

lec 0

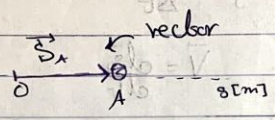
Chapter 12: Kinematics of a particle

Position / velocity
acceleration / time

object with a Mass
no dimensions
- Transition only
- No Rotation

12-2. Rectilinear Kinematics: Continuous Motion

1) Position

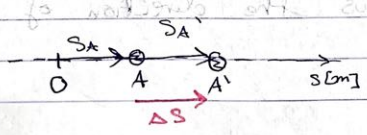


Def: Vector Quantity Representing the location of a particle with respects to an Origin

$|s_A|$ = distancia between O and the Particle.

Direction is arbitrary usually $\begin{matrix} \leftarrow + \\ \rightarrow + \\ \downarrow - \end{matrix}$

2) Displacement ... vector

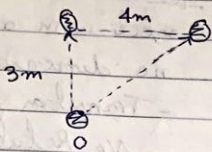


$\vec{\Delta s} = \vec{s}_{A'} - \vec{s}_A$

In this Example:

- Δs is positive when motion is to the right.
- Δs is negative when motion is to the left.

Difference between distance and displacement



- $|\text{disp}| = 5\text{m} = 3\mathbf{i} + 4\mathbf{j}$
- distance 7m

Unit: $[\text{m}]$, $[\text{ft}]$.

3) Velocity:

a) Average Velocity $\vec{V}_{\text{avg}} = \frac{\Delta \vec{S}}{\Delta t}$

b) Instantaneous Velocity $\vec{V} = \frac{d\vec{S}}{dt}$

c) Speed: Magnitude of velocity V_{sp}

d) Average speed $(V_{\text{sp}})_{\text{avg}} = \frac{S_{\text{T}}}{\Delta t}$

where S_{T} : total distance travelled.

Unit: $[\text{m/s}]$ or $[\text{ft/s}]$

Note: Direction of \vec{V} and \vec{V}_{avg} is the same as the displacement (it shows the direction of motion)

4) Acceleration

a) Average acceleration: $\vec{a}_{\text{avg}} = \frac{\Delta \vec{V}}{\Delta t} = \frac{\vec{V}_2 - \vec{V}_1}{\Delta t}$

b) Instantaneous Acceleration: $\vec{a} = \frac{d\vec{v}}{dt} = \frac{d^2\vec{s}}{dt^2}$

Unit: $[m/s^2]$ or $[ft/s^2]$.

! التسارع لا يدل على اتجاه الحركة.

- if $v_2 > v_1$ $\vec{a} +$ (accelerating Motion)
- if $v_1 < v_2$ $\vec{a} -$ (decelerating Motion)

Now:

$$\vec{v} = \frac{d\vec{s}}{dt} \rightarrow dt = \frac{d\vec{s}}{v}$$

$$\vec{a} = \frac{d\vec{v}}{dt}$$

$$\vec{a} = \frac{v \, d\vec{v}}{d\vec{s}}$$

$$\int_{s_1}^{s_2} \vec{a} \, ds = \int_{v_1}^{v_2} \vec{v} \, dv$$

$$v_2^2 + v_1^2 = v^2$$

$$v_2^2 + v_1^2 = v^2$$

$s = \text{Dis}$

$$v(t) = t^2 - t + 2 = 0$$

$$v = v_0 + at$$

$$v^2 = v_0^2 + 2as$$

lec 2:

• Constant Motion with Constant Acceleration.

1) Velocity: $[2148]$ in $[22mm]$ kind

$$\vec{a} = \frac{d\vec{v}}{dt}$$

$$\int_0^t \vec{a}_c dt = \int_{v_1}^{v_2} d\vec{v} \quad \vec{a}_c = \vec{a} \quad \vec{v}_1 = v_1 \quad \vec{v}_2 = v_2$$

$$a_c t = v_2 - v_1$$

$$v_2 = v_1 + a_c t$$

2) Position as a function of time

$$\vec{v} = \frac{d\vec{s}}{dt}$$

$$\int_0^t \vec{v} dt = \int_{s_1}^{s_2} d\vec{s}$$

$$\int_0^t (v_1 + a_c t) dt = s_2 - s_1$$

$$v_1 t + a_c \frac{t^2}{2} = s_2 - s_1$$

$$v_1 t + a_c \frac{t^2}{2} = \Delta s$$

$$s_2 = s_1 + v_1 t + \frac{1}{2} a_c t^2$$

3)

$$\vec{a} ds = \vec{v} dv$$

$$\int_{s_1}^{s_2} a_c ds = \int_{v_1}^{v_2} \vec{v} dv$$

$$a_c (s_2 - s_1) = \frac{v_2^2 - v_1^2}{2} \Rightarrow v_2^2 = v_1^2 + 2a_c \Delta s$$

12.17 :-

- a particle
- Straight line Motion.
- $a = 2b - 1$
- $S = 1m$
 $V = 2m/s$ } $t = 0$

Determine S, V at $t = 6s$
 S_T : total distance travelled.

$$a = \frac{dv}{dt}$$

$$\int a dt = \int dv$$

$$\int (2b - 1) dt = \int dv$$

$$b^2 - t = v - 2 \Rightarrow v(t) = b^2 - t + 2$$

at $t = 6s$:-

$$V = 32 m/s$$

$$V = \frac{ds}{dt}$$

$$v dt = ds$$

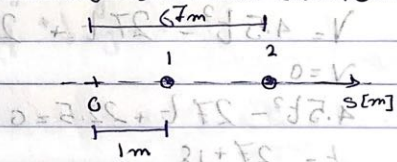
$$\int (b^2 - t + 2) dt = \int ds$$

$$\frac{b^3 t}{3} - \frac{t^2}{2} + 2b = s - 1$$

at $t = 6$:

$$S = 67m$$

Total distance travelled :-



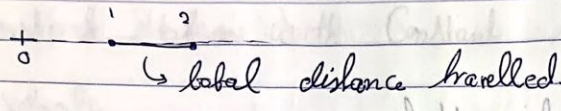
• إذا أخذ الجسم نفس الاتجاه
 لدينا أنه يتوقف لذلك نجد
 متى $v = 0$. متى إذا هو في
 الفترة الزمنية (المسافة)

$$v(t) = b^2 - t + 2 = 0 \Rightarrow b = 1 \pm \sqrt{-7} = \text{Complex}$$

• إذا لم يكن للجسم سرعة له تغير في اتجاهه الجسم من ذلك يعني

it is always tangent to the curve

e)



$$S_T = 67 - 1 = 66 \text{ m}$$

12.10.:

$$S = 1.5t^3 - 13.5t^2 + 22.5t$$

Find S
 S_T when $t = 6 \text{ s}$

$$S = -27$$

$$S_T = ?$$

Find V

$$\frac{ds}{dt} = V$$

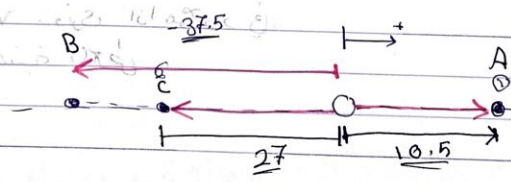
$$V = 4.5t^2 - 27t + 22.5$$

$$V = 0$$

$$4.5t^2 - 27t + 22.5 = 0$$

$$t = \frac{27 \pm 18}{9}$$

$$t_1 = 5 \text{ s} \quad t_2 = 1 \text{ s}$$



$$s = 1.5t^3 - 13.5t^2 + 22.5t$$

$s = 1.5 - 13.5 + 22.5 = 10.5 \text{ ft}$ with respect to the Origin

$$at \quad t=5, \quad s = \frac{5^2}{2} + 0 \cdot \frac{5}{1} + 0 = 12.5$$

$$s = -375 \text{ ft} \quad \left(\frac{5^2}{2} + 0 \cdot 5 + 0 \right)$$

$$A \rightarrow B \rightarrow C$$

$$S_T = 10.5 + 10.5 + 48 = 69 \text{ ft}$$

12.9:

Find s, v_2

$$g = 9.81 \text{ ms} = 32.2 \text{ ft/s}$$

Since $a = g$

$$v_2 = v + at$$

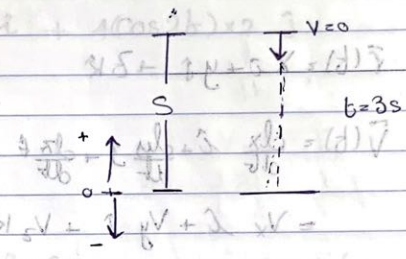
$$v_2 = 0 - (9.81)(3)$$

$$v_2 = -29.4 \text{ m/s}$$

$$\Delta s = v_1 t + \frac{1}{2} a t^2$$

$$-s = 0 - \frac{(9.81)(9)}{2}$$

$$s = 44.1$$



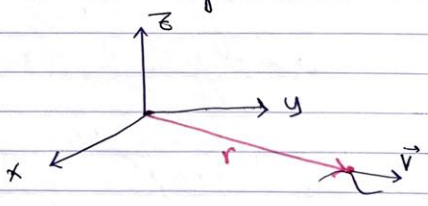
$$\begin{aligned} \uparrow +g &= -9.81 \\ \downarrow g &= 9.81 \end{aligned}$$

12.5: Rectangular Coordinates for Curvilinear Motion

$$\vec{r}(t) = x \hat{i} + y \hat{j} + z \hat{k}$$

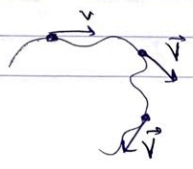
$$\vec{v}(t) = \frac{dx}{dt} \hat{i} + \frac{dy}{dt} \hat{j} + \frac{dz}{dt} \hat{k}$$

$$= v_x \hat{i} + v_y \hat{j} + v_z \hat{k}$$



$$|\vec{v}| = \sqrt{v_x^2 + v_y^2 + v_z^2}$$

\vec{v} is always tangent to the Curve



$$\vec{a} = \frac{d^2x}{dt^2} \hat{i} + \frac{d^2y}{dt^2} \hat{j} + \frac{d^2z}{dt^2} \hat{k}$$

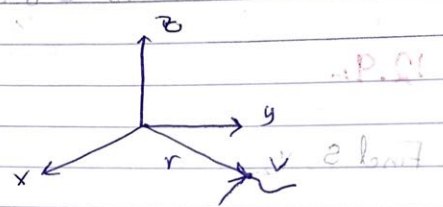
$$= a_x \hat{i} + a_y \hat{j} + a_z \hat{k}$$

S. 12-5 Rectangular Coordinates for Curvilinear Motion

$$\vec{r}(t) = x\hat{i} + y\hat{j} + z\hat{k}$$

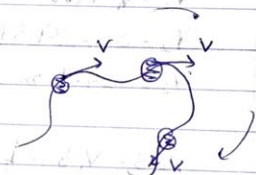
$$\vec{v}(t) = \frac{dx}{dt} \hat{i} + \frac{dy}{dt} \hat{j} + \frac{dz}{dt} \hat{k}$$

$$= v_x \hat{i} + v_y \hat{j} + v_z \hat{k}$$



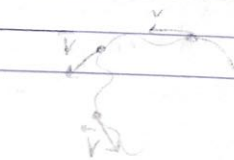
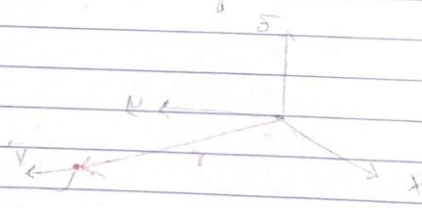
$$|\vec{v}| = \sqrt{v_x^2 + v_y^2 + v_z^2}$$

It is always tangent to the curve



$$\vec{a}(t) = \frac{d^2x}{dt^2} \hat{i} + \frac{d^2y}{dt^2} \hat{j} + \frac{d^2z}{dt^2} \hat{k}$$

$$= a_x \hat{i} + a_y \hat{j} + a_z \hat{k}$$



It is always tangent to the curve

Dynamics 3:-

12-73:

$$\vec{r} = (5\cos 2t)\hat{i} + (4\sin 2t)\hat{j} \quad \text{m}$$

Find $|\vec{v}|$

$|\vec{a}|$ at $t=1\text{s}$

$$\vec{v} = \frac{d\vec{r}}{dt} = (5)(-\sin 2t) \times 2 \hat{i} + 4(\cos 2t) \times 2 \hat{j}$$

$$\vec{v} = -10\sin 2t \hat{i} + 8\cos 2t \hat{j}$$

\vec{v} at $t=1$:-

$$\vec{v} = -10\sin 2 \hat{i} + 8\cos 2 \hat{j}$$

$$\left. \begin{aligned} \pi \text{ rad} &= 180^\circ \\ 2 \text{ rad} &= ? \end{aligned} \right\}$$

$$\theta = \frac{2 \times 180}{3.14159} = \frac{360}{\pi}$$

$$\vec{v}(1) = -9.093 \hat{i} - 3.329 \hat{j}$$

① $|\vec{v}| = \sqrt{(-9.093)^2 + (-3.329)^2} = 9.68 \text{ m/s}$

$$\vec{a} = -20\cos 2t \hat{i} - 16\sin 2t \hat{j}$$

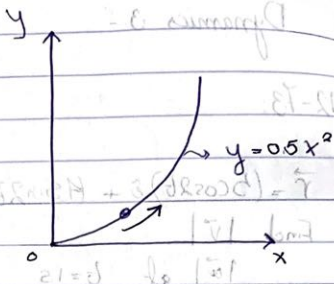
$$\vec{a}(1) = 8.323 \hat{i} + 14.549 \hat{j}$$

② $|\vec{a}| = 16.8 \text{ m/s}^2$

12-83:

$$V_x = 5t \text{ ft/s}$$

Find $|\vec{r}|$
 $|\vec{a}|$ when $t=1$ s



where at $t=0$, $x=0$

$$V_x = \frac{dx}{dt}$$

$$x dx = V_x dt$$

$$\int_0^x dx = \int_0^t 5t dt$$

$$x = \frac{5t^2}{2} \Rightarrow$$

$$x = 2.5t^2$$

$$y = 0.5 (2.5t^2)^2$$

$$y = 3.125t^4$$

$$x \text{ at } t=1 = 2.5 \text{ ft}$$

$$y \text{ at } t=1 = 3.125 \text{ ft}$$

$$\text{so } |\vec{r}| = \sqrt{(2.5)^2 + (3.125)^2} = 4.08 \text{ ft}$$

$$a_x = \frac{dV_x}{dt} = 5 \text{ ft/s}^2$$

$$V_y = 12.5t^3$$

$$a_y = 37.5t^2$$

$$a_y = 37.5 \text{ ft/s}^2 \Rightarrow |\vec{a}| = \sqrt{(37.5)^2 + (5)^2} = 37.8 \text{ ft/s}^2$$

• Another Method to solve Question:- y]

$y = 0.5x^2$ derive with Respect to t

$$v_y = \dot{y} \leftarrow \left(\frac{dy}{dt} \right) = \left(\frac{dx}{dt} \right) \cdot x$$

$$\frac{d^2y}{dt^2} = \frac{dx}{dt} \frac{dx}{dt} + x \frac{d^2x}{dt^2}$$

$$a_y = \left(\frac{dx}{dt} \right)^2 + x a_x$$

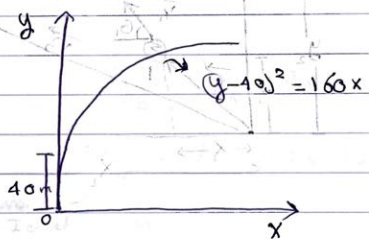
$$a_y = v_x^2 + x a_x$$

• $\frac{d^2y}{dt^2} = \frac{dx}{dt} \frac{dx}{dt} + x \frac{d^2x}{dt^2}$
 • $\frac{d^2y}{dt^2} = \frac{dx}{dt} \frac{dx}{dt} + x \frac{d^2x}{dt^2}$
 • $\frac{d^2y}{dt^2} = \frac{dx}{dt} \frac{dx}{dt} + x \frac{d^2x}{dt^2}$

12.86:

$v_y = 180 \text{ m/s}$ (constant)

Find $|\vec{v}|$
at $y = 80 \text{ m}$



$$* \underline{a_y = 0}$$

$$(y-40)^2 = 160x$$

$$2(y-40) \frac{dy}{dt} = 160 \frac{dx}{dt}$$

$$2(y-40) \dot{y} = 160 \dot{x}$$

$$2(y-40)v_y = 160 v_x$$

Derive wr to t:

$$2(y-40) \ddot{y} + \dot{y} (2\dot{y}) = 160 \ddot{x}$$

$$2(y-40) \ddot{y} + 2\dot{y}^2 = 160 \ddot{x}$$

put $v_y = 180$

$v_x = 90 \text{ m/s}$

$$|\vec{v}| = \sqrt{90^2 + 180^2} = 201$$

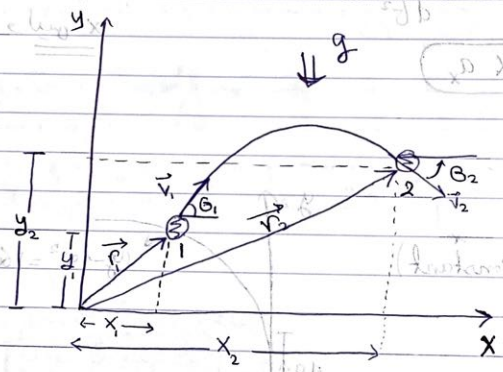
$$80 v_x = \frac{20}{\cos(30^\circ)} = 232$$

$$2 [(y-40) a_y + v_y^2] = 160 a_x$$

$$\Rightarrow a_x = 405 \text{ m/s}^2$$

$$|a| = 405 \text{ m/s}^2$$

12.6: Projectile Motion



المسار عبارة عن
 منحنى parabola

* Horizontally: \rightarrow

Prove @ $v_2 = v_1 + a_c b$

$$v_{2x} = v_{1x} + 0$$

$\Rightarrow v_x$ is constant

السرعة الأفقية للكرة ثابتة.

Prove @ $v_2^2 = v_1^2 + 2a_c (d_2 - d_1)$

$$v_{2x}^2 = v_{1x}^2 + 0$$

$$\rightarrow v_{2x} = v_{1x}$$

$$\Delta S = v_1 b + \frac{1}{2} a_c b^2$$

$$x_2 = x_1 + v_x b \rightarrow \text{يساوية}$$

المسافة

Vertically: 1+

$$y_2 = y_1 + v_{1y} t - \frac{1}{2} g t^2 \quad - (1)$$

$$v_{2y}^2 = v_{1y}^2 - 2g(y_2 - y_1) \quad - (2)$$

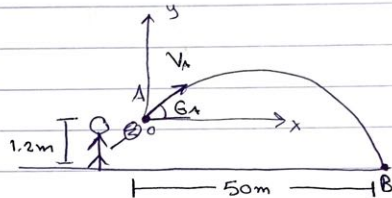
$$y_2 = y_1 + v_{1y} t - \frac{1}{2} g t^2 \quad - (3)$$

↑ +

سوال 12-89، در این مسئله v_x و v_y در $t = 2.5$ s را پیدا کنید.

12-89:

$$t_{AB} = 2.5 \text{ s}$$



$$v_x = \frac{50}{2.5} = 20 \text{ m/s}$$

$$v_{yB} = v_{yA} + a_y t$$

$$v_{Ax} = 20 \text{ m/s}$$

$$v_{Ax} = v_A \cos \theta_A \quad - (1)$$

$$v_{yB} = v_{yA} - (9.81)(2.5)$$

zero I dont know it

$$\text{So: } y_2 = y_1 + v_{1y} t - \frac{1}{2} g t^2$$

$$-1.2 = 0 + v_{Ay} (2.5) - \frac{1}{2} (9.81)(2.5)^2$$

$$v_{Ay} = 11.78$$

Horizontally A to B

$$x = v_{Ax} t = v_A \cos \theta_A \quad - (2)$$

Divide 2 by 1: $\frac{v_{Ay}}{v_{Ax}} = \tan \theta_A$

$$\frac{11.78}{20} = \tan \theta_A$$

$$\frac{11.78}{20} = \tan \theta_A$$

$$0.589 = \tan \theta_A$$

$$\theta_A = 30.5^\circ$$

$$\text{So } v_A = \frac{20}{\cos(30.5)} = 23.2$$

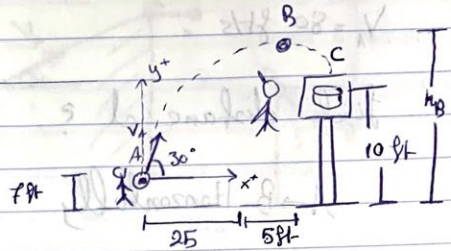
Dynamics

lec 3

12-99:-

Find V_A , h_B

A \rightarrow C Horizontally



$$x_c = x_A + V_{Ax} t_{AC}$$

$$30 = 0 + V_{Ax} t_{AC}$$

$$30 = V_A \cos 30 t_{AC} \quad \text{--- ①}$$

A \rightarrow C vertically

$$y_c = y_A + V_{Ay} t_{AC} - \frac{1}{2} g t_{AC}^2$$

$$3 = 0 + V_A \sin 30 t_{AC} - \frac{32.2}{2} t_{AC}^2$$

$$3 = V_A \sin 30 t_{AC} - 16.1 t_{AC}^2 \quad \text{--- ②}$$

Solving ① with ②

$$t_{AC} = 0.943 \text{ s} \quad V_A = 36.7 \text{ ft/s}$$

Now to find h_B :-

Horizontally A \rightarrow B

$$x_B = x_A + V_{Ax} t_{AB}$$

$$25 = 0 + (36.7)(\cos 30) t_{AB}$$

$$t_{AB} = 0.786 \text{ s}$$

Vertically A \rightarrow B :-

$$y_B = y_A + V_{Ay} t_{AB} - \frac{1}{2} g t_{AB}^2$$

$$h_B = 0 + (36.7) \sin 30 (0.786) - \left(\frac{1}{2}\right) (32.2) (0.786)^2$$

$$h_B = 11.5 \text{ ft}$$

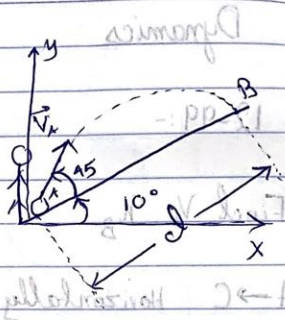
(2) (3) (4) (5) (6) (7) (8) (9) (10) (11) (12) (13) (14) (15) (16) (17) (18) (19) (20) (21) (22) (23) (24) (25) (26) (27) (28) (29) (30) (31) (32) (33) (34) (35) (36) (37) (38) (39) (40) (41) (42) (43) (44) (45) (46) (47) (48) (49) (50) (51) (52) (53) (54) (55) (56) (57) (58) (59) (60) (61) (62) (63) (64) (65) (66) (67) (68) (69) (70) (71) (72) (73) (74) (75) (76) (77) (78) (79) (80) (81) (82) (83) (84) (85) (86) (87) (88) (89) (90) (91) (92) (93) (94) (95) (96) (97) (98) (99) (100)

12-102

$$V_A = 80 \text{ ft/s}$$

find distance d ?

A \rightarrow B Horizontally



$$x_B = x_A + V_{Ax} t_{AB}$$

$$d \cos 10 = 0 + (80 \cos 55) t_{AB} \quad (1)$$

$$d \cos 10 = 80 \cos 55 t_{AB} \quad (2)$$

A \rightarrow B Vertically

$$y_B = y_A + V_{Ay} t_{AB} - \frac{1}{2} g t_{AB}^2$$

$$d \sin 10 = 0 + 80 \sin 55 t_{AB} - \frac{32.2}{2} t_{AB}^2 \quad (3)$$

Solving (1) with (2)

$$t_{AB} = 3.57 \text{ s}$$

$$d = 166 \text{ ft}$$

Handwritten notes at the bottom of the page, including a calculation: $(80 \cos 55) t_{AB} = d \cos 10$ and $(80 \sin 55) t_{AB} - \frac{32.2}{2} t_{AB}^2 = d \sin 10$.

Exam Question (1)

Find V_A, V_B, G_B

Horizontally:-

$$X_B = X_A + V_{Ax} t_{AB}$$

$$0 = 0 + V_A \cos 30^\circ t_{AB} \quad \text{--- (1)}$$

Vertically

$$Y_B = Y_A + V_{Ay} t_{AB} + \frac{1}{2} g t_{AB}^2$$

$$-3 = 0 + V_A \sin 30^\circ t_{AB} + \frac{1}{2} (9.81) t_{AB}^2 \quad \text{--- (2)}$$

$$t_{AB} = \frac{V_A}{g}$$

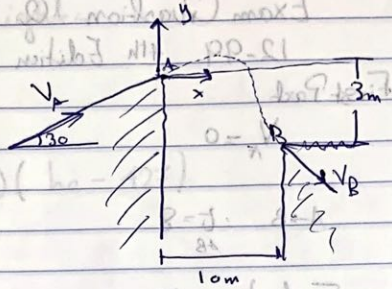
$$V_{Bx} = V_{Ax} = V_A \cos 30^\circ$$

$$V_{By} = V_{Ay} - g t_{AB}$$

$$V_{By} = V_A \sin 30^\circ - (9.81) t_{AB} \quad (\text{negative})$$

$$V_B = \sqrt{V_{By}^2 + V_{Bx}^2}$$

$$G_B = \tan^{-1} \frac{V_{By}}{V_{Bx}} \quad (\text{negative}) \quad \text{4th Quadrant}$$



Exam Question Q

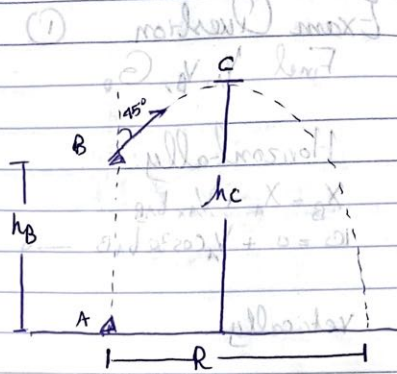
12-99 4th Edition

• First Part

$$V_A = 0$$

$$A \rightarrow B : t = 8$$

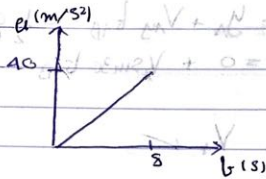
Find h_B, V_B



• Second PART:-

B \rightarrow C

Free Flight: Projectile/axis
Constant



Find h_C, R

Now: A \rightarrow B Rectilinear Motion Under varying acc

$$a = \frac{dv}{dt} = 5t$$

$y = ax + b$

$$a = \frac{dv}{dt}$$

$$\int_0^t a dt = \int_0^t dv$$

$$\frac{5t^2}{2} = v \Rightarrow v = 2.5t^2$$

$$\text{at } t = 8 \rightarrow v = (2.5)(8)^2 = 160$$

$$v = \frac{ds}{dt} \Rightarrow \int_0^t v dt = \int_0^t ds \Rightarrow \frac{2.5t^3}{3} = s$$

Put $t = 8$:- $s = 426.7 \text{ m}$

Now from B → C Free flight:-

$$V_{cy}^2 = V_{By}^2 + 2a(h_c - h_B)$$

$$0 = (160 \cos 45^\circ)^2 + (-2)(9.81)(h_c - 427)$$

$$\frac{12800}{(2)(9.81)} = h_c - 427$$

$$h_c = 1079.4$$

B → D horizontally

$$X_D = X_B + V_x t_{BD}$$

$$R = 0 + V_x t_{BD} \quad \text{--- (1)}$$

B → D vertically

$$-h_B = 0 + (160) \cos 45^\circ t_{BD} - \left(\frac{1}{2}\right)(9.81) t_{BD}^2$$

1) Velocity:-

$$-127 = 0 + \dots \quad \text{--- (2)}$$

--- (2) find t_{BD} tangent to the curve
 $t_{BD} = 26.365$

$$R = (160) \sin 45^\circ (26.36)$$

$$R = 2983 \text{ m}$$

2) Acceleration

$$\vec{a} = \frac{d\vec{v}}{dt} = v \frac{d\vec{u}}{dt} + \dot{v} \vec{u}$$

$$= v^2 \frac{d\vec{u}}{ds} + \dot{v} \vec{u}$$

$\frac{d\vec{u}}{ds} = \frac{1}{\rho} \vec{u}_n$
A. Radius of Curvature

$$\vec{a} = \underbrace{\dot{v} \vec{u}}_a \underbrace{+ \frac{v^2}{\rho} \vec{u}_n}_a$$

a_t (tangential acc)

a_n (normal acc)

$$|\vec{a}| = \sqrt{a_t^2 + a_n^2}$$

an: not a constant?

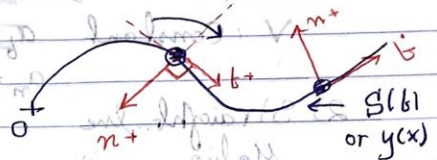
Sawli

12 Dynamics

lec 5

* 12.7: Curvilinear Motion: Normal Tangential Coordinates

t-axis: tangential to the Curve positive with the direction of Motion. (\hat{u}_t)
 ← unit vector



n-axis: \perp t-axis positive towards the center of the Curve (\hat{u}_n)

b-axis: \perp t-axis and \perp n-axis positive direction is found using Right hand Rule. (\hat{u}_b)

1) Velocity:

$$\vec{v} = v \hat{u}_t$$

magnitude \uparrow

• velocity is always tangent to the Curve.

2) Acceleration

$$\vec{a} = \frac{d\vec{v}}{dt} = \dot{v} \hat{u}_t + v \dot{\hat{u}}_t$$

$$= \frac{v^2}{\rho} \hat{u}_n + \dot{v} \hat{u}_t$$

normal

$$\hat{u}_n = \frac{v}{\rho} \hat{u}_{\text{normal}}$$

ρ : Radius of Curvature

$$\vec{a} = \dot{v} \hat{u}_t + \frac{v^2}{\rho} \hat{u}_n$$

a_t (tangential acc)

a_n (normal acc)

$$|\vec{a}| = \sqrt{a_t^2 + a_n^2}$$

a_n : تساريف الصفر الى اليمين
اليسار

Notes:

1) Rectilinear Motion

v: constant $\vec{a} = 0$

• Curvilinear Motion

v: constant $a_t = 0$

$$a_n = \frac{v^2}{r}$$

2) Straight line Motion

$r = \infty$ so $a_n = 0$

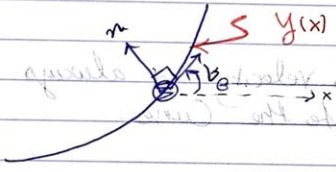
$$a_t = \dot{v}$$

Ex:

$y(x)$

$$r = \sqrt{1 + \left(\frac{dy}{dx}\right)^2}$$

$$\left| \frac{d^2y}{dx^2} \right|$$



$$\theta = \tan^{-1} \frac{dy}{dx}$$

$$\vec{v} = v \hat{t}$$

$$\vec{v} = v \hat{t}$$

$$\vec{a} = \dot{v} \hat{t} + v \dot{\hat{t}}$$

(200 lesson) no

(200 lesson) no

8 units 11/21/18 11/21/18

$$\frac{v^2}{r} = \frac{v^2}{\sqrt{1 + \left(\frac{dy}{dx}\right)^2}} \left| \frac{d^2y}{dx^2} \right|$$

12-119

$$v = 0$$

$$\dot{v} = 0.05b^2 \text{ ft/s}^2$$

Find $|\vec{v}|$

$$|\vec{a}| \text{ at } b = 18 \text{ s}$$

$$\int_0^b dv = \int_0^b \dot{v} db$$

$$v = \frac{0.05b^3}{3}$$

$$\int_0^b ds = \int_0^b v db$$

$$s = \frac{0.05b^4}{12}$$

$$s_{\text{at } b=18} = \frac{0.05(18)^4}{12} = 437.4 \text{ ft}$$

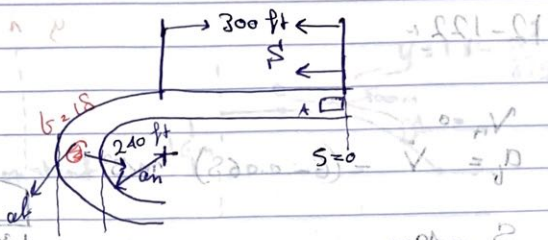
The car is in the curved region after 18 s

$$v(18) = \frac{0.05(18)^3}{3} = 97.2 \text{ ft/s}$$

$$a_t = (0.05)(18)^2 = 16.2 \text{ ft/s}^2$$

$$a_n = \frac{v^2}{r} = \frac{(97.2)^2}{240} = 39.37 \text{ ft/s}^2$$

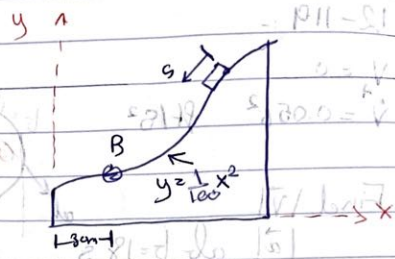
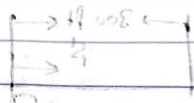
$$|\vec{a}| = 42.6 \text{ ft/s}^2$$



$$m a_n = \frac{m v^2}{r}$$

$$|\vec{a}| = \sqrt{a_t^2 + a_n^2}$$

12-122



$V_A = 0$
 $a_t = \dot{V} = (6 - 0.06s) \cdot \text{m/s}^2$

$S_B = 40 \text{ m}$

Find $|\vec{a}_B|$

$a_{tB} = 6 - 0.06 S_B$
 $= 6 - 0.06(40)$
 $= 3.6 \text{ m/s}^2$

$(\vec{a}_{\text{nb}}) = \frac{V^2}{\rho} = \frac{2[(6(40) - 0.03)(40)]^2}{79.3}$

$\int a_t ds = \int v dv$
 $\int (6 - 0.06s) ds = \int v dv$

$6s - 0.03s^2 = \frac{v^2}{2}$

$6s - 0.03s^2 = \frac{v^2}{2}$

$\vec{a}_{\text{nb}} = \frac{(19.6)^2}{79.3} = 4.84 \text{ m/s}^2$

$|\vec{a}_B| = 6.03 \text{ m/s}^2$

$\rho_B = \left[1 + \left(\frac{dy}{dx} \right)^2 \right]^{\frac{3}{2}}$

$= \left[1 + \left(\frac{1}{50}x \right)^2 \right]^{\frac{3}{2}}$

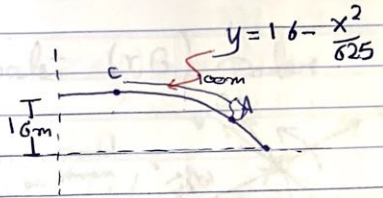
$= \left[1 + \left(\frac{30^2}{50^2} \right) \right]^{\frac{3}{2}} \times 50$

$\rho_B = 79.3 \text{ m}$

12-126:-

$$V_A = 20 \text{ m/s}$$

$$a_b = 0.5 \text{ m/s}^2 \text{ constant}$$



Final $|\vec{a}|$

$$S_c = 100 \text{ m}$$

$$(a_b)_c = (a_b)_A = 0.5 \text{ m/s}^2 \text{ Constant}$$

$$V_c^2 = V_A^2 + 2a_b(S_c - S_A)$$

$$V_c^2 = (20)^2 + 2(0.5)(100 - 0)$$
$$= 400 + 100 = 500$$

$$V_c = \sqrt{500}$$

$x=0$ when $y=1.6$

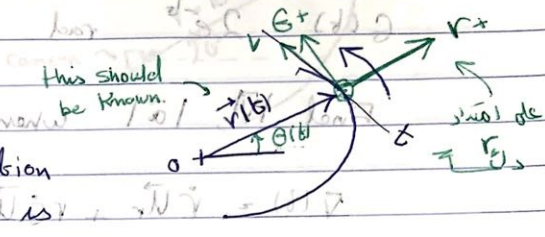
$$r_c = \left[1 + \left(\frac{dy}{dx} \right)^2 \right]^{\frac{3}{2}} = \left[1 + \left(\frac{-2x}{625} \right)^2 \right]^{\frac{3}{2}} = \left[1 + \left(\frac{-2 \times 0}{625} \right)^2 \right]^{\frac{3}{2}}$$
$$\frac{dy}{dx} = \frac{-2}{625}$$

$$r_c = \frac{625}{2} = 312.5 \text{ m}$$

$$S_0 (a_n)_c = \frac{500}{312.5} = 1.6 \text{ m/s}^2$$

$$|\vec{a}_c| = 1.68 \text{ m/s}^2$$

12.8: Cylindrical Coordinates (r, G) Polar Coordinates.



• **r-axis** :- Positive: in the direction of increasing r if G is constant \vec{u}_r

• **G-axis** :- \perp r-axis in the direction of increasing G \vec{u}_G

• **z-axis** :- \perp (r-axis, G-axis) following the right-hand rule. \vec{u}_z

$$\vec{r}(t) = r \vec{u}_r$$

1] **Velocity** :- $\vec{v}(t) = \dot{r} \vec{u}_r + \dot{\theta} r \vec{u}_G$
 $\vec{v}(t) = \dot{r} \vec{u}_r + \dot{\theta} r \vec{u}_G$
 Notes: $\dot{\theta}$: rate of change of the angle with respect to the time. $\dot{\theta} r$: tangential velocity.

2] **Acceleration** :- $\vec{a}(t) = (\ddot{r} \vec{u}_r + \dot{r} \dot{\theta} \vec{u}_G) + r \ddot{\theta} \vec{u}_G + [r \ddot{\theta} + 2\dot{r} \dot{\theta}] \vec{u}_G - \dot{\theta}^2 r \vec{u}_r$

$$\vec{a}(t) = \underbrace{[\ddot{r} - r \dot{\theta}^2]}_{\vec{a}_r} \vec{u}_r + \underbrace{[r \ddot{\theta} + 2\dot{r} \dot{\theta}]}_{\vec{a}_G} \vec{u}_G$$

... we have ...

12-1661

$r(t) = 4(1 + \sin t)$ meters (horizontal)

$\theta(t) = 2e^{-t}$ rad (angular)

Find $|\vec{v}|$, $|\vec{a}|$ when $t = 2s$:-

$\vec{v}(t) = \dot{r} \vec{u}_r + r \dot{\theta} \vec{u}_\theta$

$\dot{r}(t) = 4(\cos t)$

$\dot{\theta}(t) = -2e^{-t}$

$\vec{v}(t) = 4 \cos 2 + (4 + 4 \sin 2)(-2e^{-2})$

$\vec{v}(2) = -1.665 \vec{u}_r + (-7.623) \vec{u}_\theta = (-2.07 \text{ m/s})$

$\ddot{r}(t) = -4 \sin t$

$\ddot{\theta}(t) = 2e^{-t}$

$\vec{a}(t) = -4 \sin t \vec{u}_r - r \dot{\theta}^2 \vec{u}_r + (2e^{-t} + 2r\dot{\theta}) \vec{u}_\theta$

$\vec{a}(t) = -4.2 \vec{u}_r + 2.07 \vec{u}_\theta$

Notes

$X = 40$

Radians \vec{r} \vec{u}_r

$X = 2 \sin \theta$

Calculator θ in Degree

$\vec{u} [\dot{\theta} r + \ddot{\theta} r] + \vec{u} [\ddot{\theta} r - \dot{\theta}^2 r]$

12-176:-

$$|\vec{v}| = 40 \text{ m/s}$$

\dot{G} ? when $G = 15^\circ$

$$|\vec{v}| = \sqrt{v_r^2 + v_\theta^2}$$

$$\vec{v}_r = \dot{r}$$

$$\vec{v}_\theta = r\dot{G}$$

Now: $r = 100 \cos 2G = 86.6 \text{ m}$

$$\dot{r} = \frac{dr}{dt} = \frac{dr}{dG} \cdot \frac{dG}{dt}$$

$$= (100)(2) \sin 2G (\dot{G})$$

$$= -200 \sin 2G \cdot \dot{G}$$

$$\dot{r} = -100 \dot{G}$$

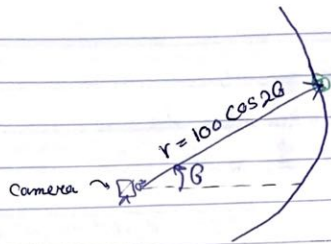
$$\vec{v}_r = -100 \dot{G}$$

$$\vec{v}_\theta = 86.6 \dot{G}$$

$$40 = \sqrt{(-100 \dot{G})^2 + (86.6 \dot{G})^2}$$

$$\dot{G} = 0.302 \text{ rad/s}$$

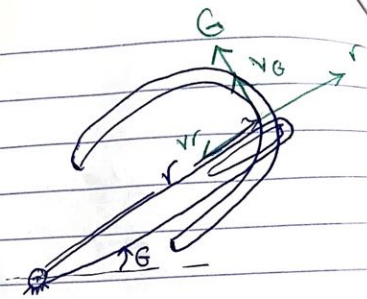
• we took the plus
since the movement
is clockwise



12-180

$$\vec{r} = 4 \sin 2\theta \text{ ft}$$

$$\dot{\theta} = 1.5 \text{ rad/s constant}$$



Find $|\vec{v}|$, $|\vec{a}|$ at $\theta = 60^\circ$

$$\dot{\theta} = 1.5 \text{ rad/s}$$

$$\ddot{\theta} = 0 \text{ rad/s}^2$$

* Chain Rule :-

$$\dot{r} = \frac{dr}{d\theta} \cdot 8 \cos 2\theta \times \dot{\theta}$$

$$\dot{r} = 8 \cos 2 \times 60 \times (1.5)$$

$$\dot{r} = -6 \text{ ft/s}$$

$$\ddot{r} = 8[\cos 2\theta \cdot \ddot{\theta} + \dot{\theta}(-2 \sin 2\theta \cdot \dot{\theta})]$$

$$\ddot{r} = -21.18 \text{ ft/s}^2$$

$$r = 3.464 \text{ ft}$$

$$v_r = -6 \text{ ft/s}$$

$$v_\theta = 5.196 \text{ ft/s}$$

$$v = 7.94 \text{ ft/s}$$

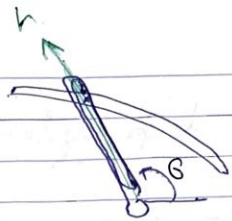
$$a_r = -38.97 \text{ ft/s}^2$$

$$a_\theta = -18. \text{ ft/s}^2$$

$$a = 42.9 \text{ ft/s}^2$$

12-184

$r = 1.5 \text{ G}$



The arm starts from rest at $\theta = 60^\circ$

$\dot{\theta} = 4t \text{ rad/s}$

Find: $v_r, v_\theta, a_r, a_\theta$ at $t = 1 \text{ s}$

$\ddot{\theta} = (4)(1) = 4 \text{ rad/s}^2$

$\dot{\theta} = 4$

$r = 1.5 \text{ G}$

$\dot{r} = 1.5 \dot{\theta} \rightarrow \dot{r} = (1.5)(4) = 6 \text{ m/s}$

$\ddot{r} = 1.5 \ddot{\theta} \rightarrow \ddot{r} = (1.5)(4) = 6 \text{ m/s}^2$

$\int_{60}^{\theta} \dot{\theta} dt = \int_0^t 4t dt$

$\theta = \frac{d\theta}{dt}$
 $\int \theta dt = \int dt$

$\int_0^t 4t dt = \theta - \frac{\pi}{3}$

$\frac{4t^2}{2} = \theta - \frac{\pi}{3}$

$2 = \theta - \frac{\pi}{3} \rightarrow \theta = 2 + \frac{\pi}{3} = \frac{6 + \pi}{3} = 3.05 \text{ rad} = 174.6^\circ$

$r = (1.5)(3.05) = 4.575 \text{ ft}$

$a_r = -67.1 \text{ ft/s}^2$

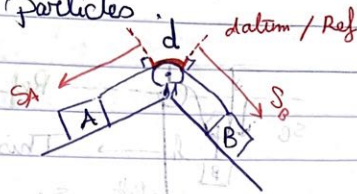
$a_\theta = 66.8 \text{ ft/s}^2$

$v_r = 6 \text{ ft/s}$

$v_\theta = 18.3 \text{ ft/s}$

At $t = 1 \text{ s}$

12.9 Absolute Dependent Motion Analysis of Two Particles lec 7



- 1) Pulley is frictionless
- 2) Cord is inextensible (length is constant)

$$L = s_A + d + s_B$$

$$\frac{d}{dt} (L = s_A + d + s_B)$$

$$0 = v_A + 0 + v_B$$

$$\boxed{v_A = -v_B}$$

$$\boxed{a_A = -a_B}$$

↳ Cord is increasing

or decreasing in length

(Direction)

12-199 :-

$$v_A = 2 \text{ m/s}$$

Find v_B

$$L_1 = s_A + s_C + s_C$$

$$\boxed{0 = v_A + 2v_C} \quad \text{--- (1)}$$

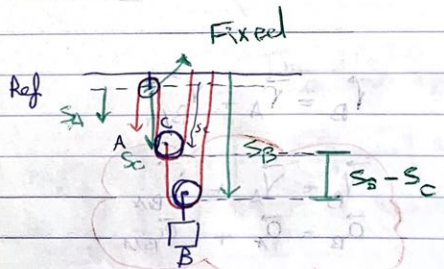
$$L_2 = s_B - s_C + s_B$$

$$\boxed{0 = 2v_B - v_C} \quad \text{--- (2)}$$

$$0 = 2v_B + 1$$

$$\boxed{v_B = -0.5}$$

↳ B تتركه زرعى ، الحبل تقصر

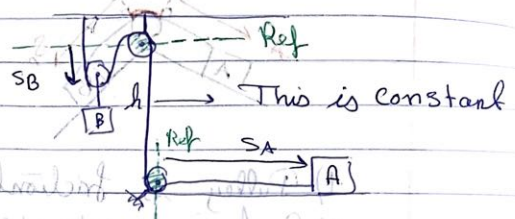


لدى سبي قطرة حبل بين الحبلين .
 Ref : الحبل

$$v_C = -\frac{v_A}{2} = -1$$

Example: Find the relationship between $V_A + V_B, a_A, a_B$

Find the Relationship Between $V_A + V_B, a_A, a_B$



$$L = s_B + s_B + s_A$$

$$0 = v_B + v_B + v_A$$

$$0 = 2v_B + v_A$$

$$\textcircled{1} \quad v_A = -2v_B$$

$$a_A = -2a_B$$

• انحصار جمع بين سرعتين متساويين يكون حول ثابت

• اذا حولت A فان B تقصر
• والسرعة تصبح

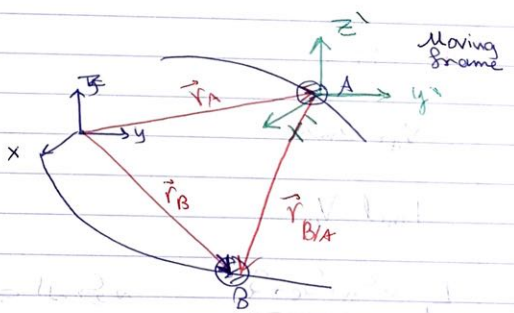
12.10 Relative Motion Using translating

- Fixed $\xrightarrow{\text{sees}}$ Absolute Motion
- In the moving object $\xrightarrow{\text{sees}}$ Relative Motion

$$\vec{r}_B = \vec{r}_A + \vec{r}_{B/A}$$

$$\vec{v}_B = \vec{v}_A + \vec{v}_{B/A}$$

$$\vec{a}_B = \vec{a}_A + \vec{a}_{B/A}$$



$$1 + gV_C = 0$$

$$20 = gV$$

$$V_{D1} = 0 \Rightarrow V_{A1} = 0$$

$$a_D + 2a_A = 0$$

$$a_A = -\frac{1}{2} a_{max} \text{ (Direktion)}$$

$$S_{A2} = S_{A1} + V_{A1} b + \frac{1}{2} a_A b^2$$

$$7.3 = 0 + 0 + (\frac{1}{2})(-1)(b^2)$$

$$\frac{b^2}{2} = 7.3$$

$$b = 1.22 \text{ s}$$

$$2) \vec{V}_B = \vec{V}_A + \vec{V}_{B/A}$$

$$-2 = -1.88 + V_{B/A}$$

$$V_{B/A} = -2 + 1.88 = -2.88$$

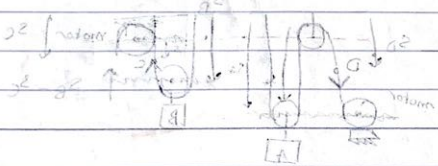
$$L = S_B + S_B - S_C$$

$$0 = (2S_B) - S_C$$

$$0 = 2V_B - V_C$$

$$2V_B + 4 = 0$$

$$V_B = -2$$



$$0 = 2V_B + 4 \Rightarrow V_B = -2$$