. (4.39) to find $\zeta = 0.4$, and Eq. (4.42) to find $\omega_n = 3.82$. Thus, $G(s) = \frac{K}{s^2 + 2\zeta\omega_n s + \omega_n^2}$. Since $C_{\text{final}} = 11.03$, $\frac{K}{\omega_n^2} = 11.03$. Hence,

$K = 160.95$. Substituting all values,

$$G(s) = \frac{160.95}{s^2 + 3.056s + 14.59}$$

c. From the graph, %OS = 40%. Using Eq. (4.39), $\zeta = 0.28$. Also from the graph,

$$T_p = \frac{\pi}{\omega_n \sqrt{1 - \zeta^2}} = 4. \text{ Substituting } \zeta = 0.28, \text{ we find } \omega_n = 0.818.$$

Thus,

$$G(s) = \frac{K}{s^2 + 2\zeta\omega_n s + \omega_n^2} = \frac{0.669}{s^2 + 0.458s + 0.669}.$$