



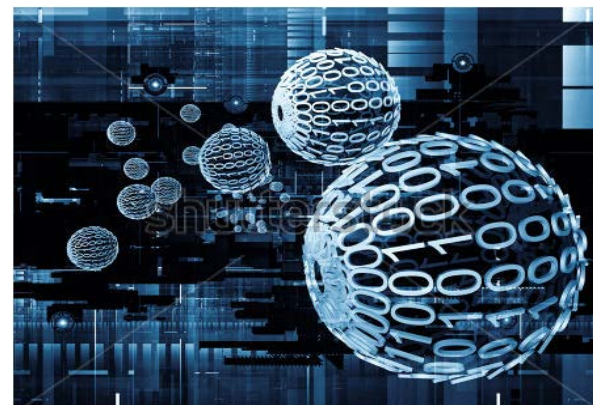
BIRZEIT UNIVERSITY

Faculty of Engineering and Technology

Department of Electrical and Computer Engineering

Modern Communication Systems, ENEE3306

Dr. Mohammad Jubran



Lecture 3

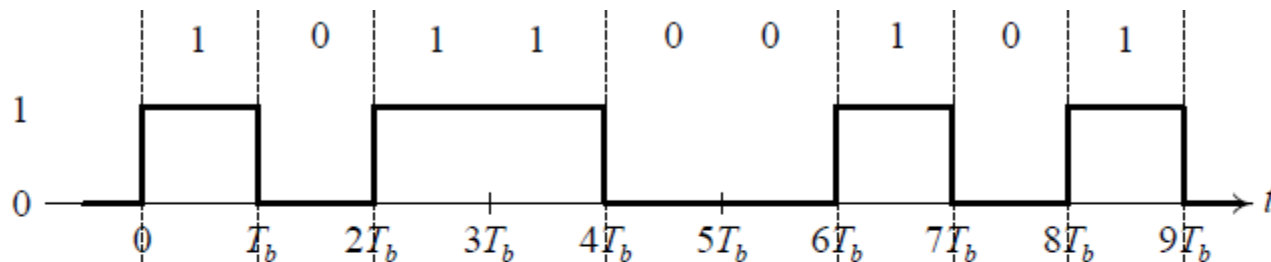
- Baseband transmission is conducted at low frequencies.
- Passband transmission happens in a frequency band toward the high end of the spectrum.
- Satellite communication is in the 6–8 GHz band, while mobile phones systems are in the 800 MHz–2.0 GHz band.
- Bits are encoded as a variation of the amplitude, phase or frequency, or some combination of these parameters of a sinusoidal carrier.
- The carrier frequency is much higher than the highest frequency of the modulating signals (or messages).
- Shall consider binary amplitude-shift keying (BASK), binary phase-shift keying (BPSK) and binary frequency-shift keying (BFSK): Error performance, optimum receivers, spectra.
- Extensions to quadrature phase-shift keying (QPSK), offset QPSK (OQPSK) and minimum shift keying (MSK).



Digital Passband Modulation – Binary Passband Modulated

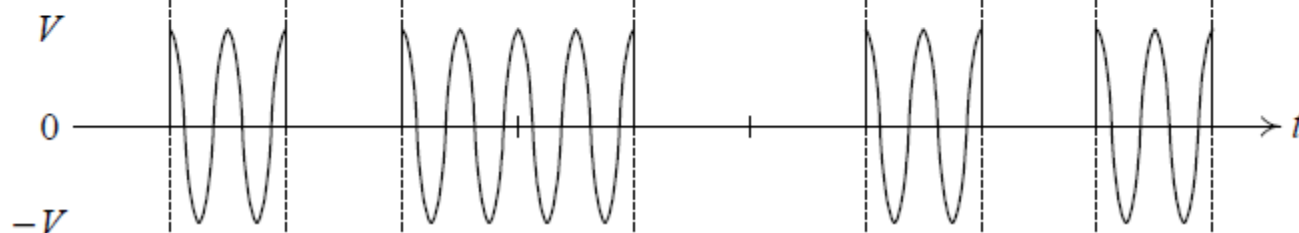
Signals

(a) Binary data

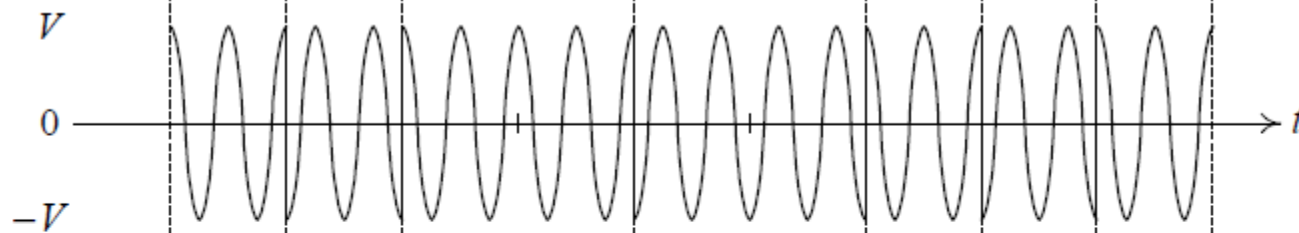


(b) Modulating signal
 $m(t)$

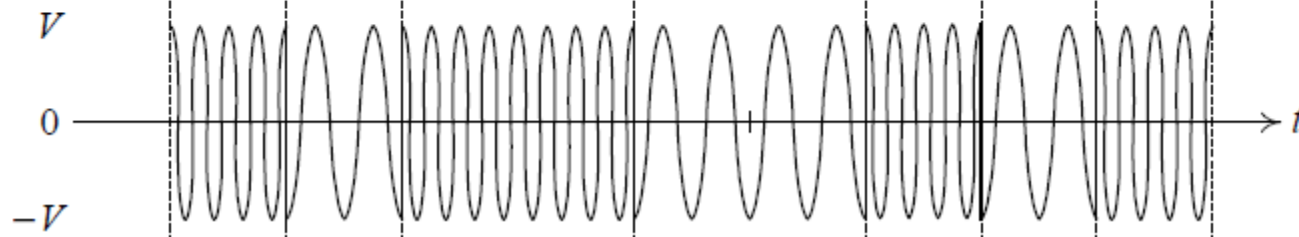
(c) BASK signal



(d) BPSK signal



(e) BFSK signal



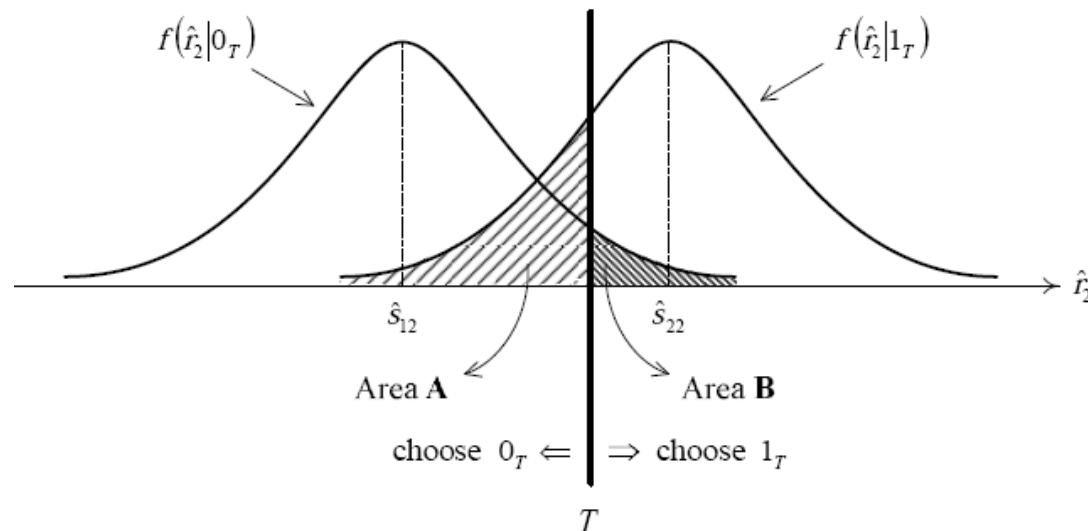


Digital Passband Modulation – Recall from previous material

➤ To detect b_k , compare \hat{r}_2 to the threshold value T

$$\rightarrow \hat{r}_2 = \int_0^{T_b} r(t) \hat{\Phi}_2(t) dt \quad \rightarrow T = \frac{\hat{s}_{22} + \hat{s}_{12}}{2} + \left(\frac{N_o/2}{\hat{s}_{22} - \hat{s}_{12}} \right) \ln \left(\frac{P_1}{P_2} \right)$$

$$\rightarrow P[\text{error}] = P \left[\begin{array}{l} \text{"0" decided and "1" transmitted) or} \\ \text{"1" decided and "0" transmitted) } \end{array} \right]$$

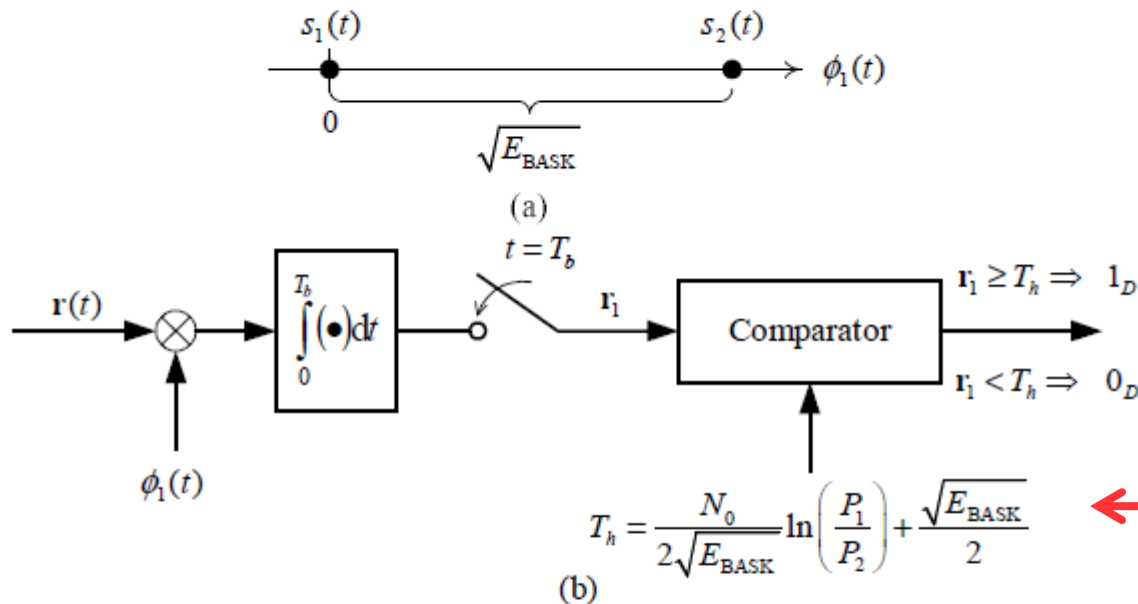


$$P[\text{error}] = Q \left(\frac{\hat{s}_{22} - \hat{s}_{12}}{2\sqrt{N_o/2}} \right) = Q \left(\frac{\text{distance between the signals}}{2 \times \text{noise RMS value}} \right)$$

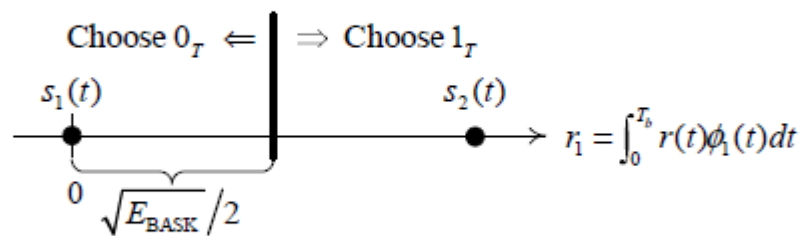


Digital Passband Modulation – Binary Amplitude-Shift Keying (BASK)

$$\begin{cases} s_1(t) = 0, & \text{"0}_T \\ s_2(t) = V \cos(2\pi f_c t), & \text{"1}_T \end{cases}, \quad 0 < t \leq T_b, \quad f_c = n/T_b$$



Try to derive this



$$P[\text{error}]_{BASK} = Q\left(\sqrt{\frac{E_{BASK}}{2N_0}}\right)$$

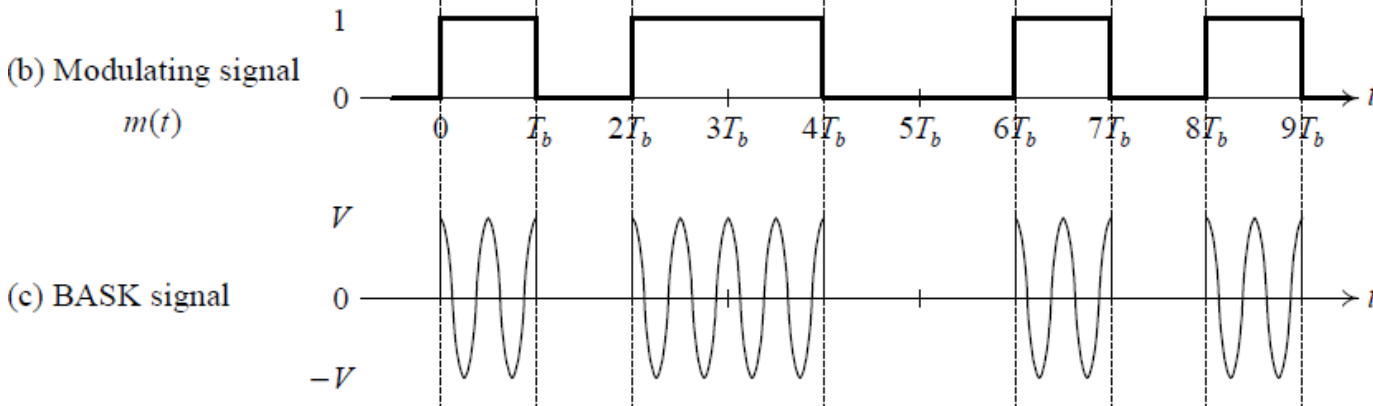


Digital Passband Modulation – PSD of BASK

➤ Notice that

$$\rightarrow S_{BASK}(t) = S_{NRZ}(t) \times \cos(2\pi f_c t)$$

(a) Binary data

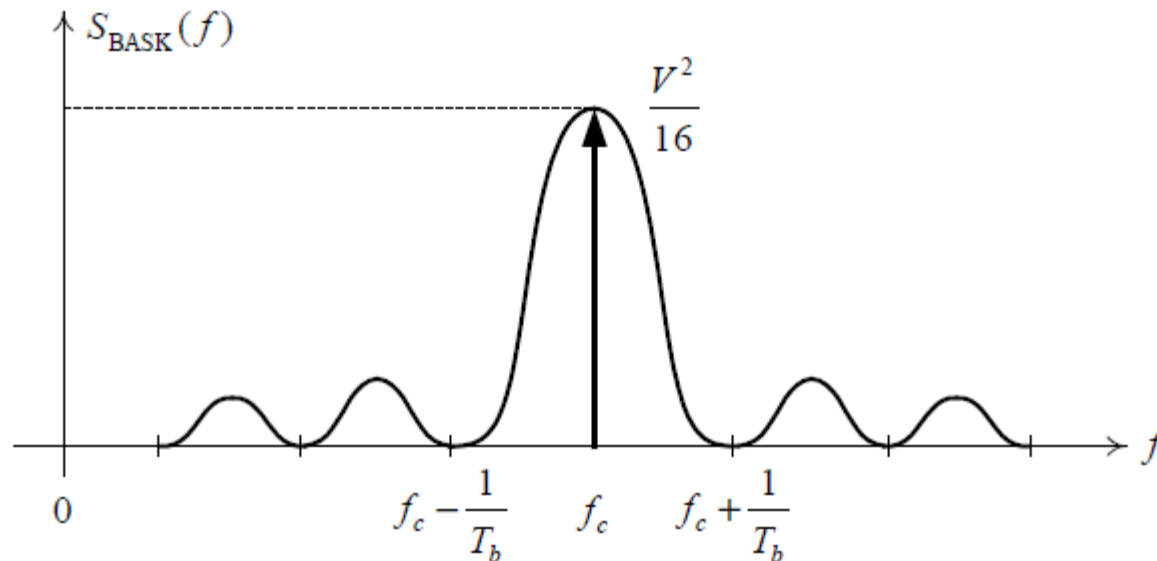


$$\rightarrow S_{BASK}(f) = S_{NRZ}(f) * F(\cos^2(2\pi f_c t))$$

$$= \left(\frac{V^2 T_b \text{sinc}^2(\pi f T_b)}{4} + \frac{V^2 \delta(f)}{4} \right) * \left(\frac{\delta(f - f_c) + \delta(f + f_c)}{4} \right)$$

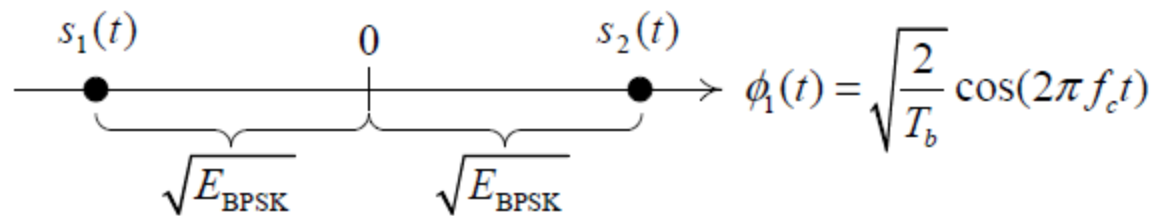
$$\begin{aligned} \rightarrow S_{BASK}(f) &= S_{NRZ}(f) * F(\cos(2\pi f_c t)) \\ &= \left(\frac{V^2 T_b \text{sinc}^2(\pi f T_b)}{4} + \frac{V^2 \delta(f)}{4} \right) * \left(\frac{\delta(f - f_c) + \delta(f + f_c)}{4} \right) \\ &= \left(\frac{V^2 T_b \text{sinc}^2(\pi T_b (f - f_c))}{16} + \frac{V^2 \delta(f - f_c)}{16} \right) \\ &\quad + \left(\frac{V^2 T_b \text{sinc}^2(\pi T_b (f + f_c))}{16} + \frac{V^2 \delta(f + f_c)}{16} \right) \\ &= \frac{V^2}{16} (\delta(f - f_c) + \delta(f + f_c) + T_b \text{sinc}^2(\pi T_b (f - f_c))) \end{aligned}$$

$$S_{\text{BASK}}(f) = \frac{V^2}{16} \left[\delta(f - f_c) + \delta(f + f_c) + \frac{\sin^2[\pi T_b(f + f_c)]}{\pi^2 T_b(f + f_c)^2} + \frac{\sin^2[\pi T_b(f - f_c)]}{\pi^2 T_b(f - f_c)^2} \right].$$



Approximately 95% of the total transmitted power lies in a band of $3/T_b$ (Hz), centered at f_c .

$$\begin{cases} s_1(t) = -V \cos(2\pi f_c t), & \text{if "0}_T\text{"} \\ s_2(t) = +V \cos(2\pi f_c t), & \text{if "1}_T\text{"} \end{cases}, \quad 0 < t \leq T_b,$$

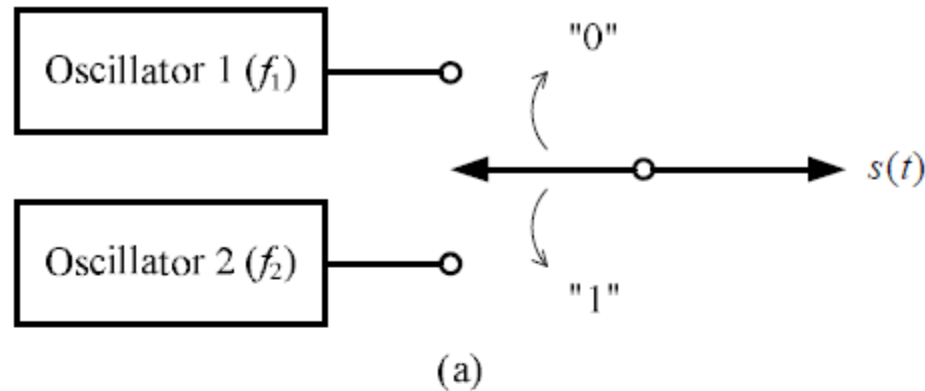


Try to derive
these

$$P[\text{error}]_{\text{BPSK}} = Q \left(\sqrt{\frac{2E_{\text{BPSK}}}{N_0}} \right).$$

$$S_{\text{BPSK}}(f) = \frac{V^2}{4} \left[\frac{\sin^2[\pi(f - f_c)T_b]}{\pi^2(f - f_c)^2 T_b} + \frac{\sin^2[\pi(f + f_c)T_b]}{\pi^2(f + f_c)^2 T_b} \right].$$

Similar to that of BASK, but no impulse functions at $\pm f_c$.



$$\begin{cases} s_1(t) = V \cos(2\pi f_1 t + \theta_1), & \text{if "0}_T\text{"} \\ s_2(t) = V \cos(2\pi f_2 t + \theta_2), & \text{if "1}_T\text{"} \end{cases}, \quad 0 < t \leq T_b.$$

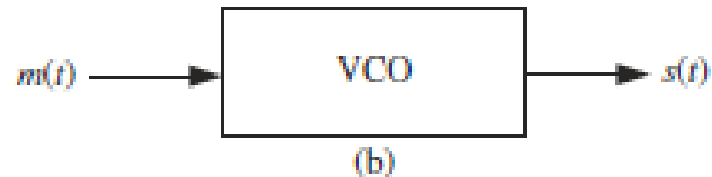
- Minimum frequency separation for *coherent* orthogonality ($\theta_1 = \theta_2$):

Try to
derive this

$$(\Delta f)_{\min}^{[\text{coherent}]} = \frac{1}{2T_b}.$$

- Minimum frequency separation for *noncoherent* orthogonality ($\theta_1 \neq \theta_2$):

$$(\Delta f)_{\min}^{[\text{noncoherent}]} = \frac{1}{T_b}.$$



$$\begin{cases} s_1(t) = V \cos 2\pi(f_c - f_d)t \\ s_2(t) = V \cos 2\pi(f_c + f_d)t \end{cases}, \quad 0 < t \leq T_b,$$

➤ where f_c is the carrier frequency and f_d is the *frequency deviation*

$$f_c = n/4T_b,$$

$$f_d = \begin{cases} m/4T_b & \text{(coherent orthogonality)} \\ m/2T_b & \text{(noncoherent orthogonality)} \end{cases},$$

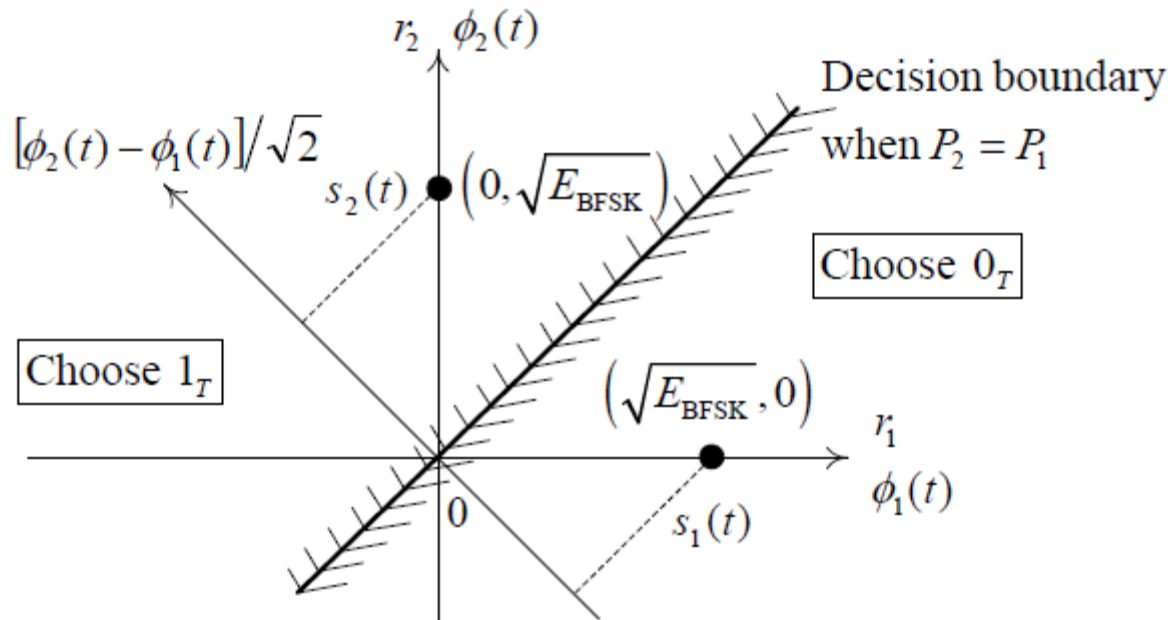
Try to
derive this

➤ Where $n \gg m$



Digital Passband Modulation – Binary Frequency-Shift Keying (BFSK)

$$\phi_1(t) = \frac{s_1(t)}{\sqrt{E_{\text{BFSK}}}}, \quad \phi_2(t) = \frac{s_2(t)}{\sqrt{E_{\text{BFSK}}}}.$$



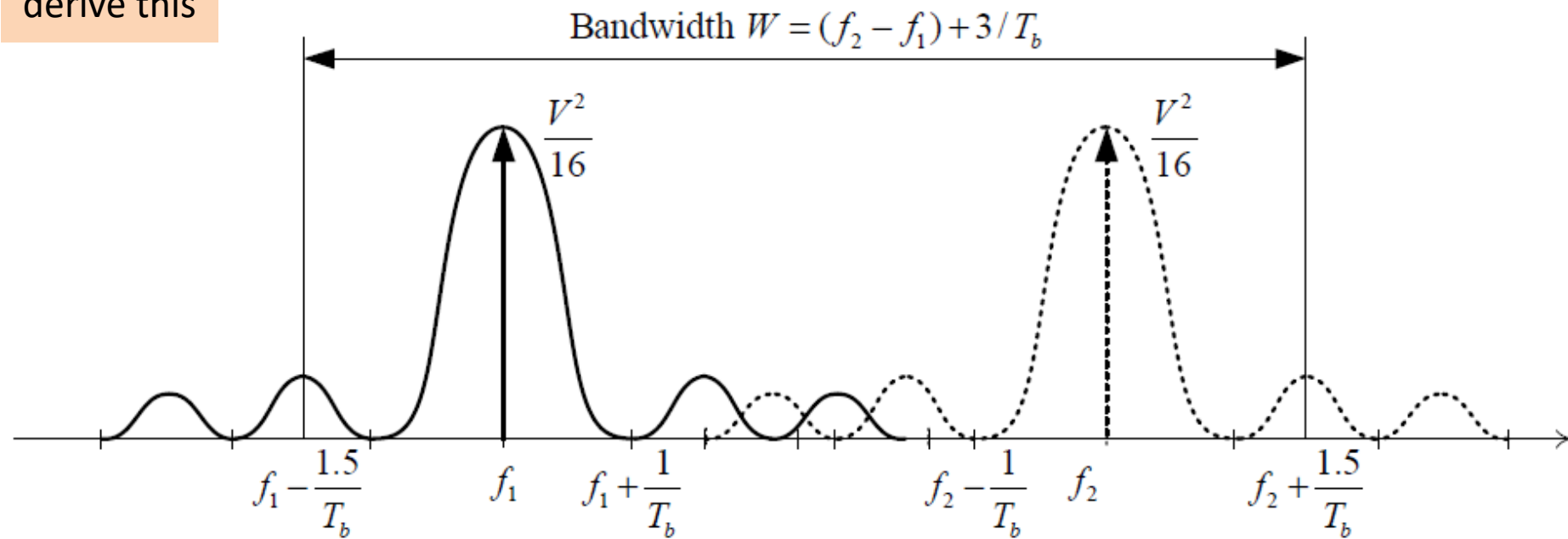
$$P[\text{error}]_{\text{BFSK}} = Q \left(\sqrt{\frac{E_{\text{BFSK}}}{N_0}} \right).$$



Digital Passband Modulation – PSD of BFSK

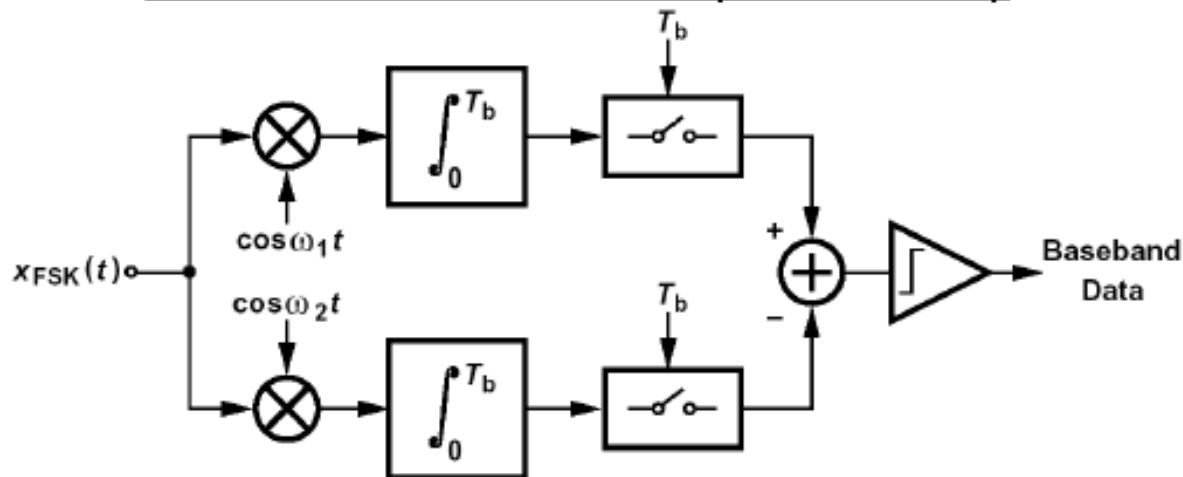
$$S_{\text{BFSK}}(f) = \frac{V^2}{16} \left[\delta(f - f_2) + \delta(f + f_2) + \frac{\sin^2[\pi T_b(f + f_2)]}{\pi^2 T_b(f + f_2)^2} + \frac{\sin^2[\pi T_b(f - f_2)]}{\pi^2 T_b(f - f_2)^2} \right] + \frac{V^2}{16} \left[\delta(f - f_1) + \delta(f + f_1) + \frac{\sin^2[\pi T_b(f + f_1)]}{\pi^2 T_b(f + f_1)^2} + \frac{\sin^2[\pi T_b(f - f_1)]}{\pi^2 T_b(f - f_1)^2} \right].$$

Try to derive this

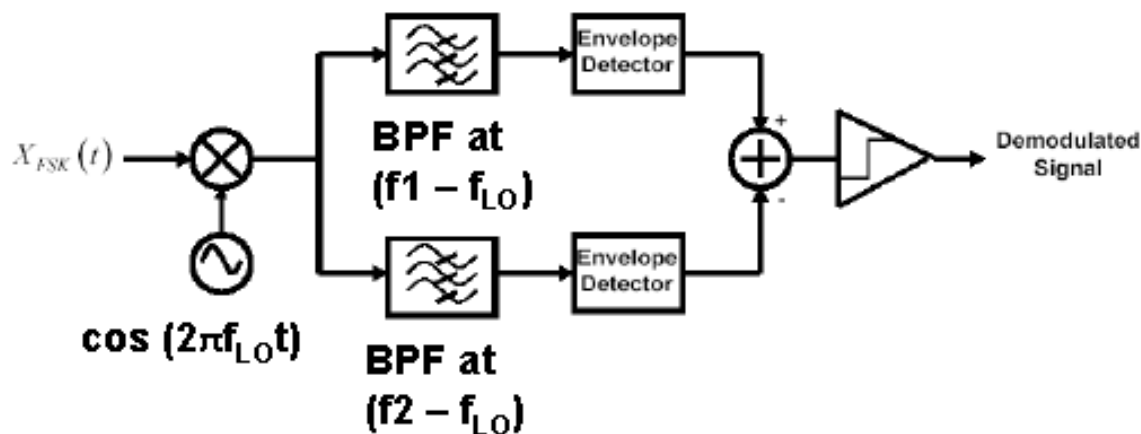




FSK Demodulation (Coherent)

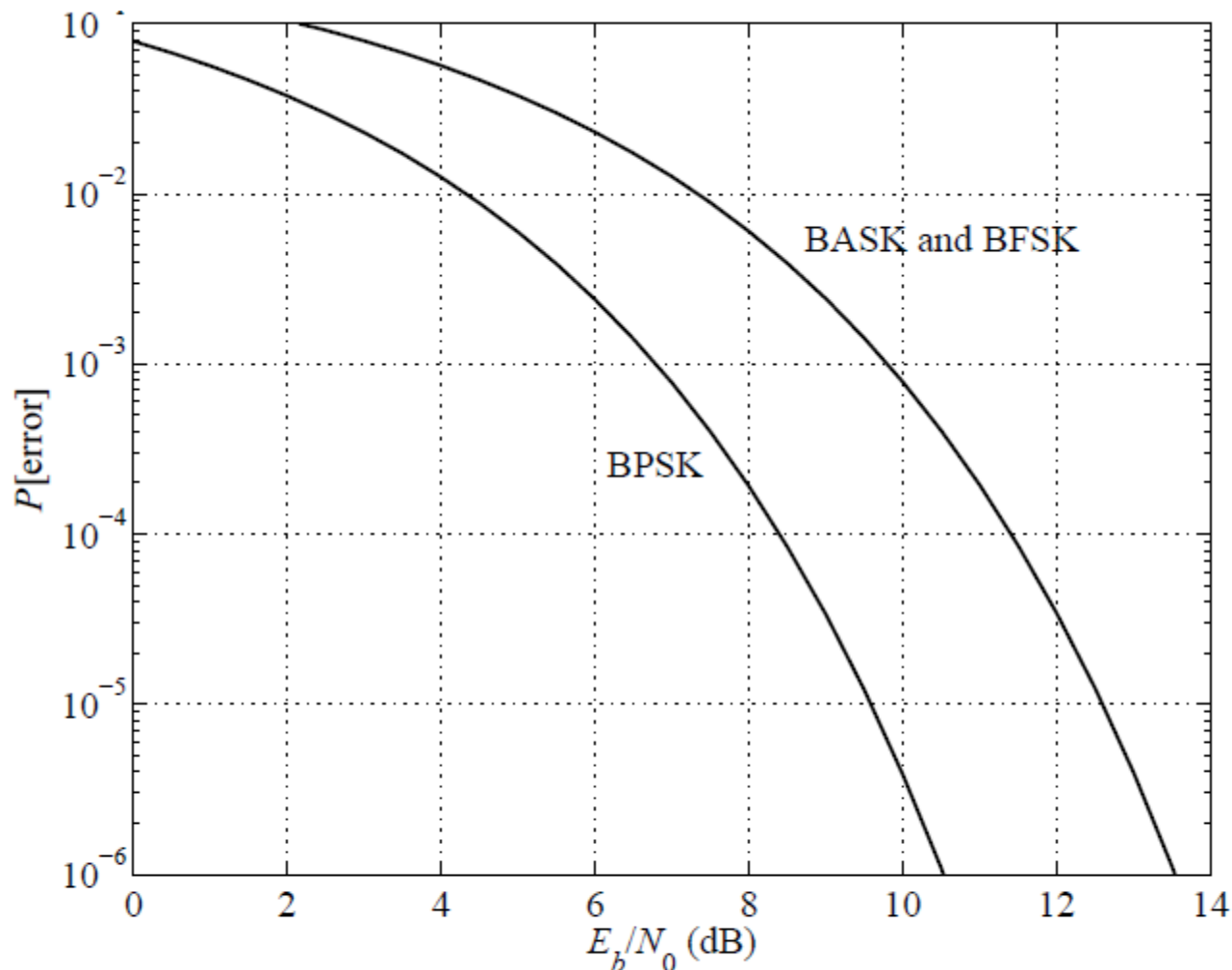


FSK Demodulation (Non-Coherent)





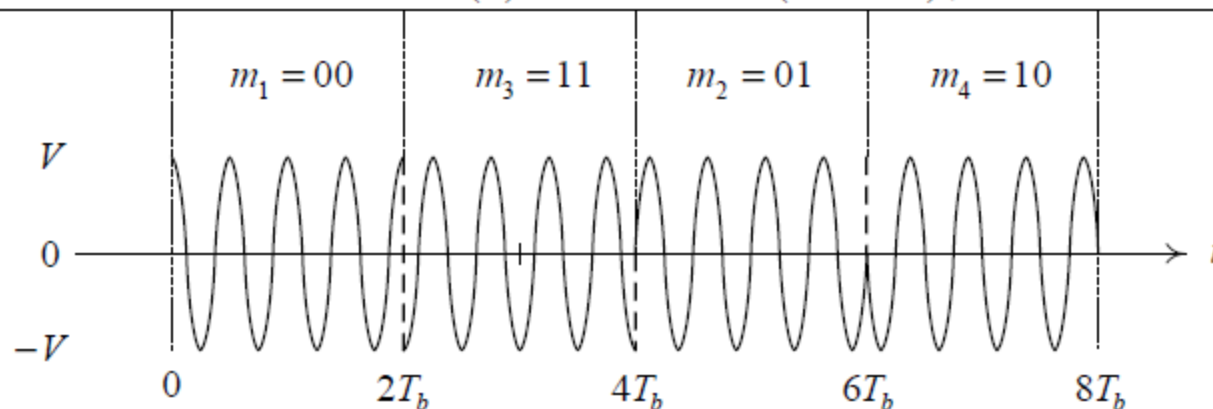
Digital Passband Modulation – Performance Comparison of BASK, BPSK and BFSK



$$P[\text{error}]_{\text{BPSK}} = Q\left(\sqrt{\frac{2E_b}{N_0}}\right), \quad P[\text{error}]_{\text{BASK}} = P[\text{error}]_{\text{BFSK}} = Q\left(\sqrt{\frac{E_b}{N_0}}\right).$$

- Basic idea behind QPSK: $\cos(2\pi f_c t)$ and $\sin(2\pi f_c t)$ are orthogonal over $[0, T_b]$ when $f_c = k/T_b$, k integer \Rightarrow Can transmit two different bits over the same frequency band at the same time.
- The symbol signaling rate (i.e., the *baud rate*) is $r_s = 1/T_s = 1/(2T_b) = r_b/2$ (symbols/sec), i.e., *halved*.

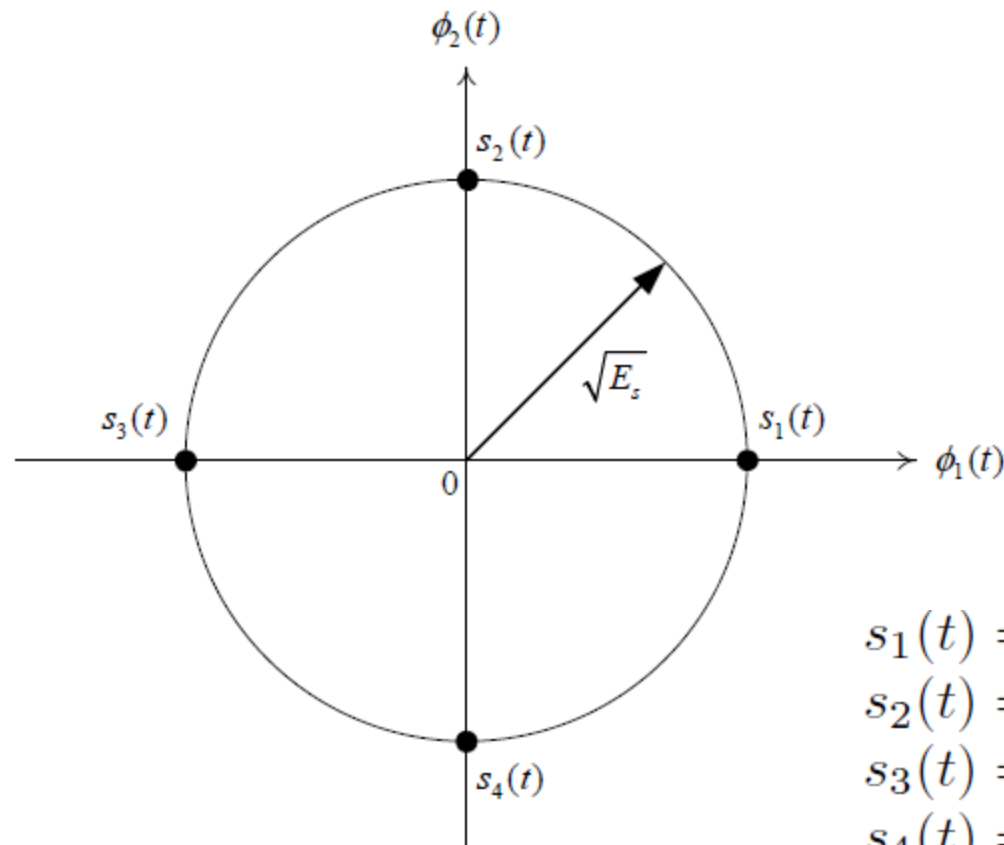
Bit Pattern	Message	Signal Transmitted
00	m_1	$s_1(t) = V \cos(2\pi f_c t), \quad 0 \leq t \leq T_s = 2T_b$
01	m_2	$s_2(t) = V \sin(2\pi f_c t), \quad 0 \leq t \leq T_s = 2T_b$
11	m_3	$s_3(t) = -V \cos(2\pi f_c t), \quad 0 \leq t \leq T_s = 2T_b$
10	m_4	$s_4(t) = -V \sin(2\pi f_c t), \quad 0 \leq t \leq T_s = 2T_b$



Digital Passband Modulation – Signal Space Representation of QPSK

$$\int_0^{T_s} s_i^2(t) dt = \frac{V^2}{2} T_s = V^2 T_b = E_s,$$

$$\phi_1(t) = \frac{s_1(t)}{\sqrt{E_s}}, \quad \phi_2(t) = \frac{s_2(t)}{\sqrt{E_s}}.$$



$$\begin{aligned} s_1(t) &= V \cos(2\pi f_c t), \\ s_2(t) &= V \sin(2\pi f_c t), \\ s_3(t) &= -V \cos(2\pi f_c t), \\ s_4(t) &= -V \sin(2\pi f_c t), \end{aligned}$$

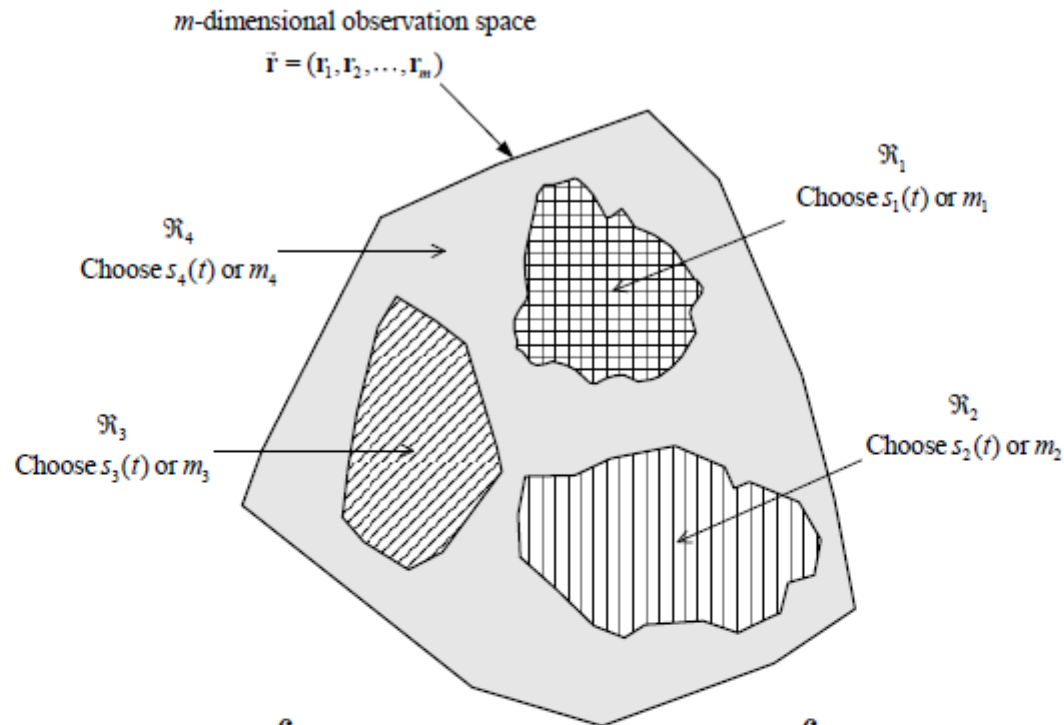
→ $P[\text{error}] = 1 - P[\text{correct}]$ ← **Minimize Error or Maximize correct decision**

$$\rightarrow P[\text{correct}] = P \left[\begin{array}{l} (S_1 \text{ decided and } S_1 \text{ transmitted) or} \\ (S_2 \text{ decided and } S_2 \text{ transmitted) or} \\ (S_3 \text{ decided and } S_3 \text{ transmitted) or} \\ (S_4 \text{ decided and } S_4 \text{ transmitted) or} \end{array} \right]$$

$$= P[S_{1,D}, S_{1,T}] + P[S_{2,D}, S_{2,T}] + P[S_{3,D}, S_{3,T}] + P[S_{4,D}, S_{4,T}]$$

$$= P[S_{1,D} / S_{1,T}] P[S_{1,T}] + P[S_{2,D} / S_{2,T}] P[S_{2,T}] \\ + P[S_{3,D} / S_{3,T}] P[S_{3,T}] + P[S_{4,D} / S_{4,T}] P[S_{4,T}]$$

$$= P_1 \int_{R_1} f(\vec{r} / S_{1,T}) d\vec{r} + P_2 \int_{R_2} f(\vec{r} / S_{2,T}) d\vec{r} + P_3 \int_{R_3} f(\vec{r} / S_{3,T}) d\vec{r} + P_4 \int_{R_4} f(\vec{r} / S_{4,T}) d\vec{r}$$



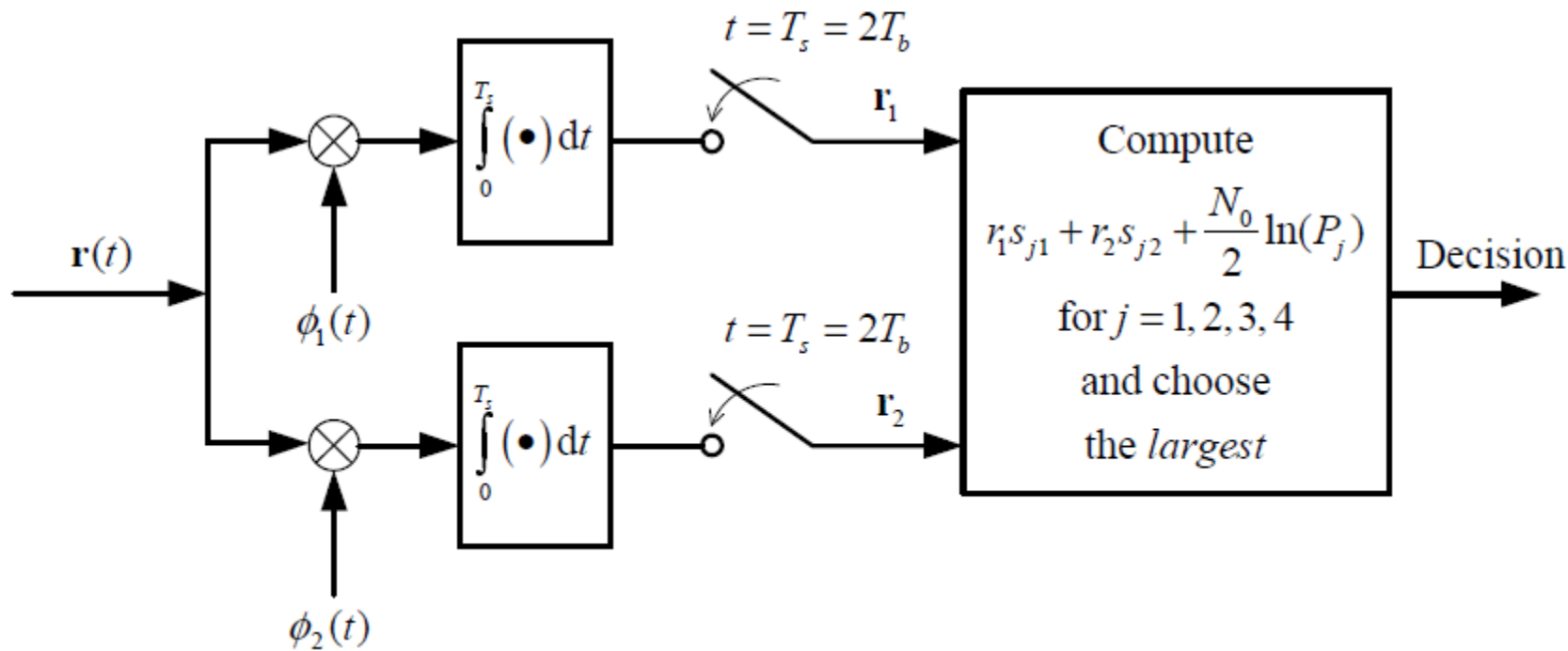
$$\begin{aligned}
 P[\text{correct}] &= \int_{\mathfrak{R}_1} P_1 f(\vec{r}|s_1(t)) d\vec{r} + \int_{\mathfrak{R}_2} P_2 f(\vec{r}|s_2(t)) d\vec{r} \\
 &+ \int_{\mathfrak{R}_3} P_3 f(\vec{r}|s_3(t)) d\vec{r} + \int_{\mathfrak{R}_4} P_4 f(\vec{r}|s_4(t)) d\vec{r}.
 \end{aligned}$$

Choose $s_i(t)$ if $P_i f(\vec{r}|s_i(t)) > P_j f(\vec{r}|s_j(t))$, $j = 1, 2, 3, 4$; $j \neq i$.

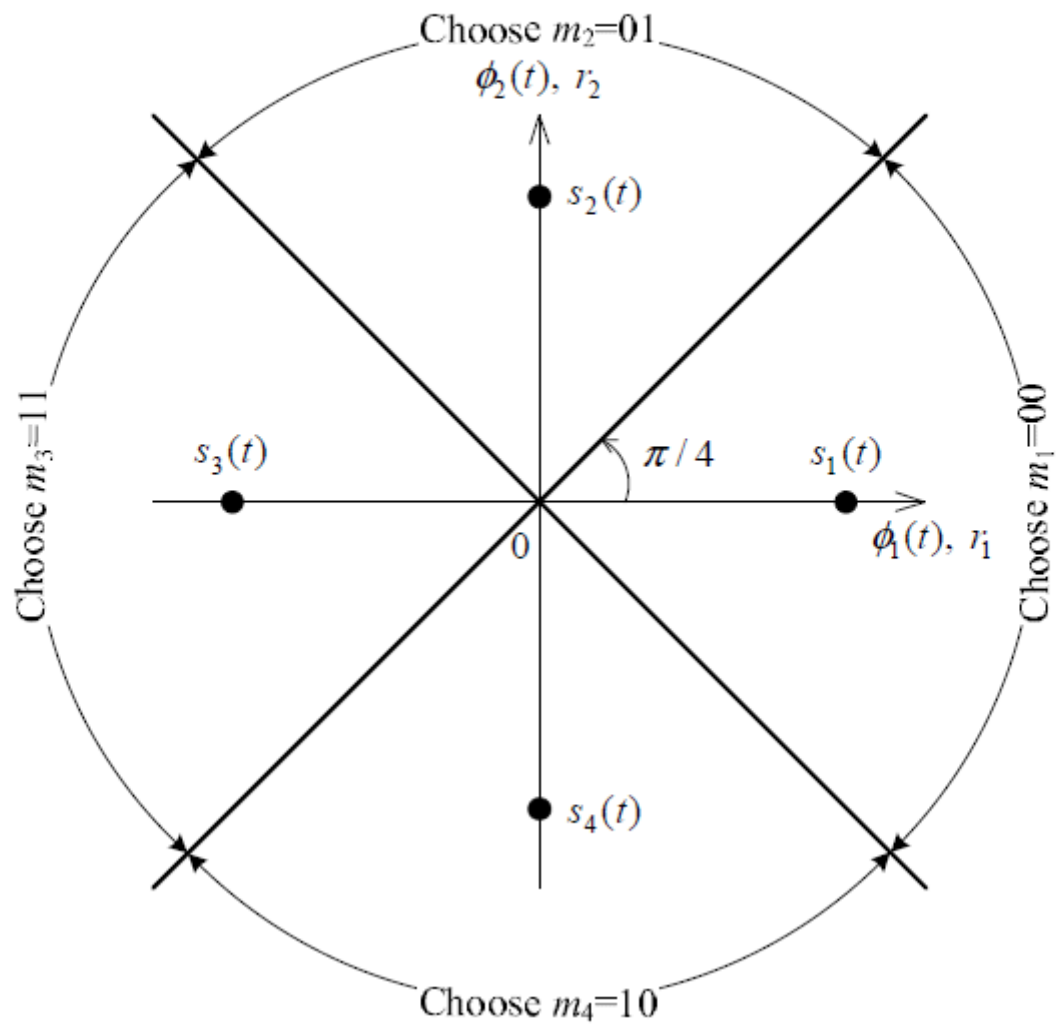


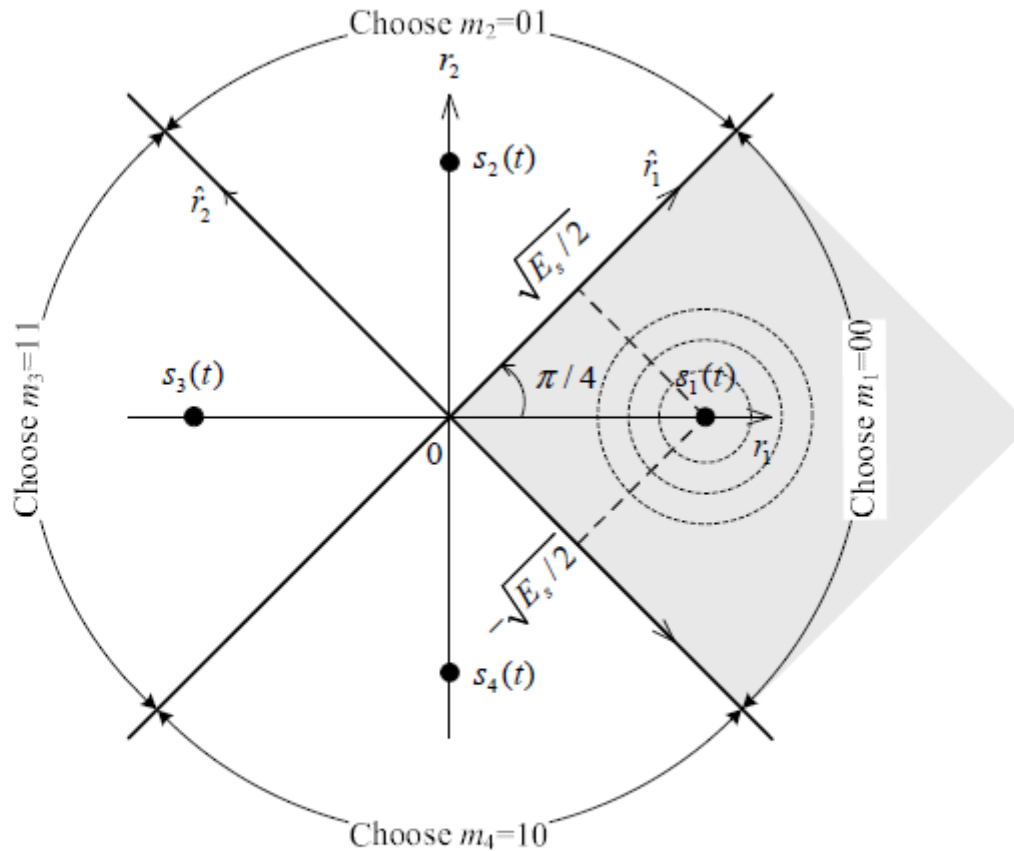
Digital Passband Modulation – Simplified Decision Rule and Receiver Implementation

$$\text{Choose } s_i(t) \text{ if}$$
$$\frac{N_0}{2} \ln P_i + r_1 s_{i1} + r_2 s_{i2} > \frac{N_0}{2} \ln P_j + r_1 s_{j1} + r_2 s_{j2}$$
$$j = 1, 2, 3, 4; j \neq i.$$

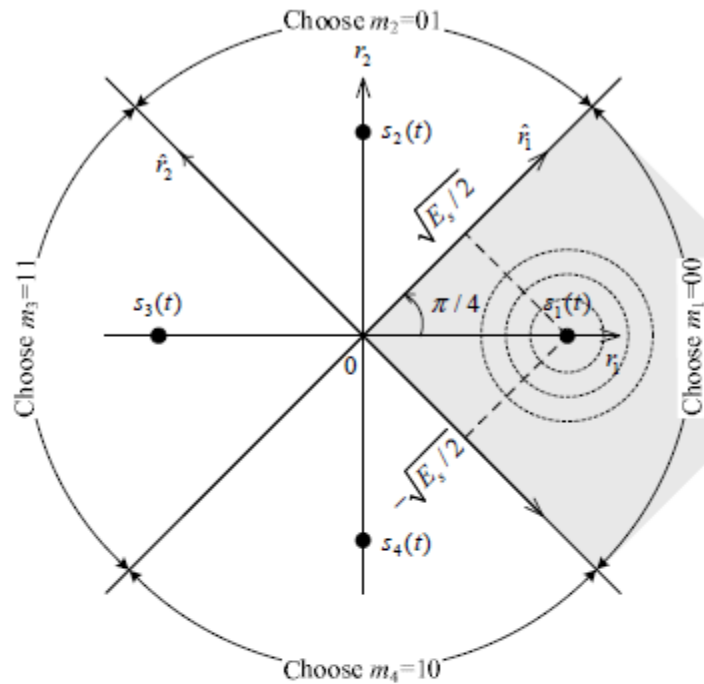


Choose $s_i(t)$ if $(r_1 - s_{i1})^2 + (r_2 - s_{i2})^2$ is the smallest





$$P[\text{error}] = P[\text{error}|s_i(t)] = 1 - P[\text{correct}|s_i(t)] = 1 - \left[1 - Q \left(\sqrt{\frac{E_s}{N_0}} \right) \right]^2$$



$$P[m_2|m_1] = Q\left(\sqrt{\frac{E_s}{N_0}}\right) \left[1 - Q\left(\sqrt{\frac{E_s}{N_0}}\right)\right],$$

$$P[m_3|m_1] = Q^2\left(\sqrt{\frac{E_s}{N_0}}\right),$$

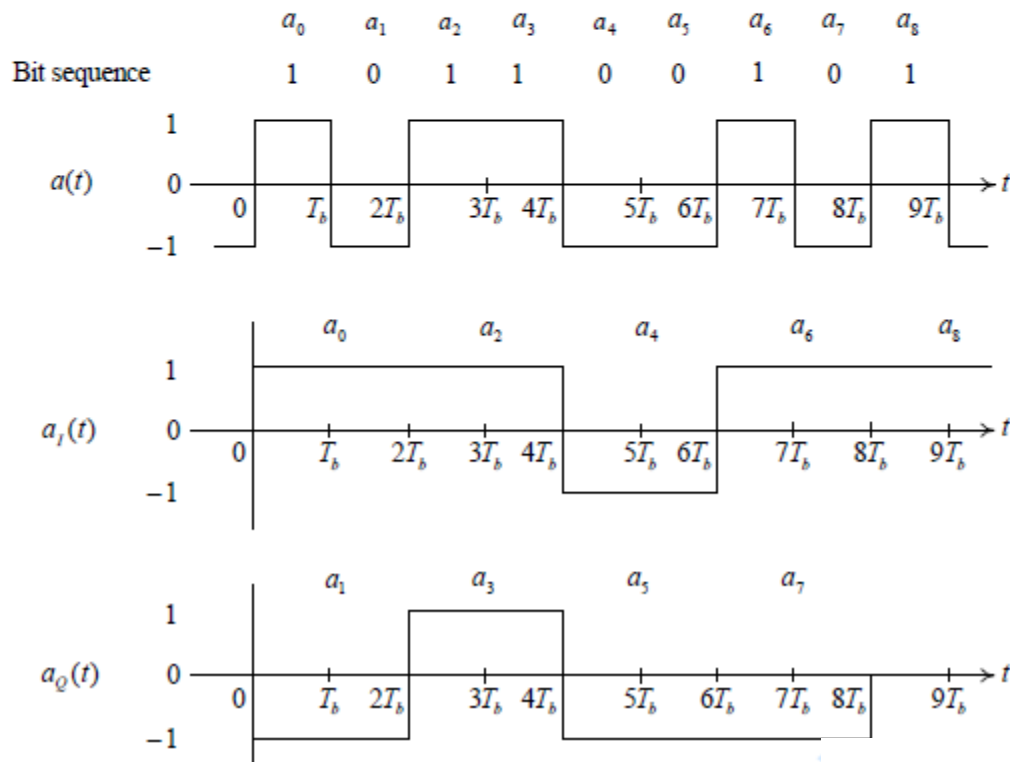
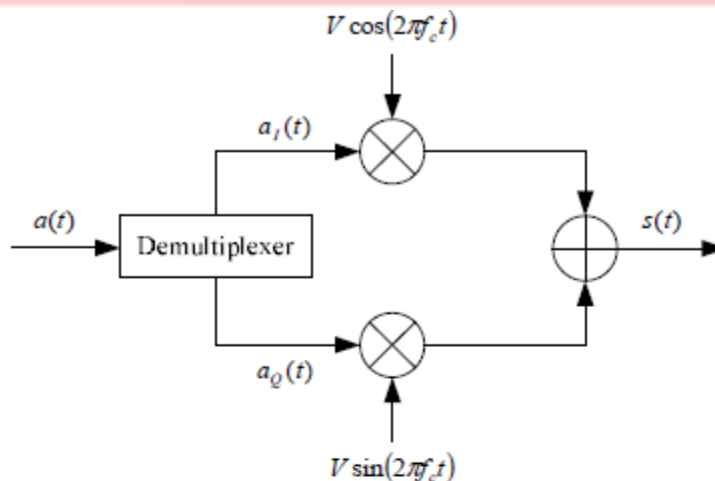
$$P[m_4|m_1] = Q\left(\sqrt{\frac{E_s}{N_0}}\right) \left[1 - Q\left(\sqrt{\frac{E_s}{N_0}}\right)\right].$$

$$\begin{aligned} P[\text{bit error}] &= 0.5P[m_2|m_1] + 0.5P[m_4|m_1] + 1.0P[m_3|m_1] \\ &= Q\left(\sqrt{\frac{E_s}{N_0}}\right). \end{aligned}$$

Gray mapping: Nearest neighbors are mapped to the bit pairs that differ in only one bit.

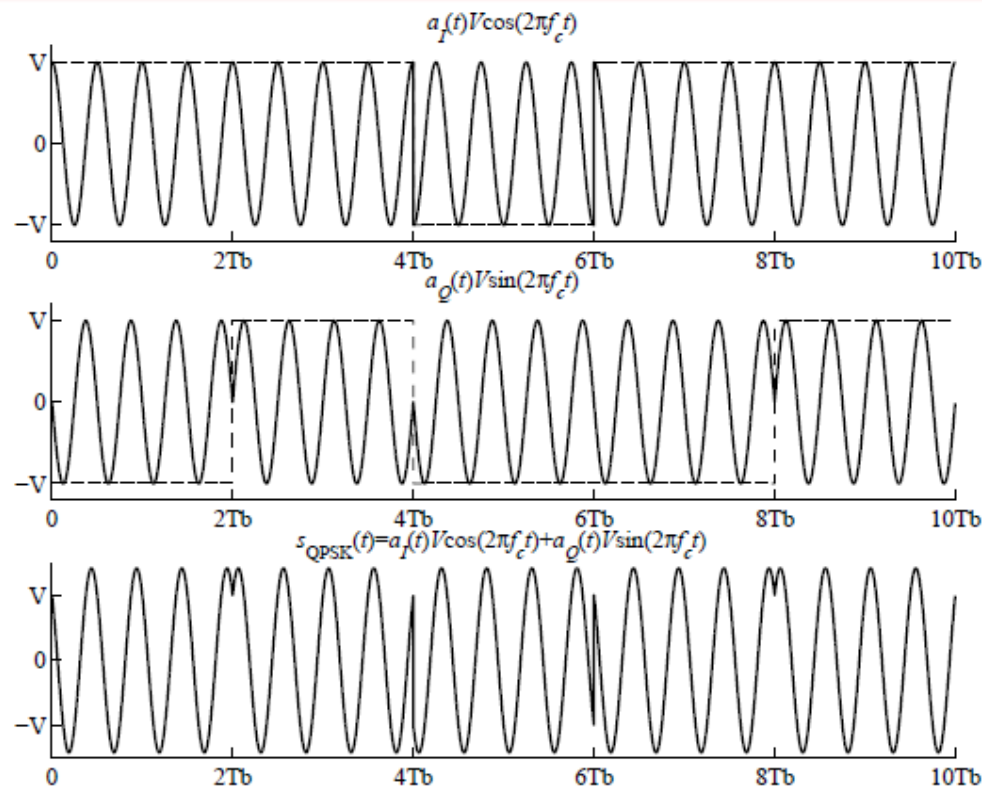


Digital Passband Modulation – An Alternative Representation of QPSK





Digital Passband Modulation – An Alternative Representation of QPSK



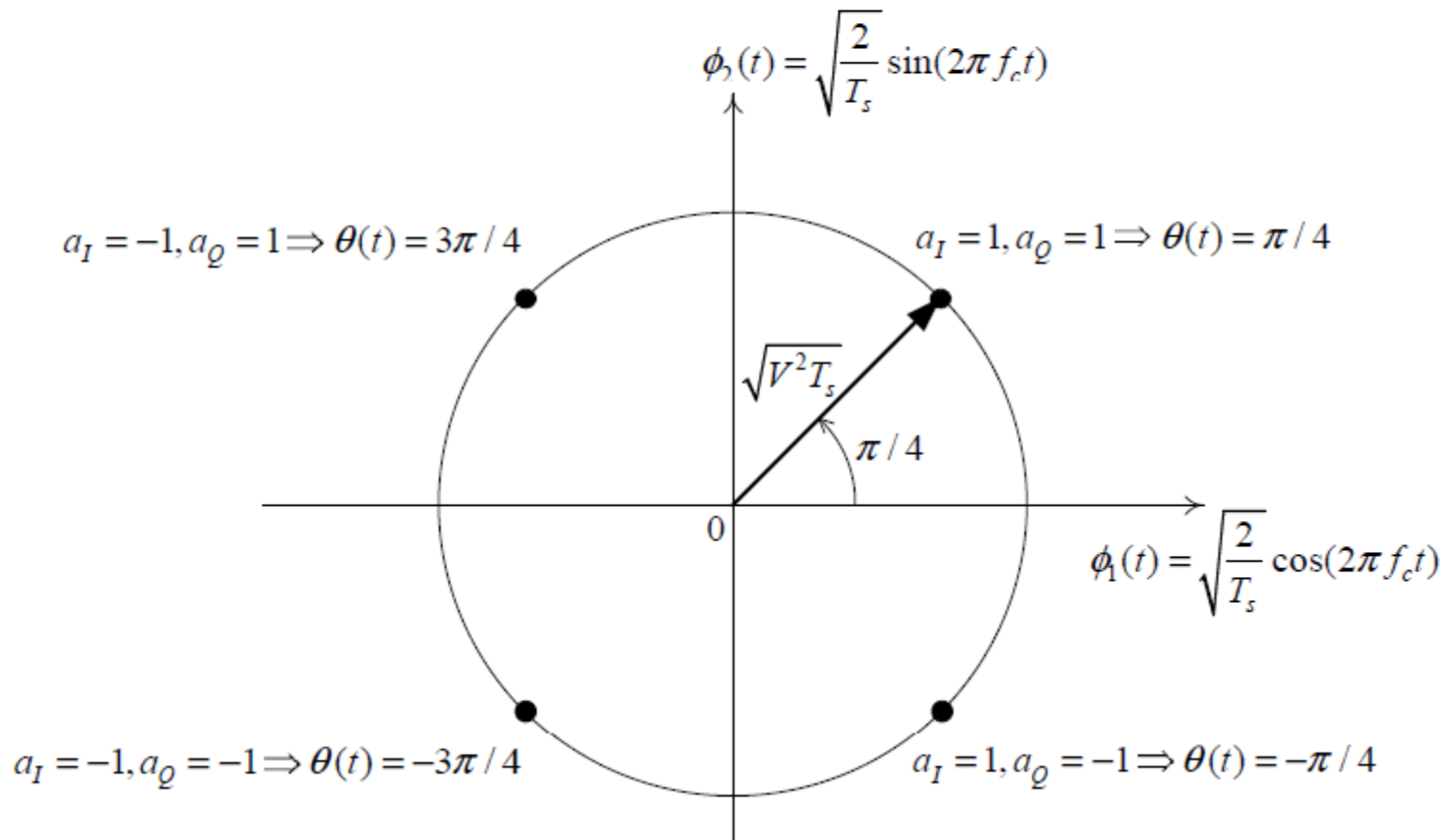
$$\begin{aligned}
 s(t) &= a_I(t)V \cos(2\pi f_c t) + a_Q(t)V \sin(2\pi f_c t) \\
 &= \sqrt{a_I^2(t) + a_Q^2(t)}V \cos\left(2\pi f_c t - \tan^{-1}\left(\frac{a_Q(t)}{a_I(t)}\right)\right) = \sqrt{2}V \cos[2\pi f_c t - \theta(t)].
 \end{aligned}$$

$$\theta(t) = \begin{cases} \pi/4, & \text{if } a_I = +1, a_Q = +1 \text{ (bits are 11)} \\ -\pi/4, & \text{if } a_I = +1, a_Q = -1 \text{ (bits are 10)} \\ 3\pi/4, & \text{if } a_I = -1, a_Q = +1 \text{ (bits are 01)} \\ -3\pi/4, & \text{if } a_I = -1, a_Q = -1 \text{ (bits are 00)} \end{cases} .$$



Digital Passband Modulation – Signal Space Representation of QPSK

$$\begin{cases} \phi_1(t) = \frac{V \cos(2\pi f_c t)}{\sqrt{V^2 T_b}} \\ \phi_2(t) = \frac{V \sin(2\pi f_c t)}{\sqrt{V^2 T_b}} \end{cases}, \quad 0 < t < T_s = 2T_b,$$

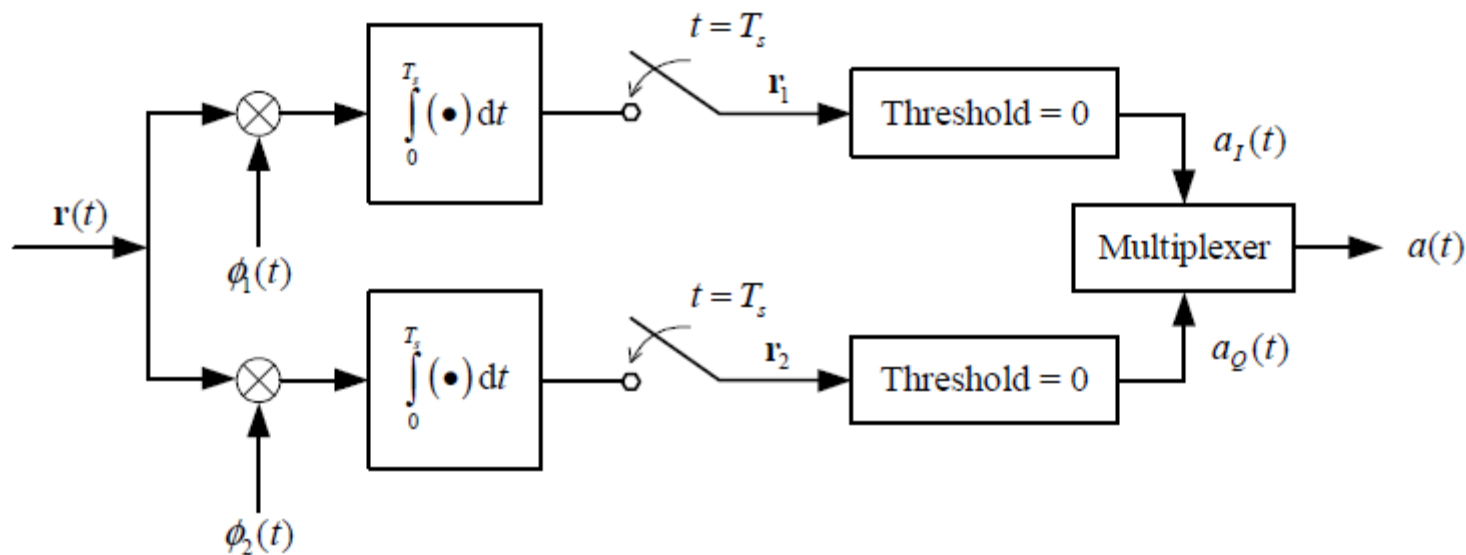
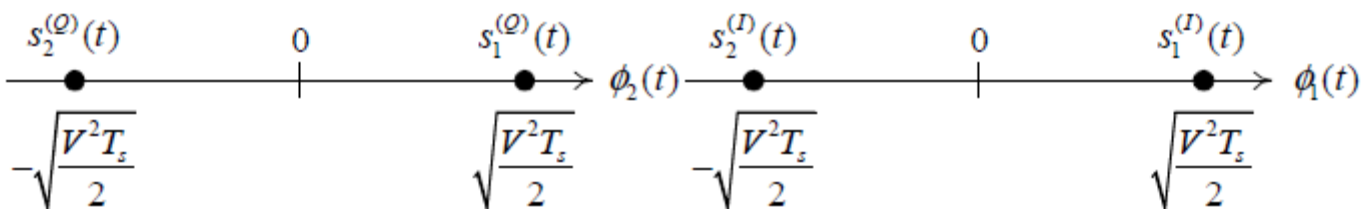




Digital Passband Modulation – Receiver Implementation of QPSK

Quadrature bit stream

Inphase bit stream

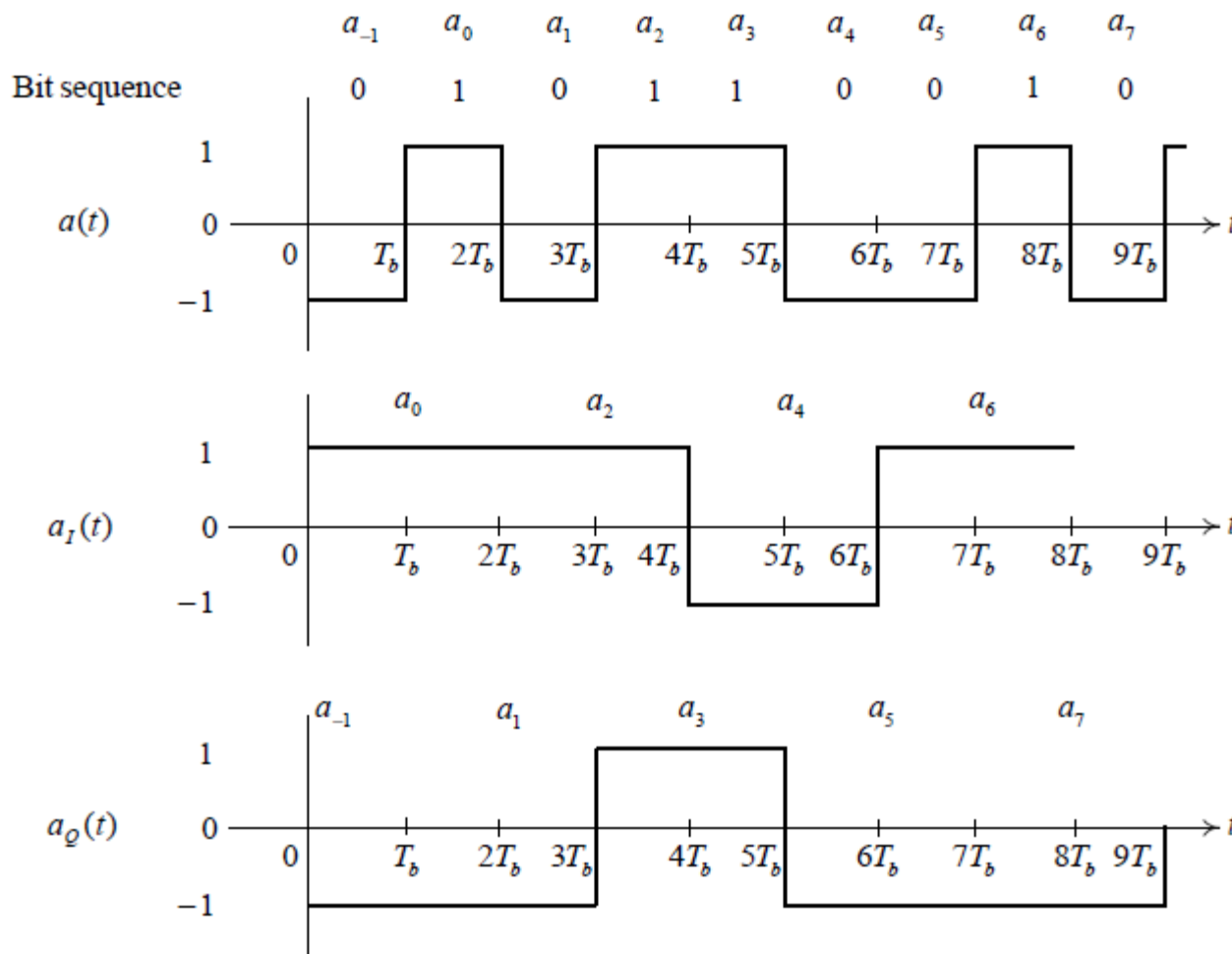


$$P[\text{bit error}] = Q\left(\sqrt{\frac{V^2 T_s}{N_0}}\right) = \dots = Q\left(\sqrt{\frac{2E_b}{N_0}}\right).$$



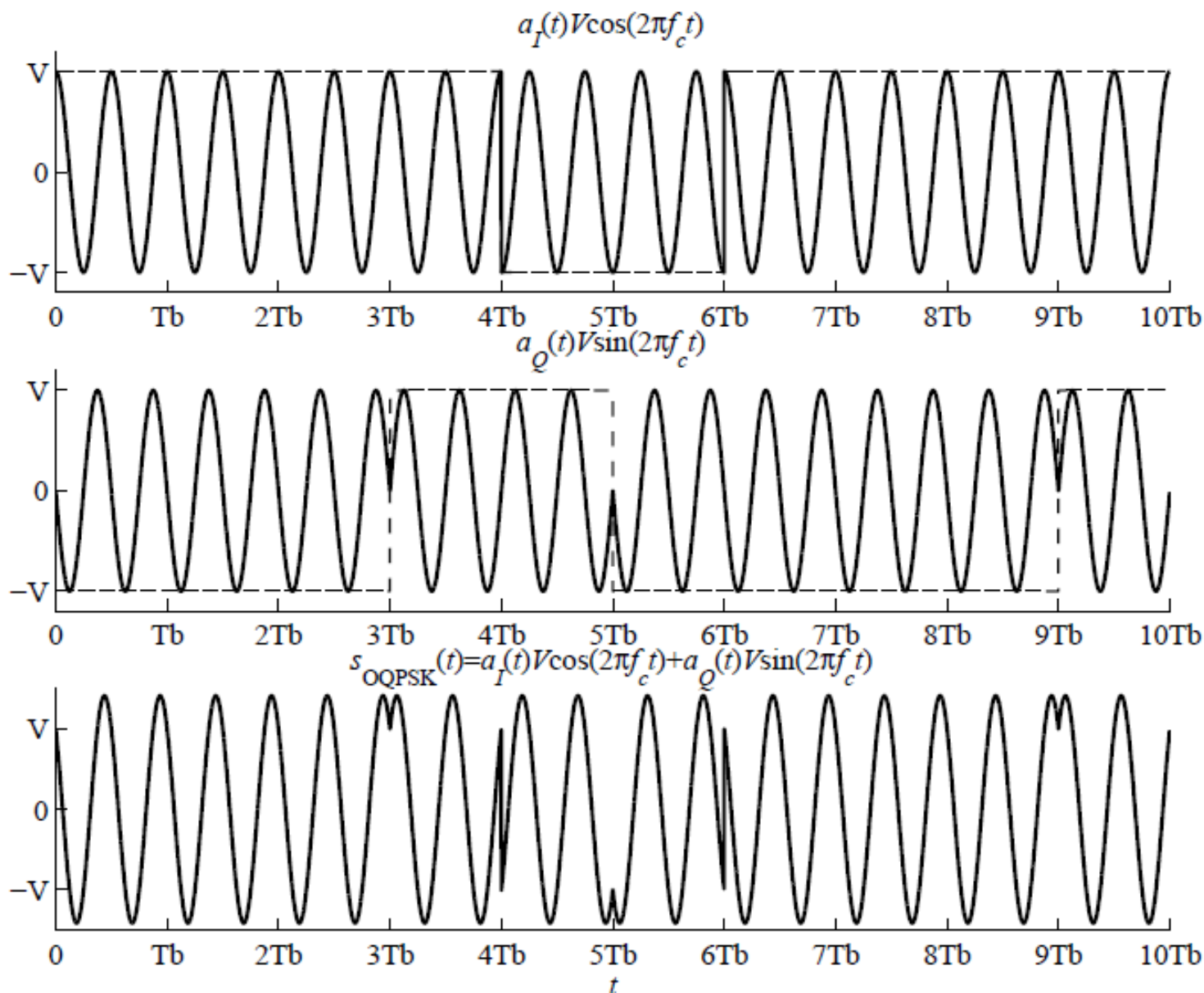
Digital Passband Modulation – Offset Quadrature Phase Shift Keying (OQPSK)

In OQPSK the $a_I(t)$ and $a_Q(t)$ bit streams are offset by one bit interval T_b .





Digital Passband Modulation – Offset Quadrature Phase Shift Keying (OQPSK)

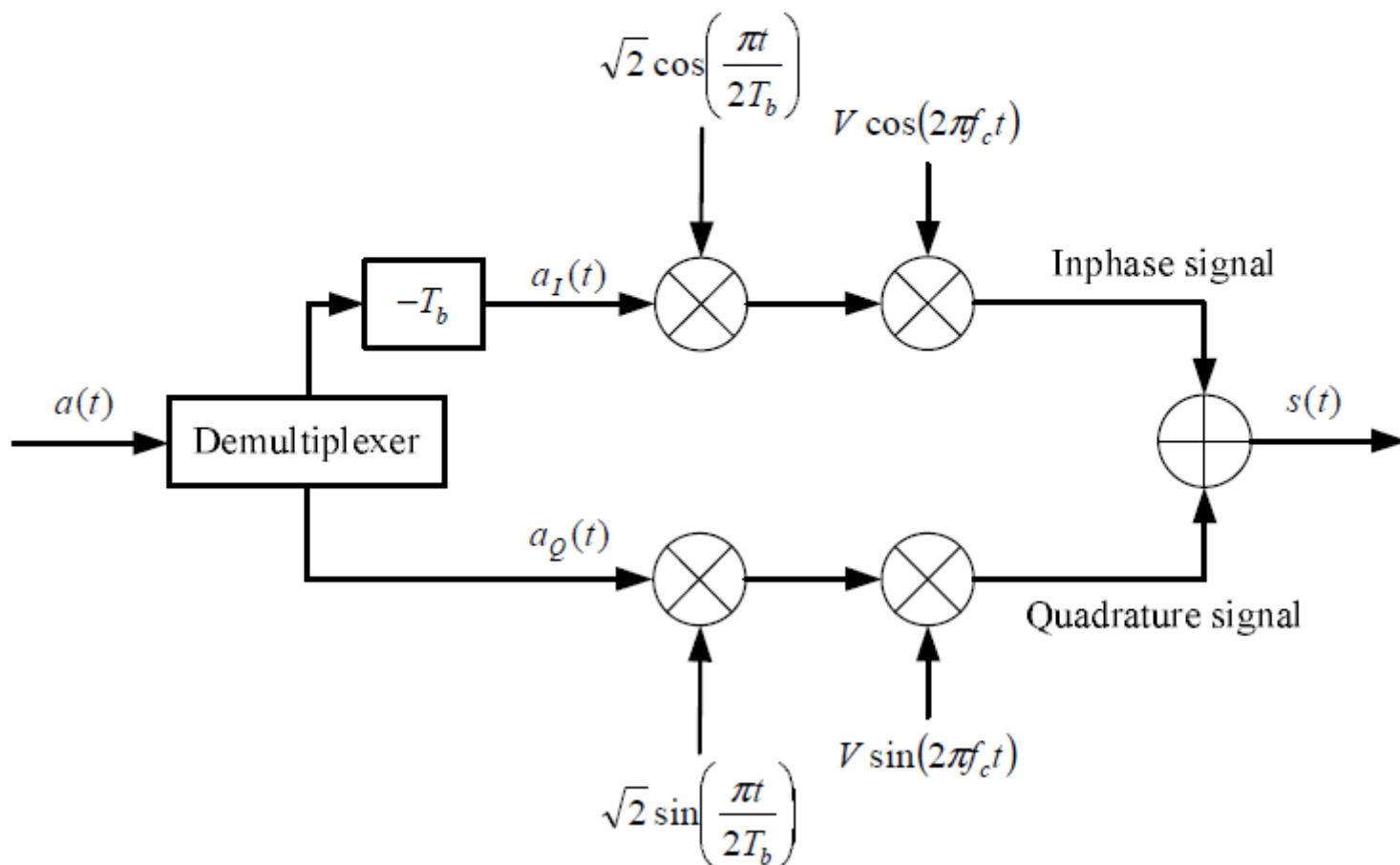




Digital Passband Modulation – Minimum Shift Keying (MSK)

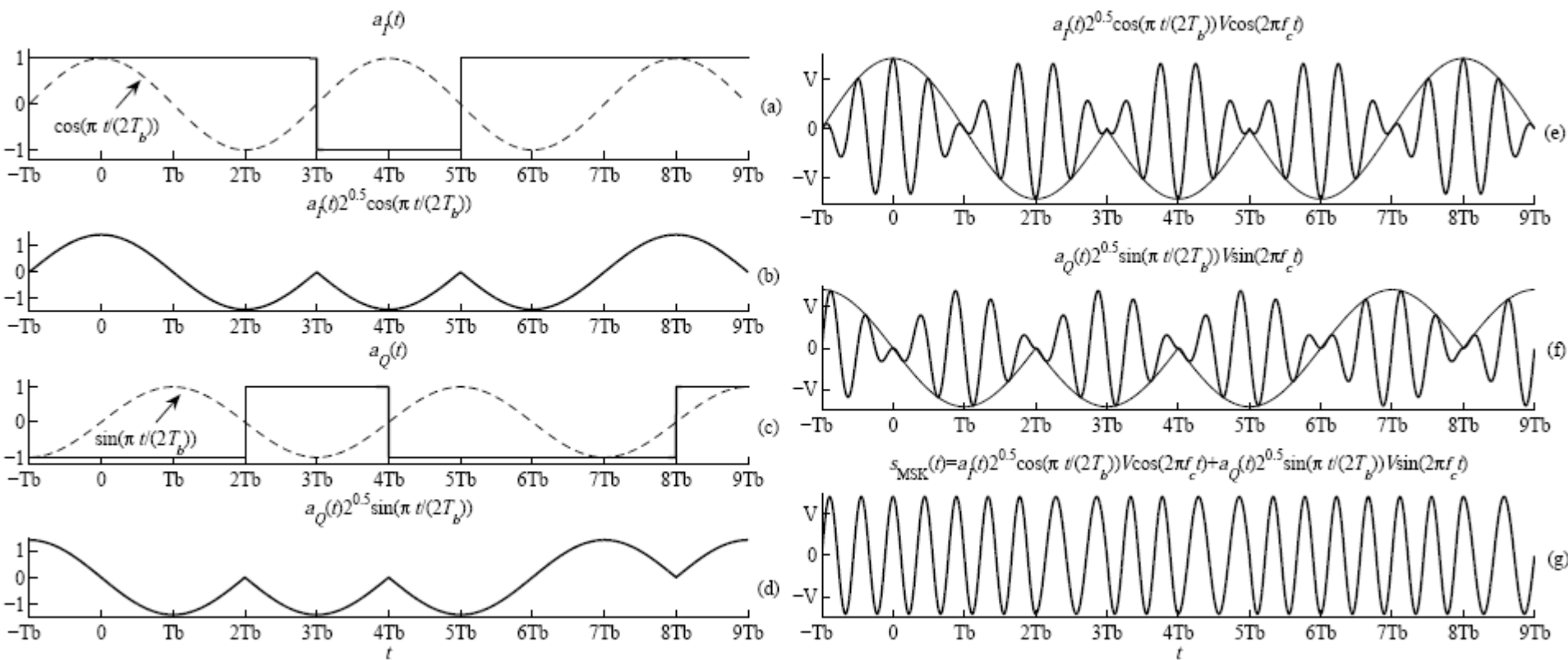
Both QPSK and OQPSK signals have sudden jumps.

MSK eliminates the jumps altogether by applying weighting functions to the carriers $V \cos(2\pi f_c t)$ and $V \sin(2\pi f_c t)$.



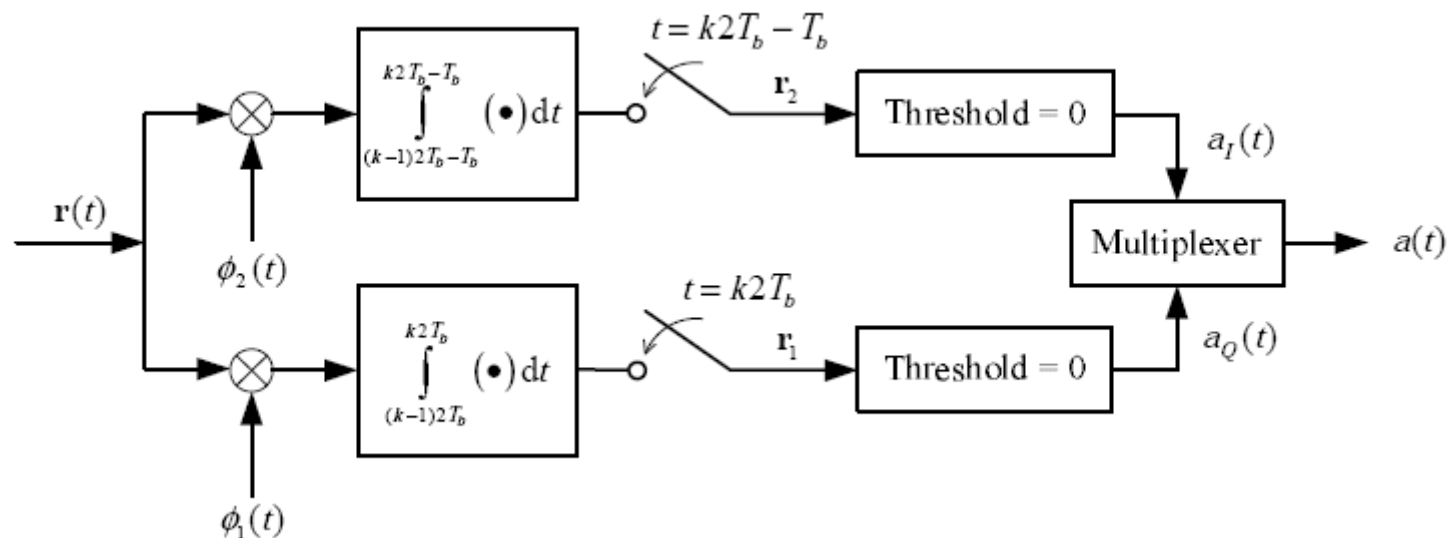


Digital Passband Modulation – Generation of an MSK Signal





Digital Passband Modulation – Block Diagram of MSK Receiver



$$\phi_1(t) = \left[\sqrt{2} \sin\left(\frac{\pi t}{2T_b}\right) V \sin(2\pi f_c t) \right] / \sqrt{V^2 T_b},$$

$$\phi_2(t) = \left[\sqrt{2} \cos\left(\frac{\pi t}{2T_b}\right) V \cos(2\pi f_c t) \right] / \sqrt{V^2 T_b}.$$

$$P[\text{bit error}] = Q\left(\sqrt{\frac{2E_b}{N_0}}\right), \quad E_b = V^2 T_b \text{ is the energy per bit.}$$



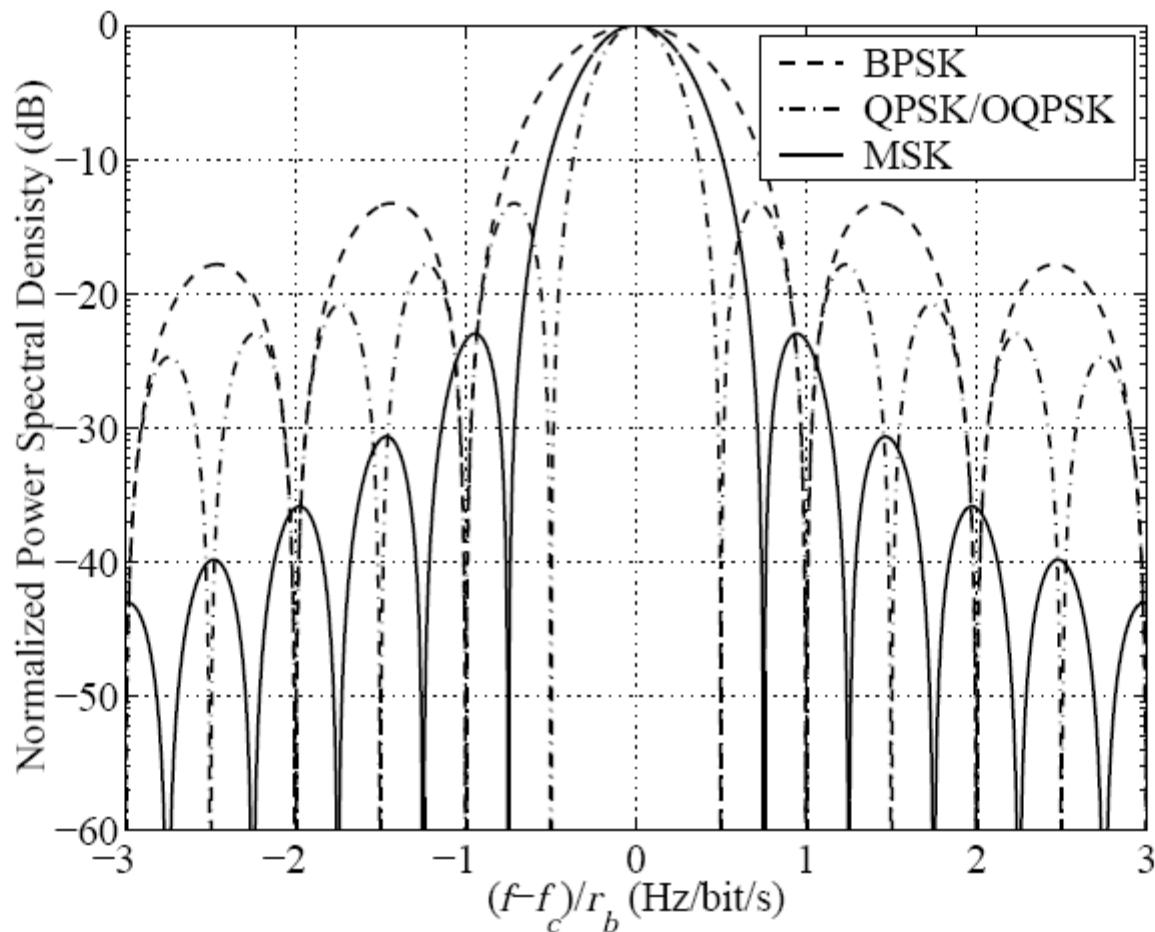
$$\begin{aligned} s(t) &= a_I(t)\sqrt{2} \cos\left(\frac{\pi t}{2T_b}\right) V \cos(2\pi f_c t) + a_Q(t)\sqrt{2} \sin\left(\frac{\pi t}{2T_b}\right) V \sin(2\pi f_c t) \\ &= A \cos(2\pi f_c t - \theta). \end{aligned}$$

$$A = \left[a_I^2(t)2V^2 \cos^2\left(\frac{\pi t}{2T_b}\right) + a_Q^2(t)2V^2 \sin^2\left(\frac{\pi t}{2T_b}\right) \right]^{\frac{1}{2}} = \sqrt{2}V$$

$$\theta = \tan^{-1} \left\{ \frac{a_Q(t) \sin\left(\frac{\pi t}{2T_b}\right)}{a_I(t) \cos\left(\frac{\pi t}{2T_b}\right)} \right\} = \tan^{-1} \left\{ \pm \tan\left(\frac{\pi t}{2T_b}\right) \right\} = \pm \frac{\pi t}{2T_b}.$$

$$\Rightarrow s(t) = \sqrt{2}V \cos \left[2\pi \left(f_c \pm \frac{1}{4T_b} \right) t \right].$$

An MSK signal is of either frequency $f_2 = f_c + \frac{1}{4T_b}$ or $f_1 = f_c - \frac{1}{4T_b} \Rightarrow$ can be viewed as *frequency-shift keying* signal with continuous phase.



$$S_{\text{MSK}}(f) = K \left\{ \left[\frac{\cos[2\pi(f - f_c)T_b]}{4\pi^2(f - f_c)^2 - \pi^2/(4T_b^2)} \right]^2 + \left[\frac{\cos[2\pi(f + f_c)T_b]}{4\pi^2(f + f_c)^2 - \pi^2/(4T_b^2)} \right]^2 \right\}.$$



Digital Passband Modulation – Modulation in 2G Cellular Wireless Systems

	GSM/DCS-1800	IS-54/136	PDC	IS-95
Region	Europe	North America	Japan	North America
Frequency band (MHz)	900/1800/1900	800/1900	700/1500	800/1900
Multiple access	F/TDMA	F/TDMA	F/TDMA	F/CDMA
Carrier spacing (kHz)	200	30	25	1250
Modulation	GMSK	OQPSK	OQPSK	BPSK/QPSK
Speech coding (kb/s)	VSELP (HR-5.6) RPE-LTP (FR-13) ACELP (EFR-12.2)	VSELP (FR-7.95) ACELP (EFR-7.4)	PSI-CELP (HR-3.45) VSELP (FR-6.7)	QCELP (8, 4, 2, 1) RCELP (EVRC)
Frame size (ms)	4.6	40	20	20
Channel coding (convolution code)	Rate 1/2	Rate 1/2	Rate 1/2	Rate 1/2 or 1/3

HR: half-rate codec; FR: full-rate codec; EFR: enhanced full-rate codec; EVRC: enhanced variable rate codec
An adaptive multirate (AMR) codec for GSM is currently being standardized by ETSI

■ **Table 1.** Air interface characteristics of 2G systems.



Digital Passband Modulation – Modulation in 3G CDMA-Based Cellular Systems

Proposal	UTRA	cdma2000	WCDMA/NA	WIMS W-CDMA	W-CDMA	TD-SCDMA	CDMA II	CDMA I
Multiple-access	FDD: DS-CDMA TDD: T/CDMA	FDD: DS-CDMA TDD: T/CDMA	FDD: DS-CDMA TDD: T/CDMA	FDD: DS-CDMA TDD: DS-W-CDMA(FL) DS-S-TDMA (RL)	FDD: DS-CDMA TDD: T/CDMA	TDMA/CDMA	DS-CDMA	DS-CDMA
Duplex scheme	FDD/TDD	FDD/TDD	FDD/TDD	W-CDMA FDD mode: FDD S-TDMA TDD mode: TDD	FDD/TDD	TDD	FDD	FDD
Chip rate (Mc/s)	FDD: 4.096/ 8.192/16.384 TDD: 4.096	1.2288xN Mcps (NX)	FDD: 4.096/8.192/ 16.384 TDD: 4.096	4.096/8.192/ 16.384	1.024/4.096/ 8.192/16.384	1.1136	1.024/4.096/ 8.192/16.384	0.9216/3.6864/ 14.7456
Frame length	10 ms	20/5 ms	10 ms	10 ms	10 ms	5 ms	10 ms	10 ms
Channel coding	Convolutional coding (rate 1/2, 1/3, K = 9); optional outer RS coding (rate TBD)	Convolutional coding (R=1/2, 1/3, 1/4, K = 9); Turbo code of R=1/2, 1/3, 1/4 and K = 4 (pre- ferred for data transmission over 14.4 kb/s on supplemental channel)	Convolutional coding (rate 1/2, 1/3, K = 9); optional outer RS coding (R = 4/5)	Convolutional coding (FL: R = 1/2, K = 7, RL: R = 1/3, K = 9)	Convolutional coding (R = 1/2, 1/3, K = 9); Turbo code of R = 1/3 K = 3 (data transmission over 32 kb/s)	Convolutional coding (R = 3/4, K = 9); optional outer RS code; Turbo code of K = 4, R = 1/2 (preferred for data rate greater than 19.2 kb/s NRT service)	Convolutional coding (R = 1/2, 1/3, 1/4, 1/6, K = 9), select- able FEC for low rate data; Turbo code of R = 1/3 and K = 3 for high rate data and packet data	Convolutional coding R = 1/2, 1/3, 1/4, 1/6); optional outer (47, 41) RS code
Interleaving	Inter/intraframe	Intraframe	Inter/intraframe	Block interleaving (no details given)	Multistage intra or inter- frame	Interframe,	Intraframe	Intraframe
Data modulation	FDD: FL: QPSK, RL: Dual-channel- QPSK; TDD: QPSK (RL&FL)	QPSK (FL) BPSK (RL)	FDD: FL: QPSK, RL: Dual-channel QPSK; TDD: QPSK (RL&FL)	QPSK	FDD: FL: QPSK, RL: Dual-channel QPSK TDD: QPSK	DQPSK, and 16QAM for high data rate	QPSK (FL) BPSK (RL)	FL: QPSK RL: BPSK