

# **Experiment 8**

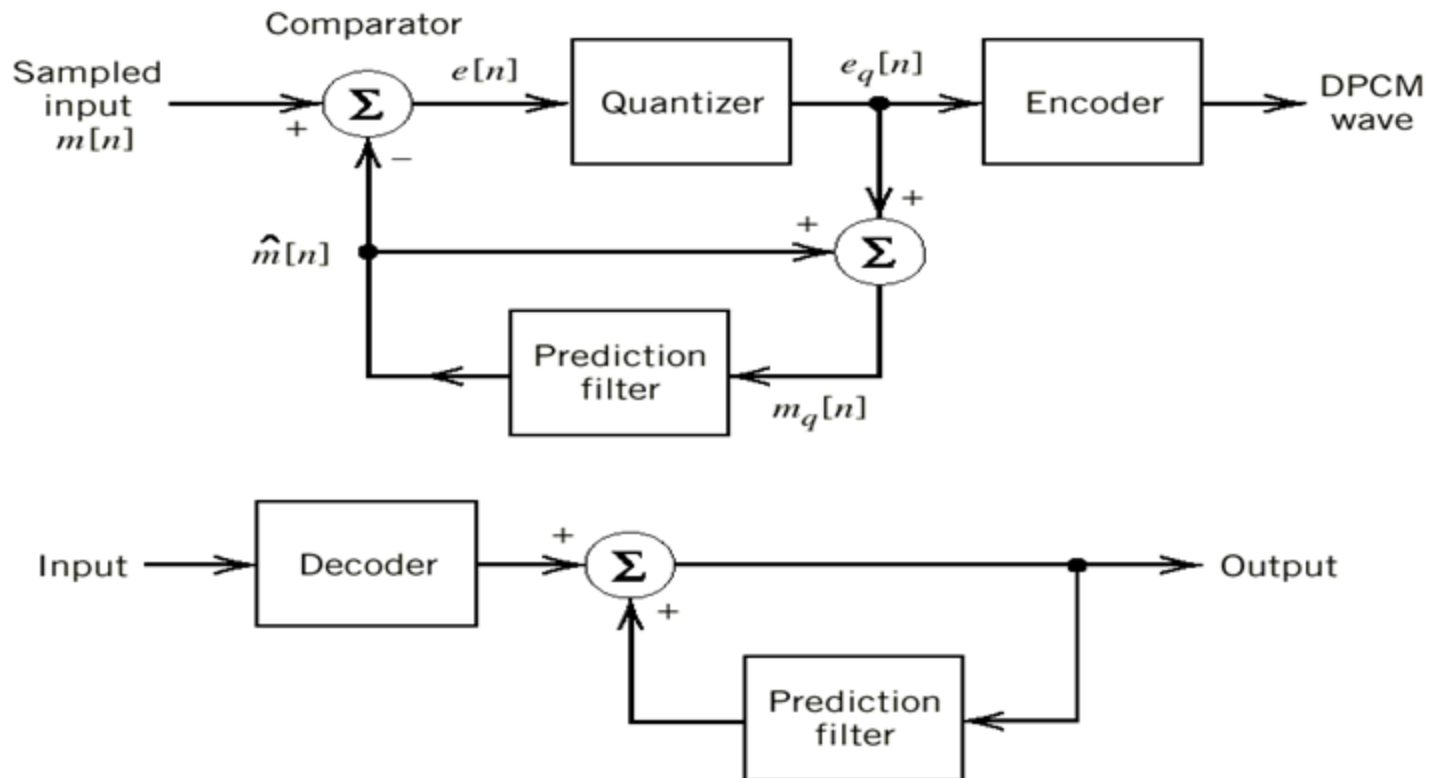
## **Delta Modulation (PCM)**

### **Part 1**

**Prepared by**  
**Dr. Wael Hashlamoun**

# Delta Modulation

- Delta modulation (DM), is a special case of the DPCM.
- The order of the prediction filter is  $p=1$  (and represents only the quantized value of the previous sample )
- In this scheme, the system transmits the sign of the difference between the current and previous samples. The sign is represented by a single bit.



# Delta Modulation: Basic Operation

Let  $m[n] = m(nT_s)$  ,  $n = 0, \pm 1, \pm 2, \dots$

where  $T_s$  is the sampling period and  $m(nT_s)$  is a sample of  $m(t)$ .

The error signal is

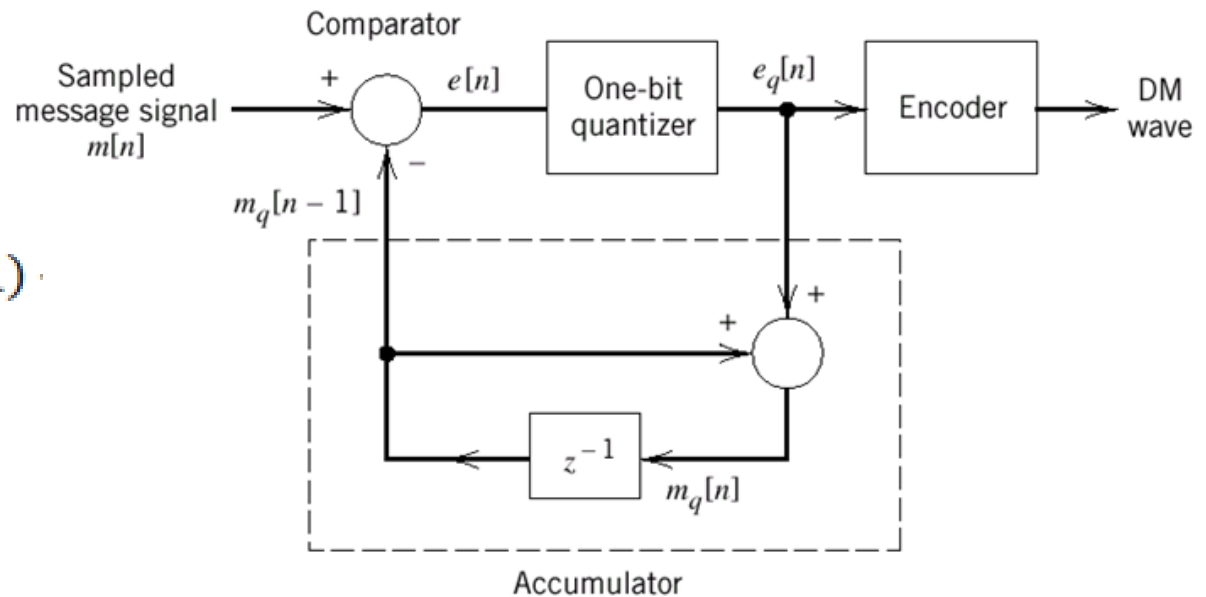
$$e[n] = m[n] - m_q[n-1]$$

$$e_q[n] = \Delta \text{sgn}(e[n]) ; \text{ quantized error}$$

$$m_q[n] = m_q[n-1] + e_q[n]$$

where  $m_q[n]$  is the quantizer output ,  $e_q[n]$  is the quantized version of  $e[n]$  ,  
and  $\Delta$  is the step size

$$\hat{x}(n) = w_1 x(n-1) \cdot$$

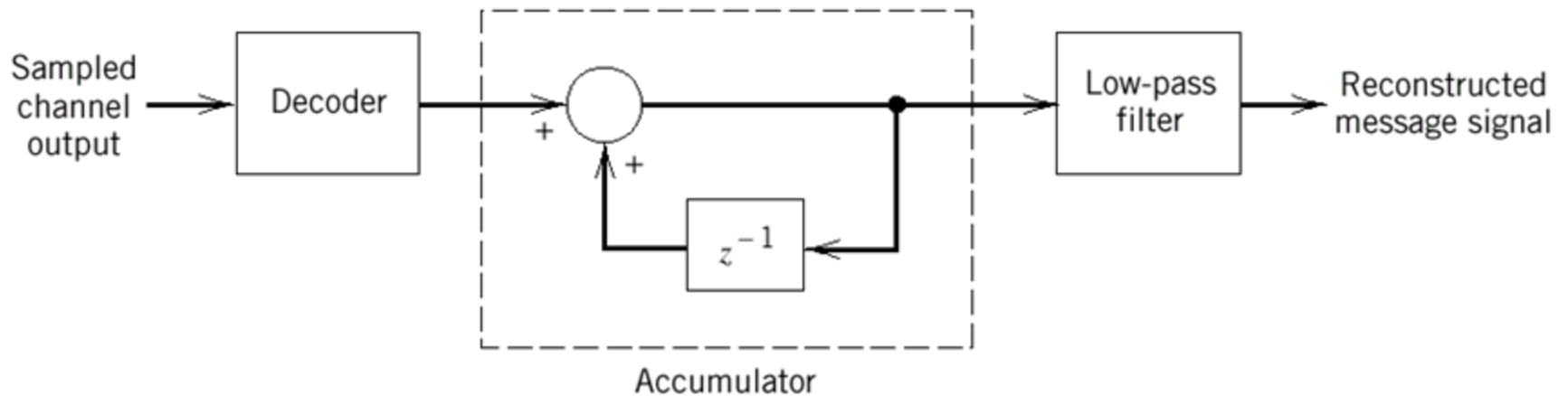


# Delta Modulation: Basic Operation

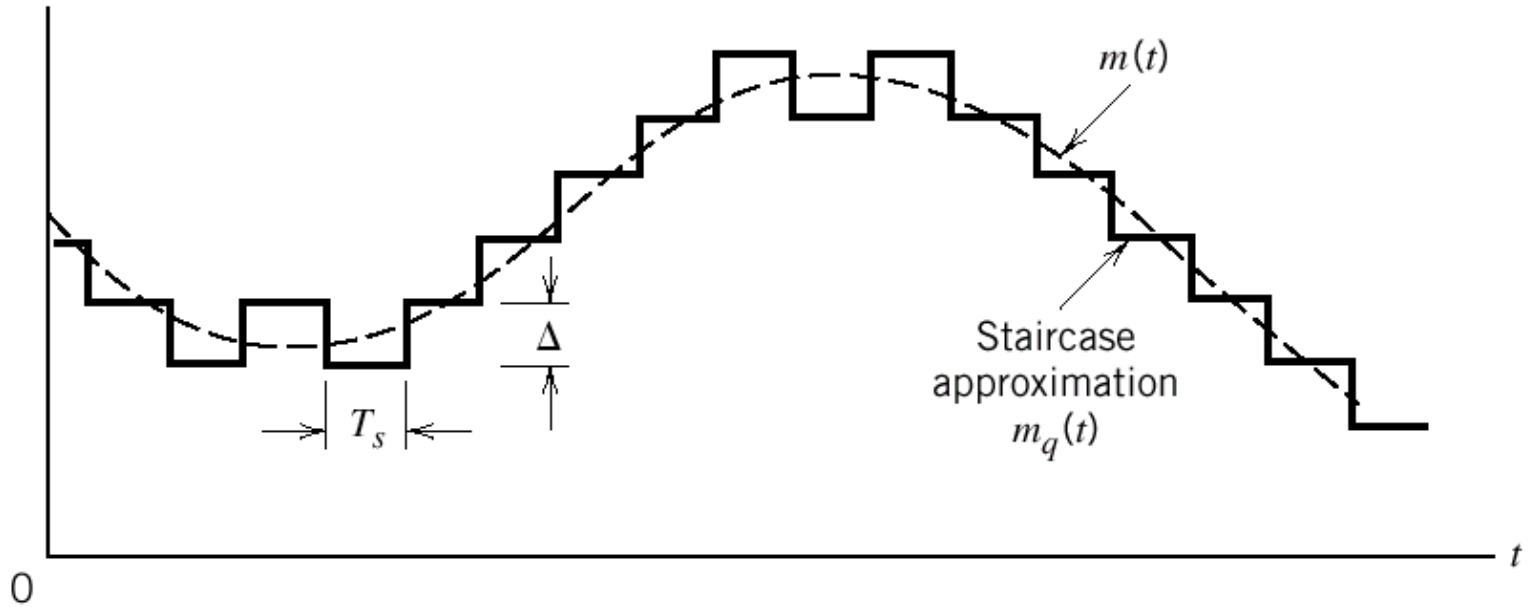
$$m_q[n] = m_q[n-1] + e_q[n]$$

$$\Rightarrow m_q[n] = \Delta \sum_{i=1}^n \text{sgn}(e[i])$$

$$= \sum_{i=1}^n e_q[i]$$



# Delta Modulation: Basic Operation



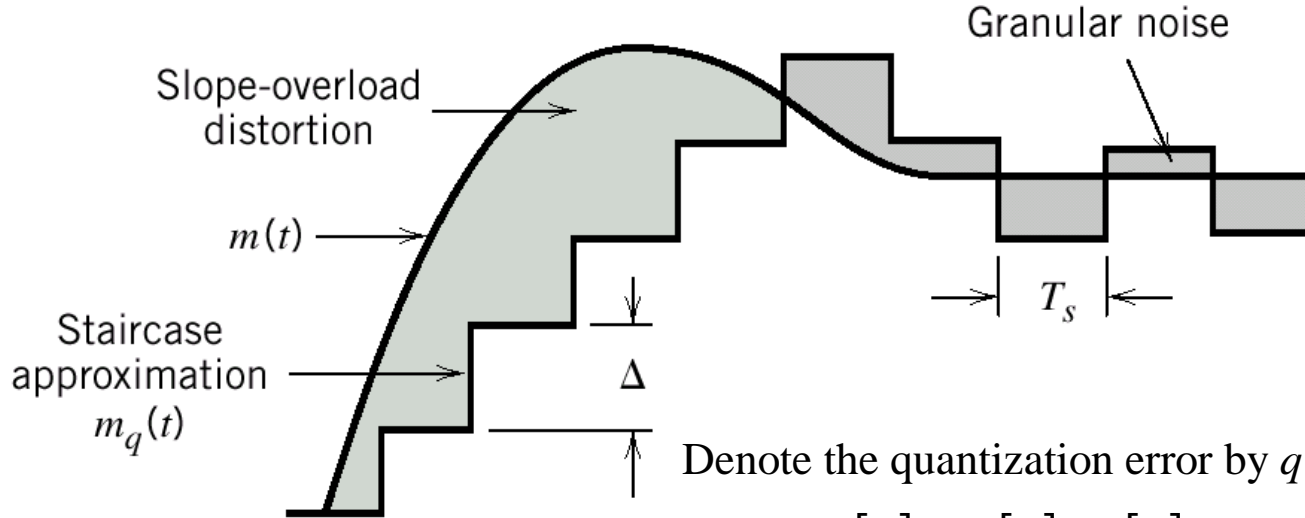
(a)

Binary  
sequence  
at modulator  
output

0 0 1 0 1 1 1 1 1 0 1 0 0 0 0 0 0

(b)

# Slope overload distortion and granular noise



Denote the quantization error by  $q[n]$ ,

$$m_q[n] = m[n] - q[n]$$

We have

$$e[n] = m[n] - m[n-1] - q[n-1]$$

Except for  $q[n-1]$ , the quantizer input is a first backward difference of the input signal (i.e., a differentiator)

To avoid slope-overload distortion, we require

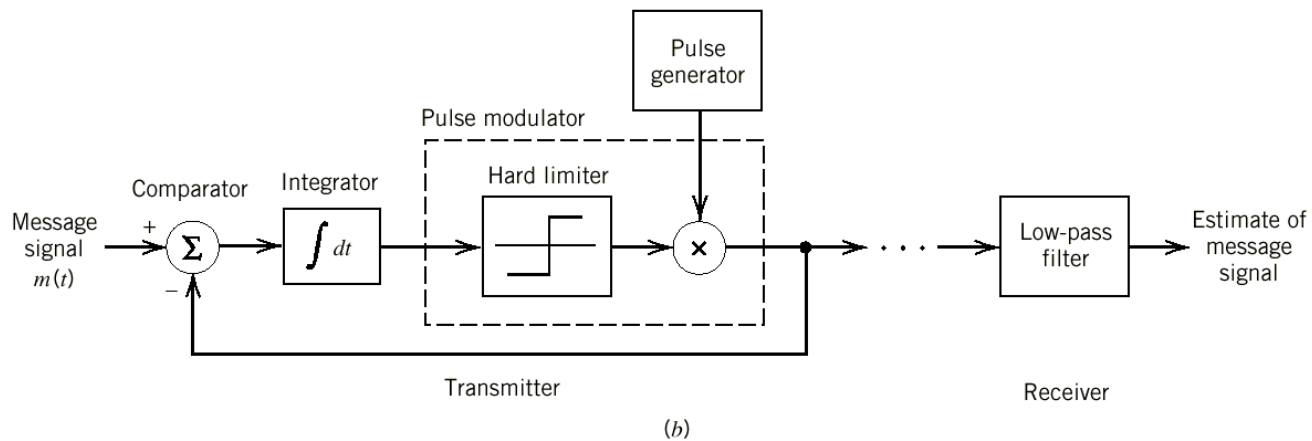
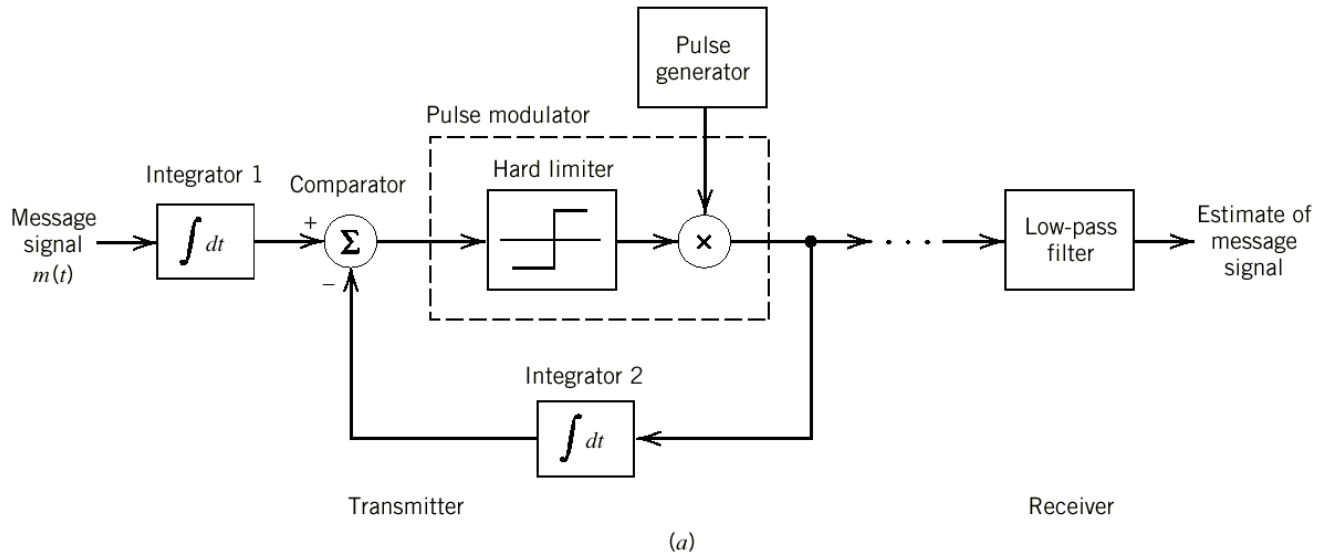
$$\text{(slope)} \quad \frac{\Delta}{T_s} \geq \max \left| \frac{dm(t)}{dt} \right|$$

On the other hand, granular noise occurs when step size  $\Delta$  is too large relative to the local slope of  $m(t)$ .

# Delta-Sigma modulation (sigma-delta modulation)

- The modulation which has an integrator can relieve the drawback of delta modulation (differentiator)
- Beneficial effects of using integrator:
- Pre-emphasize the low-frequency contents of the message  $M(f)/j2\pi f$ . Low frequencies are enhanced while high frequencies are attenuated.
- Increase correlation between adjacent samples (reduce the variance of the error signal at the quantizer input)
- Simplify receiver design because the transmitter has an integrator, the receiver consists simply of a low-pass filter. (The differentiator in the conventional DM receiver is cancelled by the integrator )

# Delta-Sigma modulation (sigma-delta modulation)





# Adaptive Delta Modulation

- The step size in delta modulation affects the quality of the transmitted waveform (slope overload or granular noise).
- A larger step-size is needed in the steep slope of modulating signal
- a smaller stepsize is needed where the message has a small slope
- In adaptive delta modulation, the step size is adjusted via a feedback control signal so as to reduce both slope overload and granular noise effects.

# Adaptive Delta Modulation

- The gain of the voltage controlled amplifier is adjusted by the output signal from the sampler. The amplifier gain determines the step-size.
- ADM quantizes the difference between the value of the current sample and the predicted value of the next sample. It uses a variable step height to predict the next values, for the faithful reproduction of the fast varying values.

