

Chapter 3:-

Integral Relations For a control volume:-

Systems vs control volumes

In a system:

- $m = \text{constant}$ $\frac{dm}{dt} = 0$
- applied forces from the surroundings causes acceleration: $F = ma$
(2nd law is applicable)

- Moments causes a rotation effect

$$M = \frac{dH}{dt}, \quad H = \int (r \times V) \rho \, dV$$

where H : is the angular momentum.

- System's energy changes due to heat transfer and work

* In a control volume: None of these are applied instead we will use: **The Reynolds Transport Theorem**

- Mass is not constant and there are mass flow to and/or from

B : represents a particular property (extensive)

β : represents $\frac{B}{m}$: (intensive)

→ There are types of control volume:-

[1] Fixed control volume

[2] moving control volume

[3] deforming control volume

constant velocity

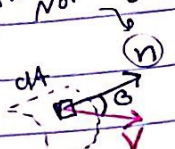
variable velocity

1- Fixed :-

* n is a unit vector
 $|n| = 1$
Normal to dA

Note:

- $V \cdot n$
- Taking $V \cos \theta$ only



Now there are three changes happening to B:-

- A change within the CV : $\frac{d}{dt} \left(\int_{c.v} \rho \beta dV \right)$
- Outflow of β from the CV : $\int_{c.s} \rho \beta V \cos \theta dA_{out}$
- Inflow of β : $\int_{c.s} \rho \beta V \cos \theta dA_{in}$

CV: Control volume.

CS: Control surface.

- The general form of the change within the System:-

$$\textcircled{1} \quad \frac{dB}{dt}_{sys} = \frac{d}{dt} \left(\int_{c.v} \rho \beta dV \right) + \int_{c.s} \rho \beta V \cos \theta dA_{out} - \int_{c.s} \rho \beta V \cos \theta dA_{in}$$

$$\rightarrow V \cdot n = V \cos \theta n = V \cos \theta = V_n \quad (\text{component of } V \text{ in direction of } n)$$

$in = (\rho V \cdot n) A$

$$\text{so } \frac{dB}{dt}_{sys} = \frac{d}{dt} \left(\int_{c.v} \rho \beta dV \right) + \int_{c.s} \rho \beta dA_{out} - \int_{c.s} \rho \beta dA_{in}$$

2- moving control volume :

- with constant velocity: eq ① stays the same

\rightarrow and V of control volume is ignored

- variable velocity: eq ①

\rightarrow But V becomes a more complicated function

3- deforming control volume :-

* $V_r = V - V_s$ ← vel of c.v

relative vel ← V_r

Fluid vel ← V

* $\frac{d}{dt}$ should be done after \int

$$\frac{dB}{dt} = \frac{d}{dt} \int_{c.v} \beta \rho dV + \int_{c.s} \beta \rho (V_r \cdot n) dA_{out} - \int_{c.s} \beta \rho (V_r \cdot n) dA_{in}$$

→ One dimensional flux :- flow properties are nearly uniform : \int becomes a sum (No need for integration)

→ Steady flow : change within CV = 0 ($\frac{d}{dt} \int_{c.v} \beta \rho dV = 0$)

• In this chapter :- we will be finding a c.v form for :

- 1- conservation of mass
- 2- linear momentum relation
- 3- Angular "
- 4- energy equation

Conservation of mass:-

$$B = \text{mass} \quad \beta = 1$$

So

$$\left(\frac{dm}{dt}\right)_{\text{sys}} = \left(\frac{d}{dt} \int_{\text{c.v.}} \rho dV\right) + \int_{\text{c.s.}} \rho V_r \cdot n dA_{\text{out}} - \int_{\text{c.s.}} \rho V_{r,\text{in}} dA_{\text{in}}$$

$$\left(\frac{dm}{dt}\right)_{\text{sys}} = 0$$

$$\text{and } \frac{d}{dt} \int \rho dV = \int \frac{\partial \rho}{\partial t} dV$$

→ and if the c.v has one-D out and inlets
Then

$$0 = \int \frac{\partial \rho}{\partial t} dV + \sum (\rho V A)_{\text{out}} - \sum (\rho V A)_{\text{in}}$$

• If the flow is steady, one Dimensional Flux

$$\sum (\rho V A)_{\text{out}} = \sum (\rho V A)_{\text{in}}$$

$$\sum \dot{m}_{\text{out}} = \sum \dot{m}_{\text{in}}$$

• If the fluid is incompressible ($\rho = \text{constant}$)

$$\sum (VA)_{\text{out}} = \sum (VA)_{\text{in}}$$

$$\sum \dot{Q}_{\text{out}} = \sum \dot{Q}_{\text{in}} \quad (\dot{Q}: \text{Volume Flow } \dots)$$

We can find V_{av} , P_{av} using

$$V_{\text{av}} = \frac{1}{A} \int V_r \cdot n dA \quad P_{\text{av}} = \frac{1}{A} \int P dA$$

$$(P\rho V)_{\text{av}} = \frac{1}{A} \int \rho (V_r \cdot n) dA = \rho_{\text{av}} V_{\text{av}}$$

The linear momentum equation:

F: represents surface Forces / Weights of mass

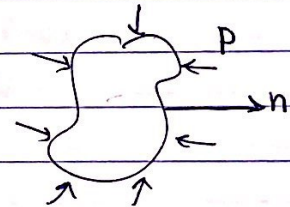
$B = mV$ $\beta = V$ \sim \underbrace{mV}

$$\frac{d(mV)}{dt}_{sys} = \sum(F) = \frac{d}{dt} \int_{c.v} (\rho P dV) + \int_{c.s} \rho A (V \cdot n) dA$$

→ We can find $\sum F_x, \sum F_y, \sum F_z$ since the equation is a vector equation

Net pressure force on a closed control surface :-
If the surface of C.V has P_a affecting (uniform value) then:

$F_{(up)} = 0$
uniform pressure



$$F_{press} = \int_{c.s} (P - P_a) (-n) dA$$

$$= \int_{c.s} P_{gage} (-n) dA$$

• P, n has opposite directions

Momentum Flux correction factor :-

for example:- $\sum F = \dot{m} (\beta_2 V_2 - \beta_1 V_1)$

β : is called correction factor and it's close to a unity

- Dimensionless
- $\beta \geq 1$

For a steady flow, one dimensional flux:-

$$\sum F = \dot{m} V_{out} - \dot{m} V_{in}$$



Frictionless flow: the Bernoulli equation:-

For a steady frictionless incompressible flow along a streamline, Bernoulli's equation (conservation of energy in a fluid) is:-

$$\frac{P_1}{\rho} + \frac{1}{2} V_1^2 + g z_1 = \frac{P_2}{\rho} + \frac{1}{2} V_2^2 + g z_2 = \text{constant}$$

Restrictions:

- 1- Steady flow :
- 2- Incompressible flow : ρ is constant
- 3- Frictionless flow : لا يوجد احتكاك بين جزيئات المائع أو بين المائع والجدران $\mu = 0$
- 4- Flow along a single stream line
تكون التدفق في اتجاه واحد على طول خط الجريان.

Angular Momentum Theorem:-

$$\sum M_o = \frac{\partial}{\partial t} \left[\int_{c.v} (r \times V) \rho dV \right] + \int_{c.s} (r \times V) \rho (V \cdot n) dA$$

for a steady flow, one dimensional flux:-

$$\sum M_o = (r \times V) \dot{m}_{out} - (r \times V) \dot{m}_{in}$$

From Forces

The energy equation:-

$$\frac{dQ}{dt} - \frac{dW}{dt} = \frac{dE}{dt} = \frac{d}{dt} \left(\int_{c.v} e \rho dV \right) + \int_{c.s} e \rho (V \cdot n) dA$$

$$\dot{Q} - \dot{W}_s - \dot{W}_r = \frac{\partial}{\partial t} \left[\int_{c.v} \left(\hat{u} + \frac{V^2}{2} + gz \right) \rho dV \right] + \int_{c.s} \left(\hat{h} + \frac{V^2}{2} + gz \right) \rho (V \cdot n) dA$$

one-dimensional energy flux terms:-

the integration goes away

$$\dot{Q} - \dot{W}_s - \dot{W}_r = \frac{\partial}{\partial t} \left[\int_{c.v} \left(\hat{u} + \frac{V^2}{2} + gz \right) \rho dV \right] + \sum \left(\hat{h} + \frac{V^2}{2} + gz \right)_{out} \dot{m}_{out} - \sum \left(\hat{h} + \frac{V^2}{2} + gz \right)_{in} \dot{m}_{in}$$

for a steady flow, one dimensional flux:-
($\dot{W}_r = 0$)

$$\dot{Q} - \dot{W}_s = \sum e \dot{m}_{out} - \sum e \dot{m}_{in}$$

$$e = gz + \frac{1}{2} V^2 + h$$

Potential Kinetic Enthalpy (Thermal energy)

Friction and shaft work in low speed flow

$$\left(\frac{P}{\gamma} + \frac{V^2}{2g} + z \right)_{in} = \left(\frac{P}{\gamma} + \frac{V^2}{2g} + z \right)_{out} + h_{friction} - h_{pump} + h_{turbine}$$

- h_f = Friction head loss
- h_p = pump head input
- h_m = turbine head extraction

→ mechanical energy out

$$\rho \int_{v_1}^{v_2} \left[\frac{1}{2} \frac{d}{dt} (V^2) + \frac{d}{dt} (gz) \right] dV = \dot{W}_2 - \dot{W}_1 - \dot{Q}$$

$$\rho \int_{v_1}^{v_2} \left[\frac{1}{2} \frac{d}{dt} (V^2) + \frac{d}{dt} (gz) \right] dV = \dot{W}_2 - \dot{W}_1 - \dot{Q}$$

→ Dimensional energy flux terms

the integration over energy

$$\rho \int_{v_1}^{v_2} \left[\frac{1}{2} \frac{d}{dt} (V^2) + \frac{d}{dt} (gz) \right] dV = \dot{W}_2 - \dot{W}_1 - \dot{Q}$$

$$\rho \int_{v_1}^{v_2} \left[\frac{1}{2} \frac{d}{dt} (V^2) + \frac{d}{dt} (gz) \right] dV = \dot{W}_2 - \dot{W}_1 - \dot{Q}$$

→ for a steady flow over a control flux

(control)

$$\dot{W}_2 - \dot{W}_1 = \dot{Q} - \dot{W}_{shaft}$$

$$\dot{Q} = \dot{Q}_s + \dot{Q}_k + \dot{Q}_p$$

→ Potential
→ Kinetic

Additional Note :-

In the linear momentum equation: How to find $\sum F$

Forces can be:

- 1- External forces, Given in the Question
- 2- Weight : mg
- 3- Hydrostatic Force
- 4- Pressure Force

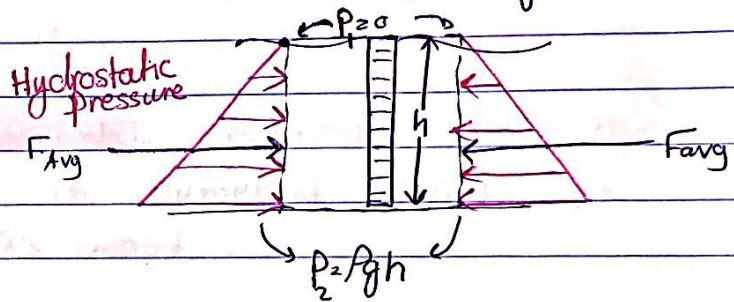
→ 3- Hydrostatic Force

- usually in gate Questions, the fluid will act on the walls of c.v causing hydro static pressure.

$$F_{avg} = \left(\frac{P_1 + P_2}{2} \right) A_{Avg}$$

$$= \frac{0 + \rho g h}{2} A$$

$$F_{avg} = \frac{\rho g h A}{2}$$



→ 4- Pressure Force

when a fluid is passing in a tube it acts on the walls of c.v causing pressure and the force resulting from this will equal:-

The pressure is $n \leftarrow m \cdot v_1 \left(\frac{P_{gage}}{\rho} \right)$ $\left(\frac{P_{gage}}{\rho} \right) m \cdot v_2 \rightarrow n$
 always action on A to inside (opposite direction of n)

$$F = \underset{\substack{\uparrow \\ \text{Direction only}}}{(\rho A)} (-n)$$